Attack tree construction: an application to the connected vehicle

CYBER-PHYSICAL SECURITY EDUCATION WORKSHOP

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Presentation Outline

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Vehicle architectural components (1)

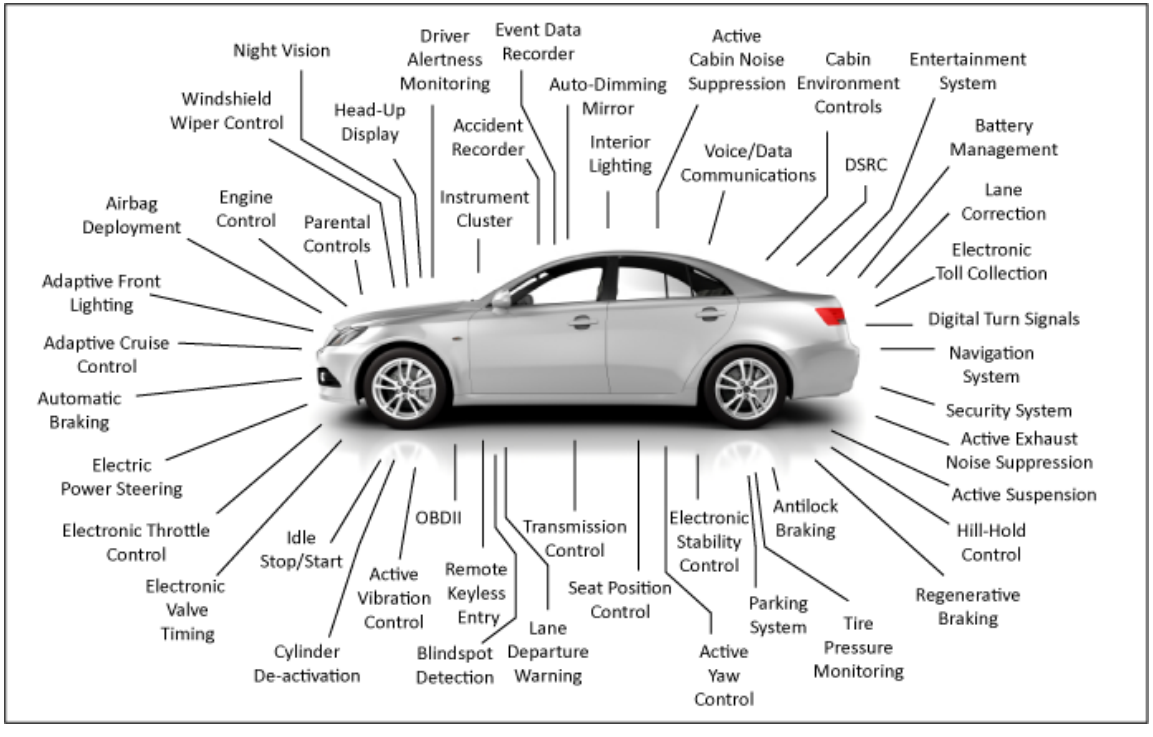

Figure : Automotive services

Cost:

The cost of electronics embedded system in the vehicle is estimated to be between 20% and 25% of total production cost

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- ECUs: Electronic Control Units, are embedded interconnected controllers in the vehicle and integrate various data processing functions that guarantee the safety and comfort of the user.


Vehicle architectural components (3)

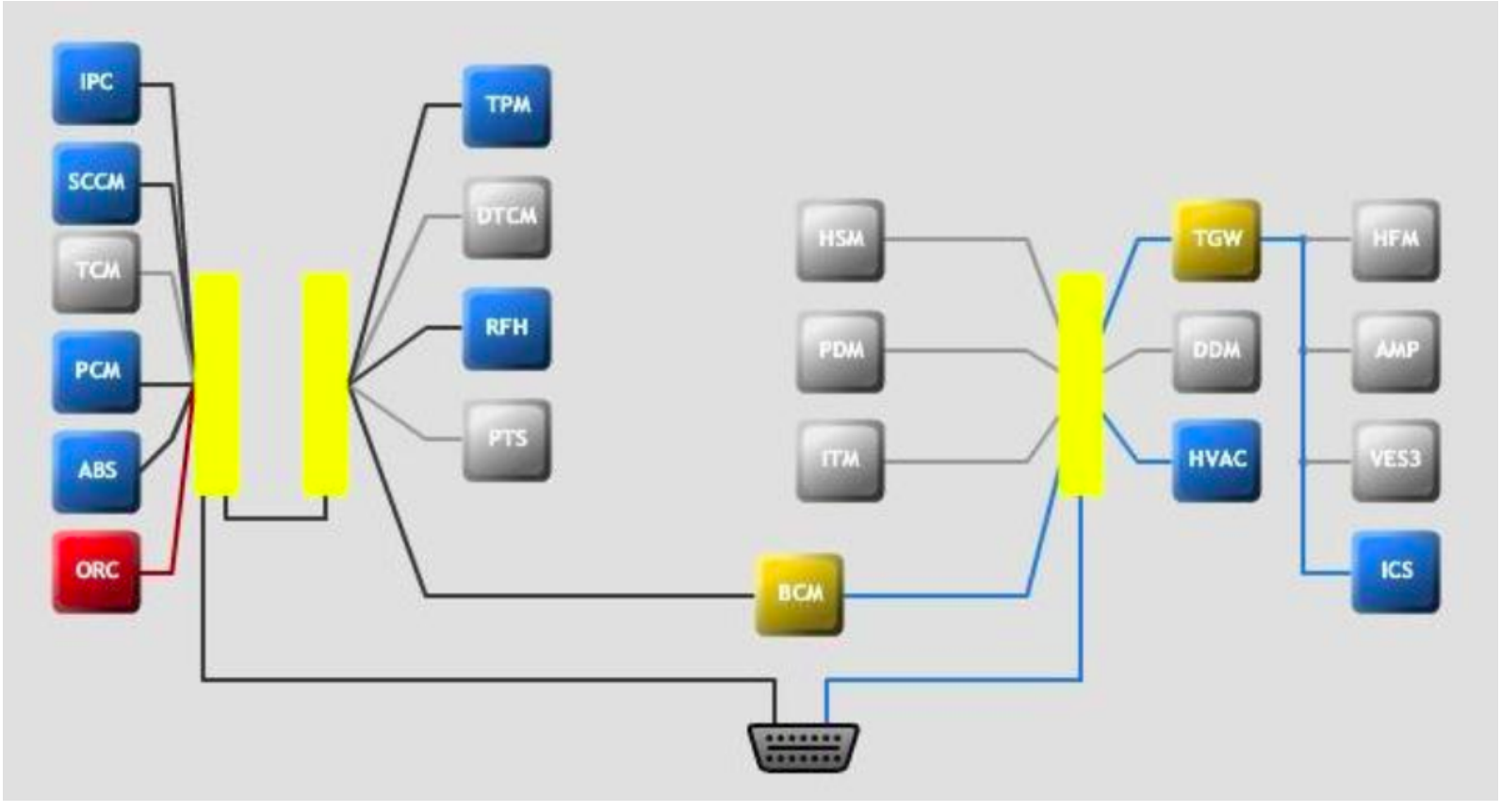
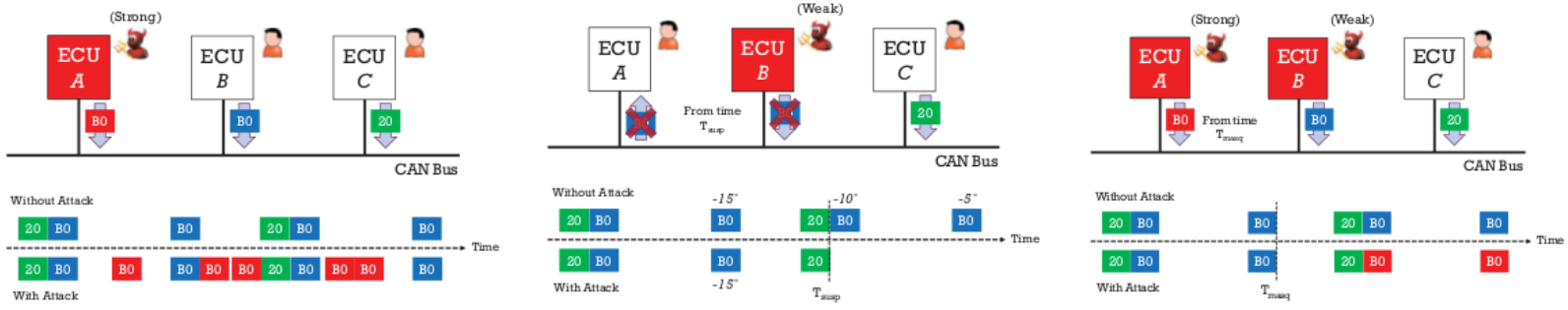


Figure : Vehicle architecture [MV15]

A vehicle architecture consists of these components interconnected by communication buses: CAN, FlexRay, . . .

Attacks on cars (1)

- Attack with physical access to the vehicle:
  - CAN frame injection attack (ECU Impersonation) [MV13, CS16]



(a) Fabrication attack. (b) Suspension attack. (c) Masquerade attack.

DoS-attack (Denial of Service)

While (True) {Send CAN ID=0, payload = 0 }

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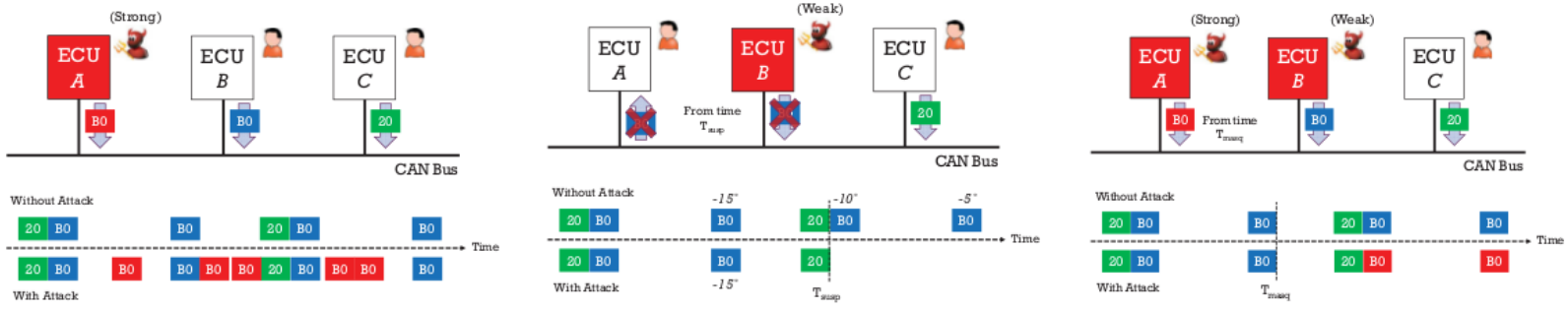

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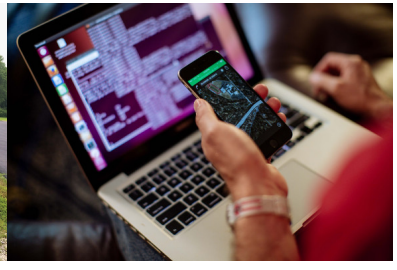
DoS-attack (Denial of Service)

While (True) {Send CAN ID=0, payload = 0 }

  - Attacks exploiting software vulnerabilities to access the internal networks (e.g CAN). [CMK+11, FPKS15]

Attacks on cars (2)

- Attacks with short/long range wireless access:
  - Wifi, Bluetooth, Cellular : [CMK+11, MV15]

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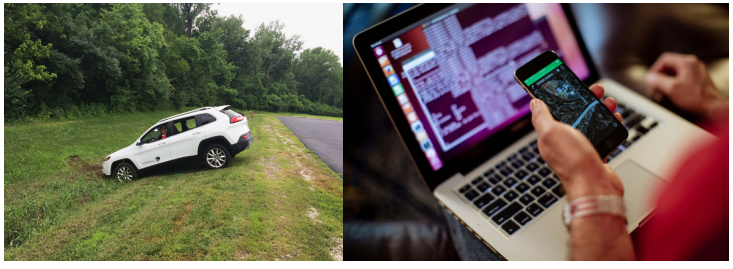


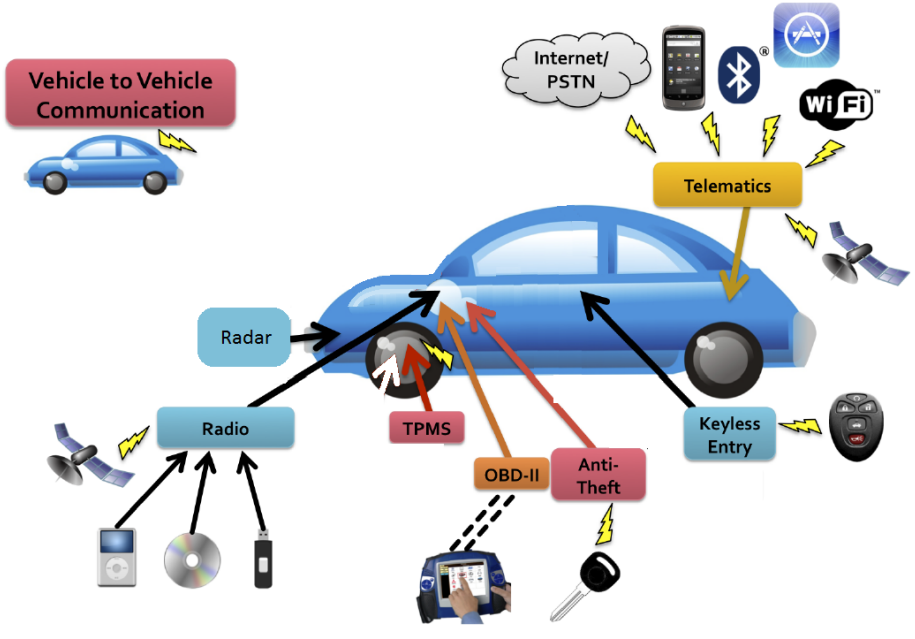


Figure : Vehicle attack vectors [CMK+11]

Presentation Outline

Motivation

- Car manufacturers have to guarantee a level of security: safety, privacy of the user.
- Some security problems have to be addressed at early design phase.
- Write clear and strong security requirements to meet the security needs.

Motivation

1. Asset identification.
2. Threat identification (per asset).
3. Impact estimation (per threat).
4. Threat level estimation [likelihood] (per threat)
   - (1) architectural design
   - (2) Adversary capabilities

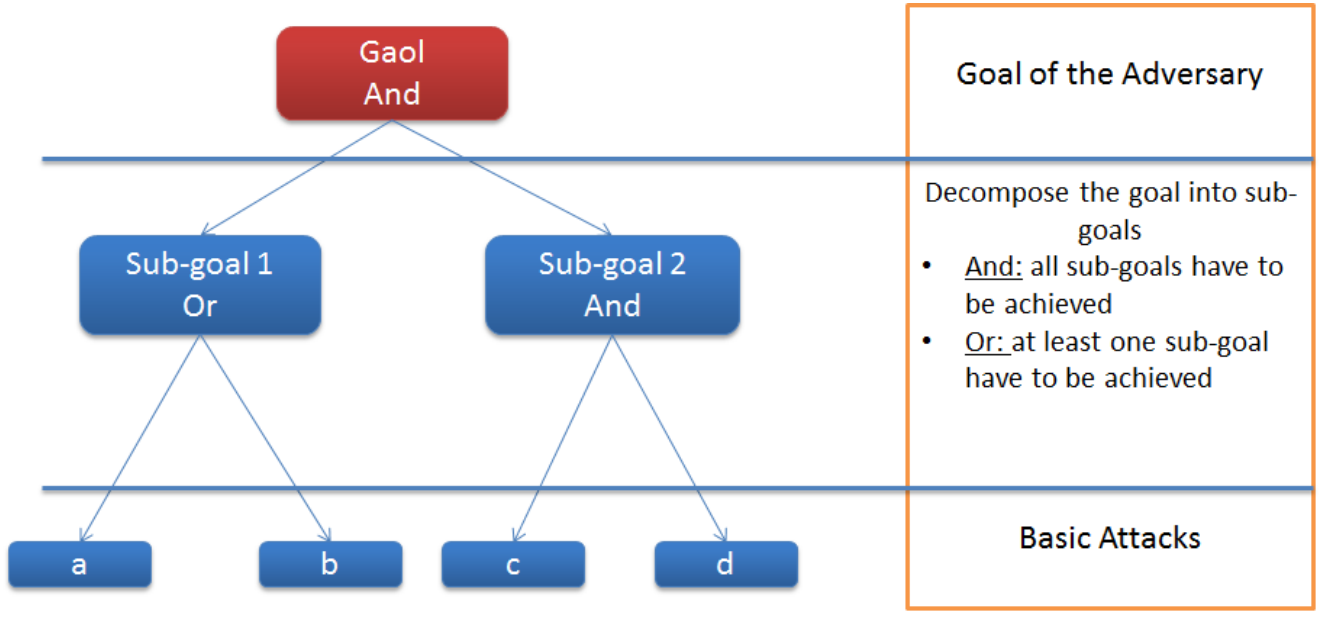
How to assess the risk

$$SC = \{SC_i\}$$

$$Risk = \sum_i Impact(SC_i) \times P_{occ}(SC_i)$$

SC	:	Set of attack scenarios (threats)
$Impact(x)$	:	Impact of the attack scenario on safety, availability, confidentiality, ...
P_{occ}	:	Likelihood of occurrence of the attack scenario is correlated with the architecture (functional, hardware)

Attack tree [Sch99]



Goal of the attack tree:

- Visualise attack paths (understand *How*)
- Helps to assess the Risk.
- Allows to think about countermeasure in an effective way.

This approach is used to support the risk assessment step.

Using attack trees

Attack trees are used to model attacks:

- Network administration: management of access policy, where to place firewalls, ... [AWK02, JN10]
- SCADA (Supervisory Control And Data Acquisition) [BFM04, TLM08]

In automotive domain:

- EVITA: E-safety vehicle intrusion protected applications (uses attack trees) [HAF+09]
- SAEJ3061: The new automotive cybersecurity standard (2016) [Com16]

Problems:

- Exhaustivity of the attack tree.
- Error prone: Security experts have to imagine all possible ways.
- Complex to draw when the system to analyze is large.

Automatic generation of attack trees

Solution: automatic generation of attack trees

Given a system model and an adversary model we want to see if the adversary can put the system in a vulnerable state, then retrace the actions.

Advantages:

- Addresses all attack vectors in a structured way.
- Automatically analyze the vehicle architecture (however large it may be).
- Lists all possible attack paths (w.r.t) the system and adversary models: exhaustivity.

Graph transformation

Graph transformation:

- The modeling is based on graph transformation system, formal modeling based on graph rewriting, which allows us to express a relational model in the form of a graph (vertex and arcs) and to explore the different possible configurations of this graph by applying transformations rules:
  - Start Graph: architectural system model
  - Transformation rules: inference rules to automate a reasoning method (deduction/derivation)

Tool:

- Groove $\rightarrow$ a tool for Graph transformation.

System Model

Modeled components: graph

- Communication nodes
- Hardware nodes, communication controllers and data storage.
- Service nodes, and access rights to hardware components.
- Data nodes.

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Behavioral model: transformation rules

- Behavior of hardware nodes.
- Behavior of service nodes.
- Behavior of the attacker.

Illustration: model

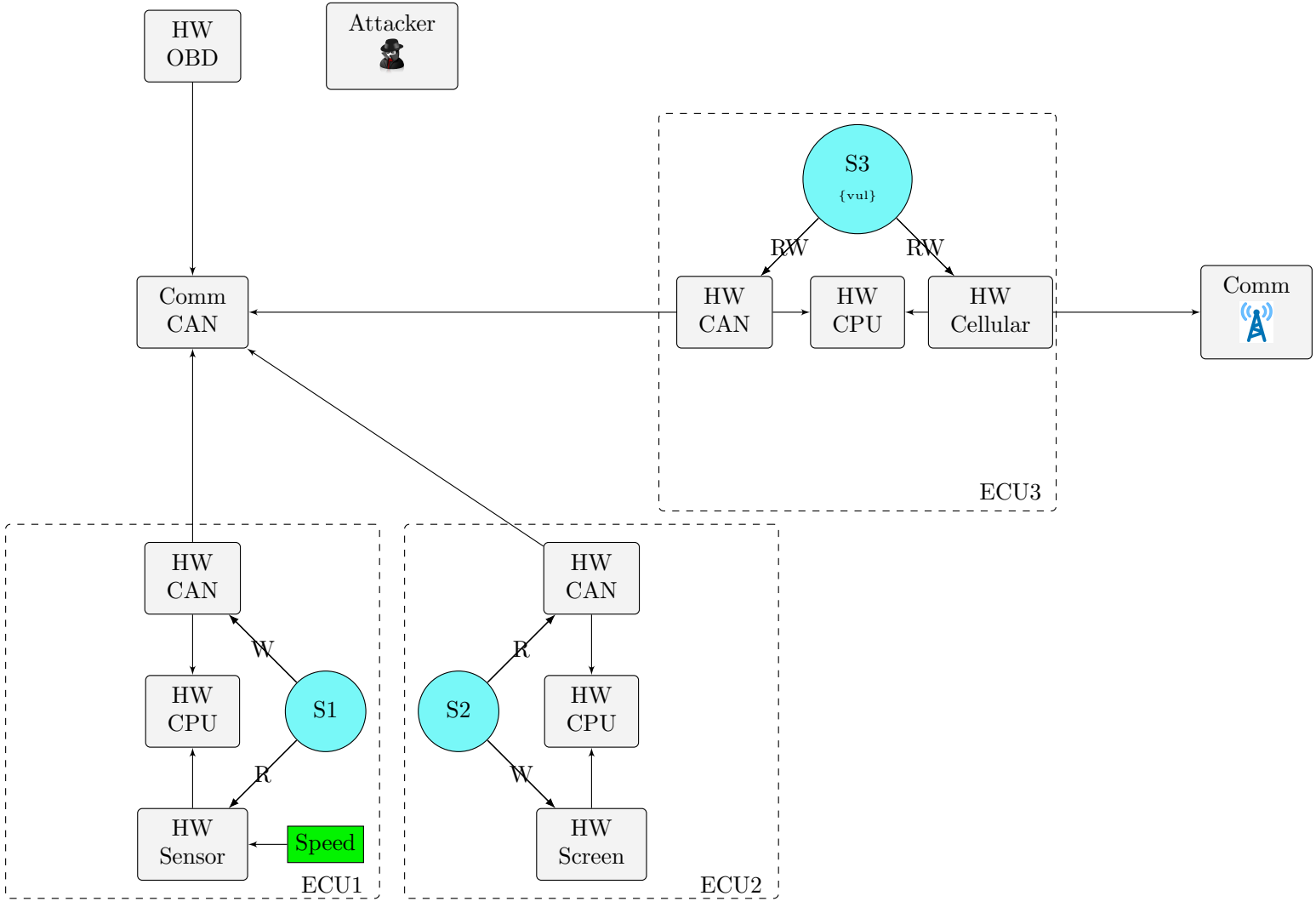

Figure : Speed acquisition and display

Transformation rules

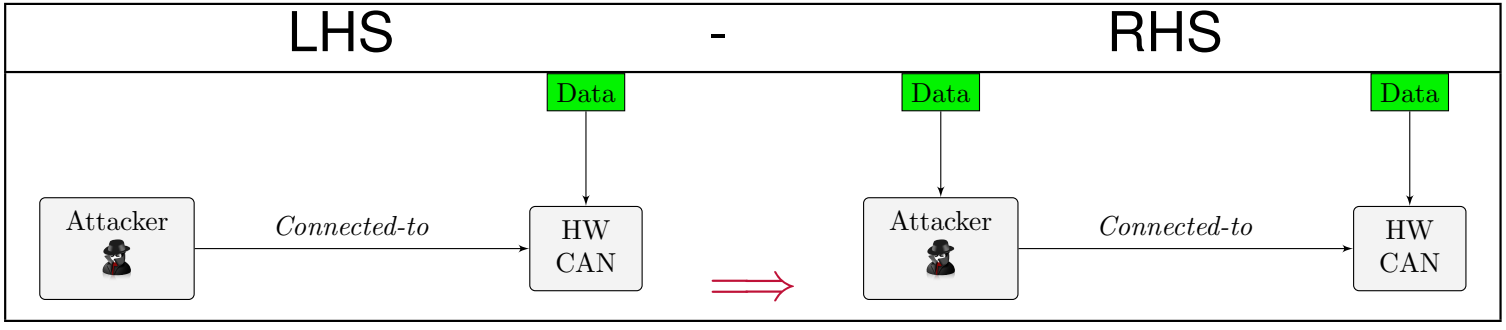

Figure : Transformation rule: attacker eavesdrop on CAN

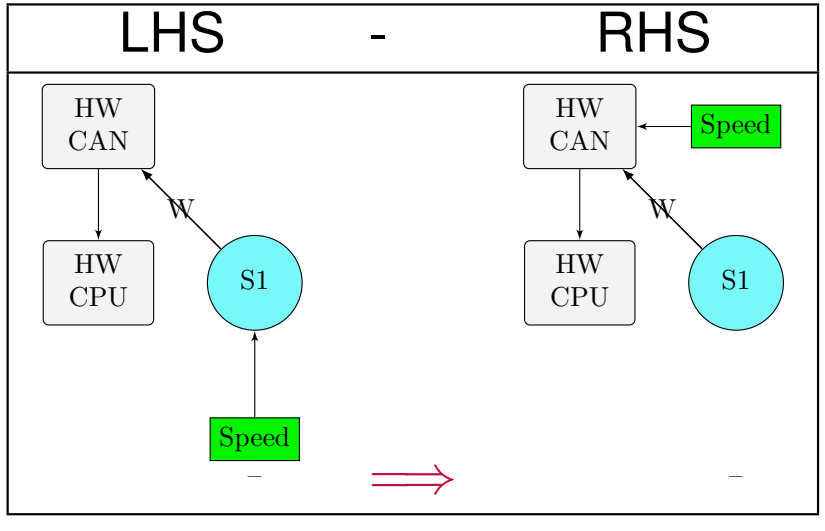

Figure : Transformation rule: Speed send to CAN

State space

state space

State space in the result of the application of transformation rules on the architectural graph.

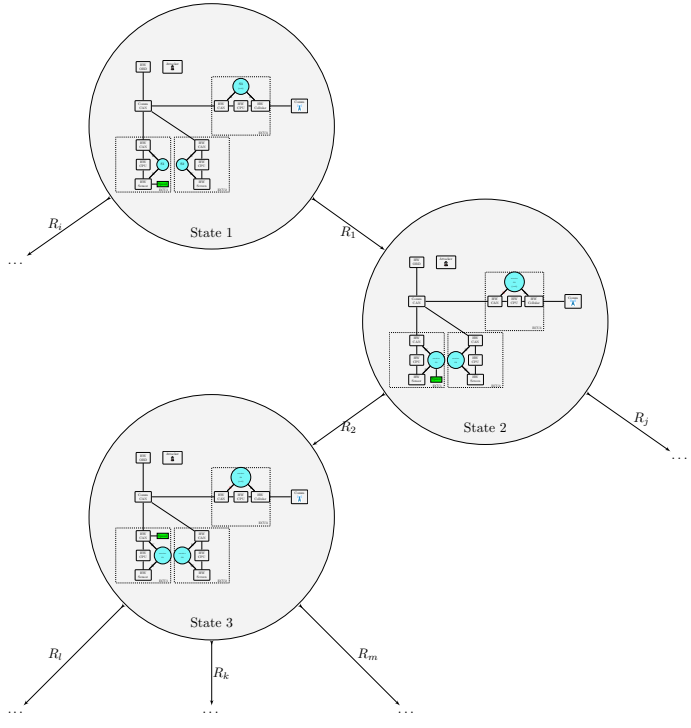

Figure : State space

Query

Query:

To find *all* vulnerable system states we make a query to see if the *threat* occurred.

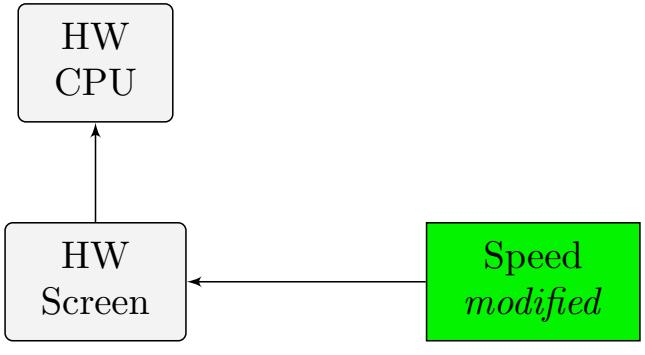

Figure : Speed modification query

Attack tree generation steps

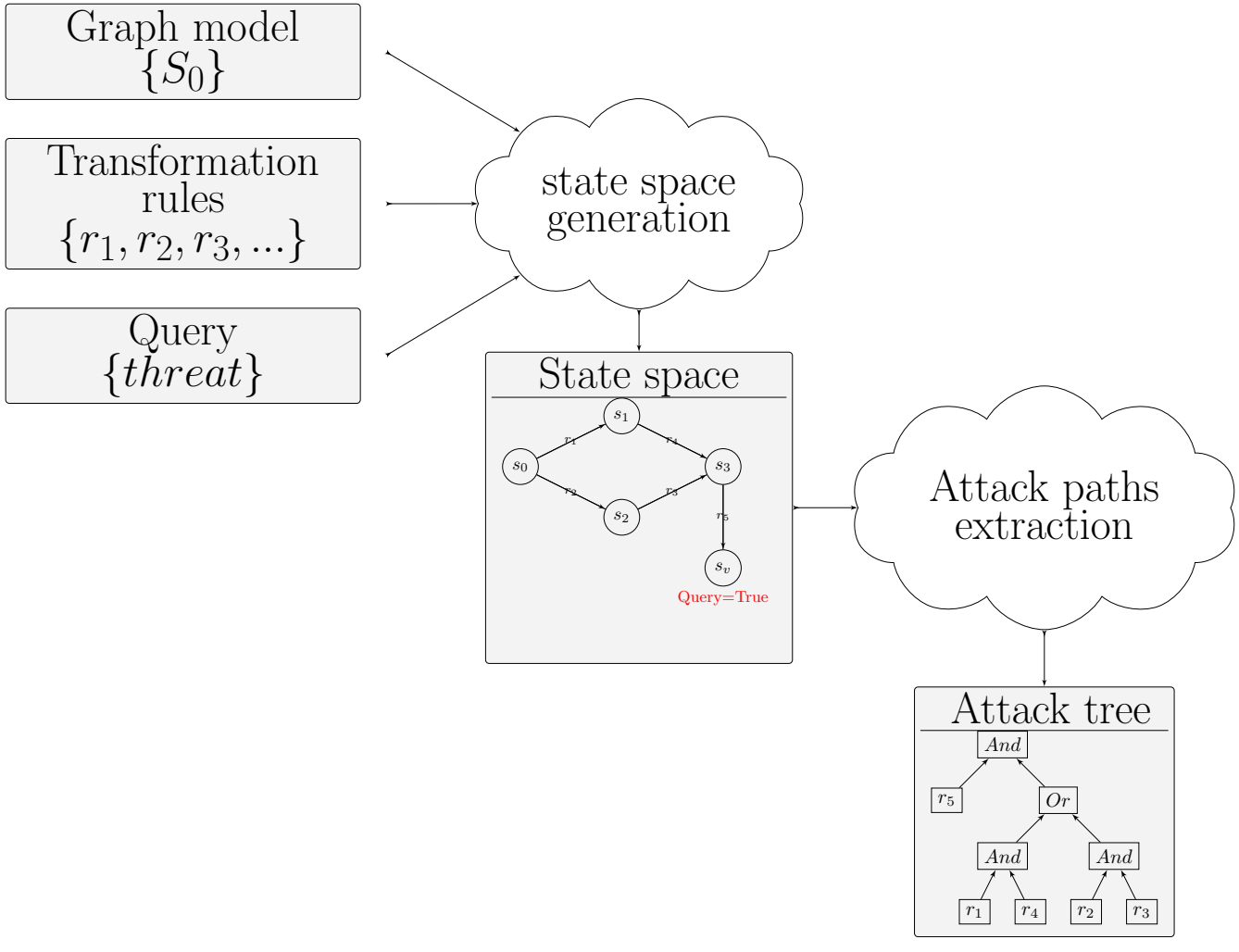

Figure : Automated generation of attack trees

Illustration: Attack tree

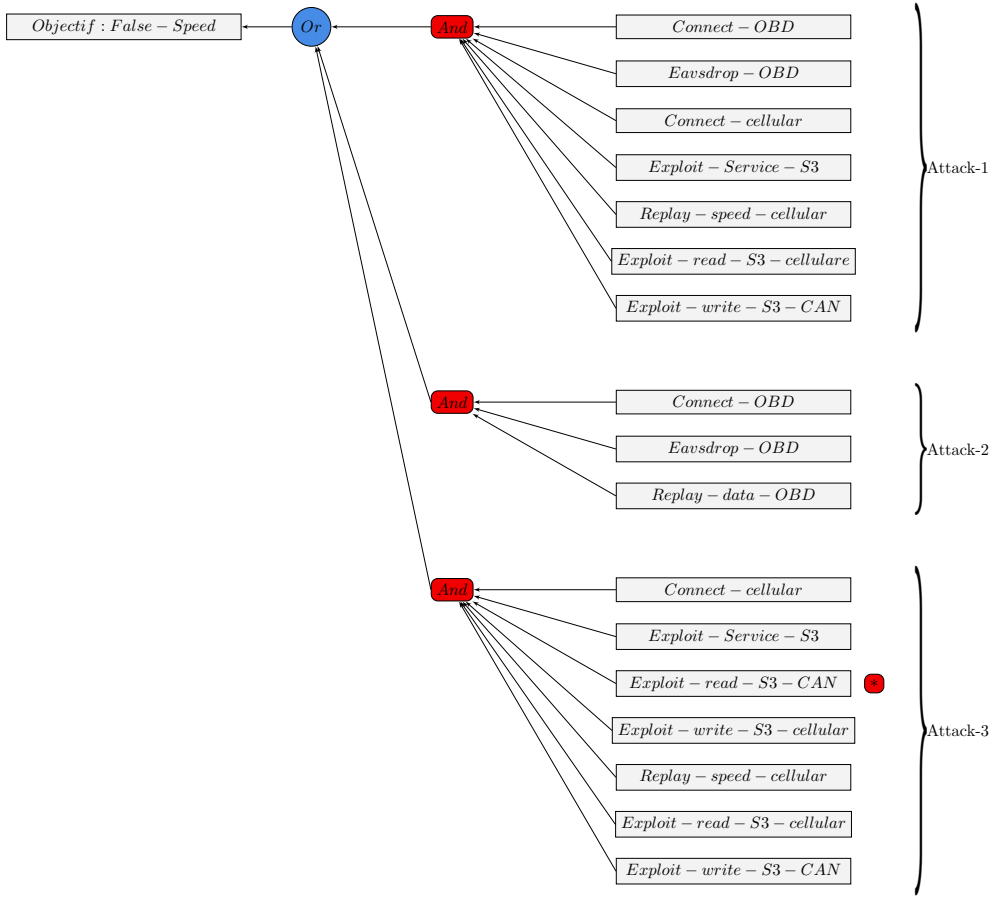

Figure : Attack tree: Speed acquisition and display

Illustration: model

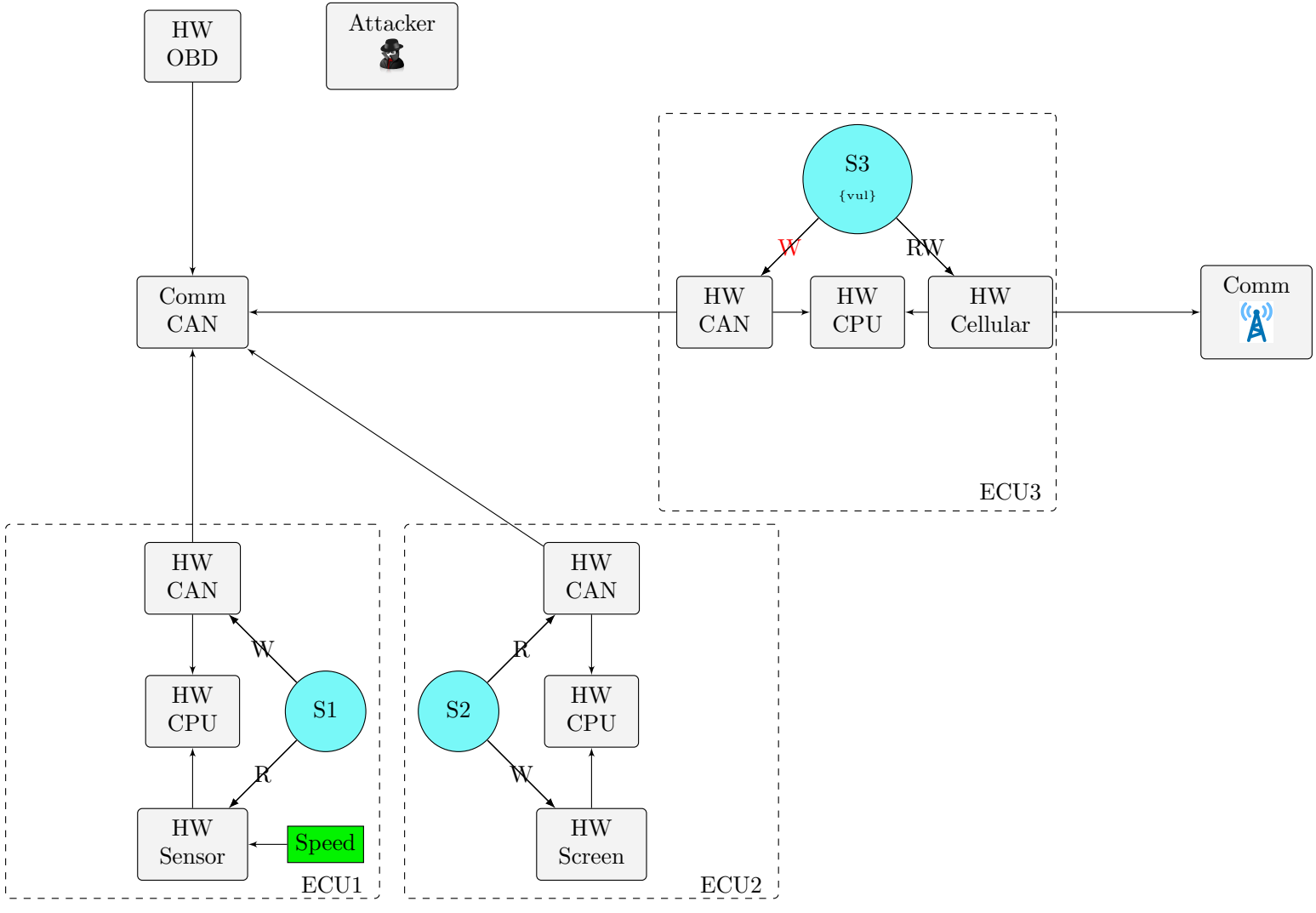

Figure : Speed acquisition and display

Illustration: Attack tree - countermeasure

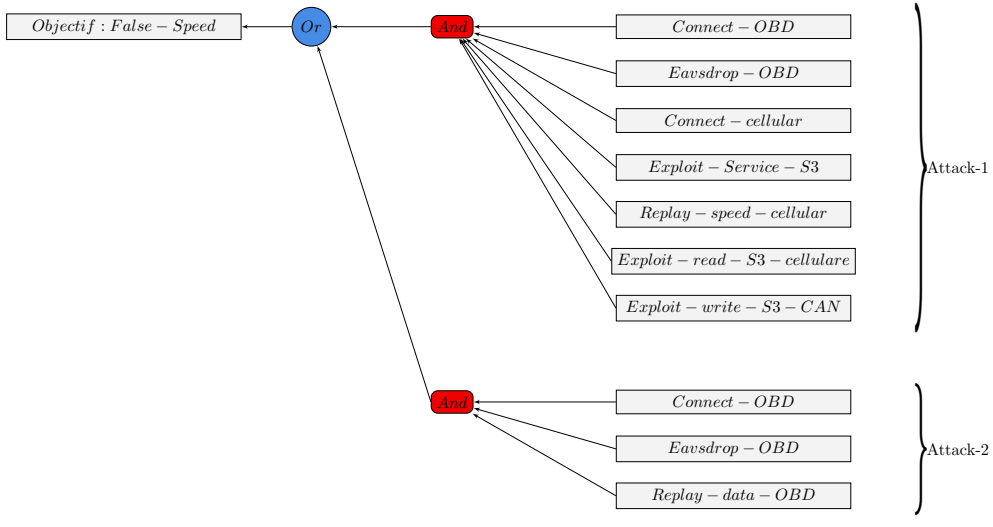

Figure : Attack tree: Speed acquisition and display

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Conclusion

- We need to consider security from design phase in order to build secure cars.
- We need to properly estimate the risk associated with threats.
- Attack trees are good tool for security risk assessment.
- Automatic generation of attack trees to overcome possible human errors and for exhaustivity.

Conclusion

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Thank you for your attention!

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