

Generalization and Learnability under Differential Privacy and its Variants

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Based on joint works with
Jing Lei and Steve Fienberg



The second Netflix Prize cancelled to settle a lawsuit

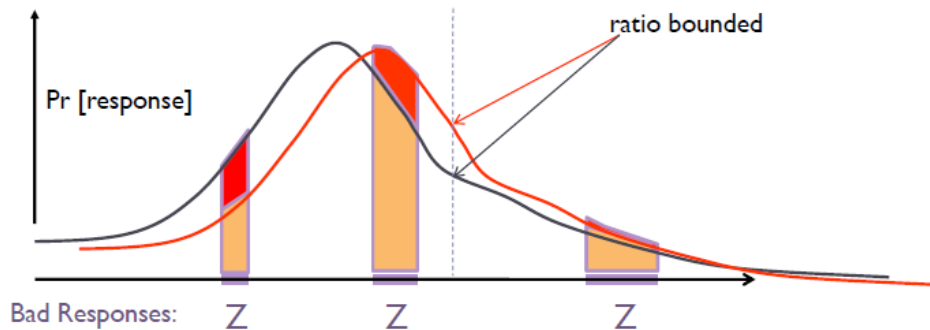
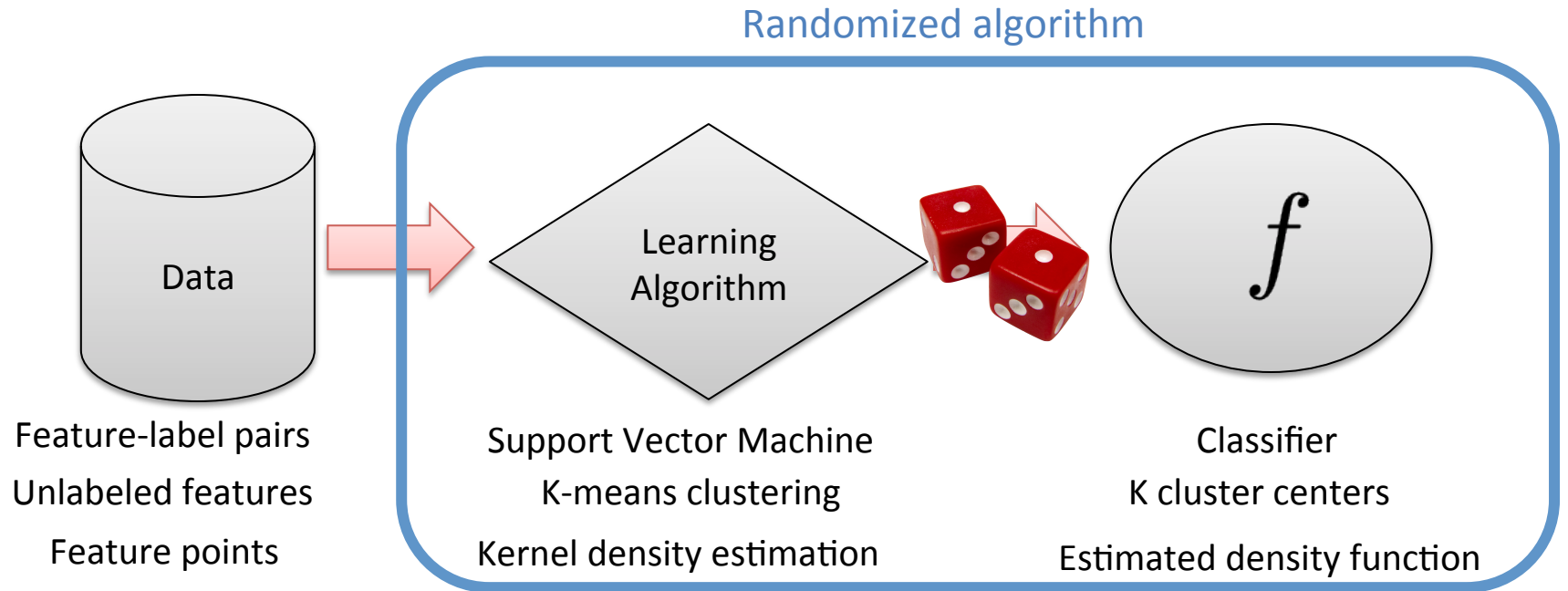


NYC's Taxi data set breached

Vijay Pandurangan posts:



Differentially private machine learning



Example: Recommendation System

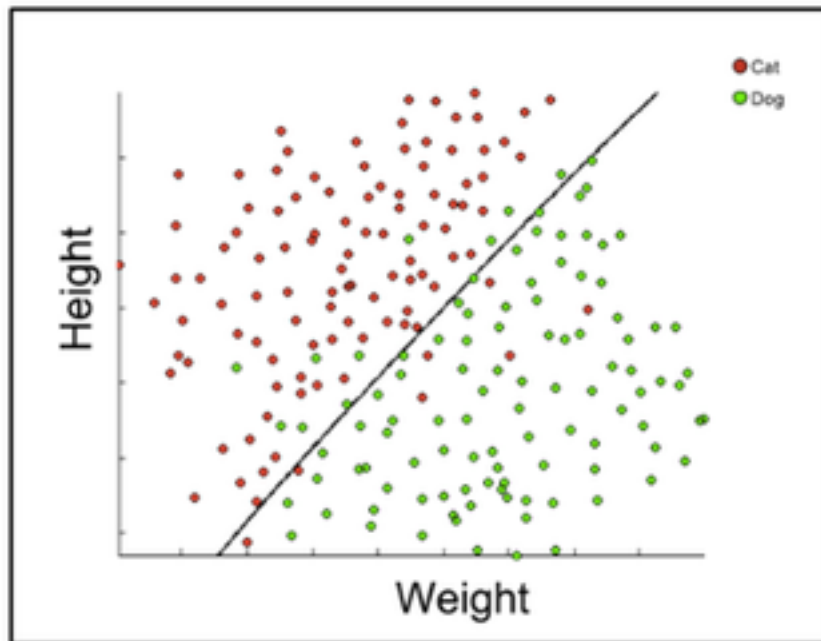
- Model based collaborative filtering.
 - Learning: $f \leftarrow A(Z)$ uses all user data.
 - Prediction: $y_i \leftarrow f(z_i)$ uses f and his own data.
- Setting:
 - Trust the service provider. Netflix is not an adversary.
 - Other users might be adversaries.
- If A is private, prediction is “post-processing”.

Synergy between learning and privacy

Underfitting

f is parsimonious

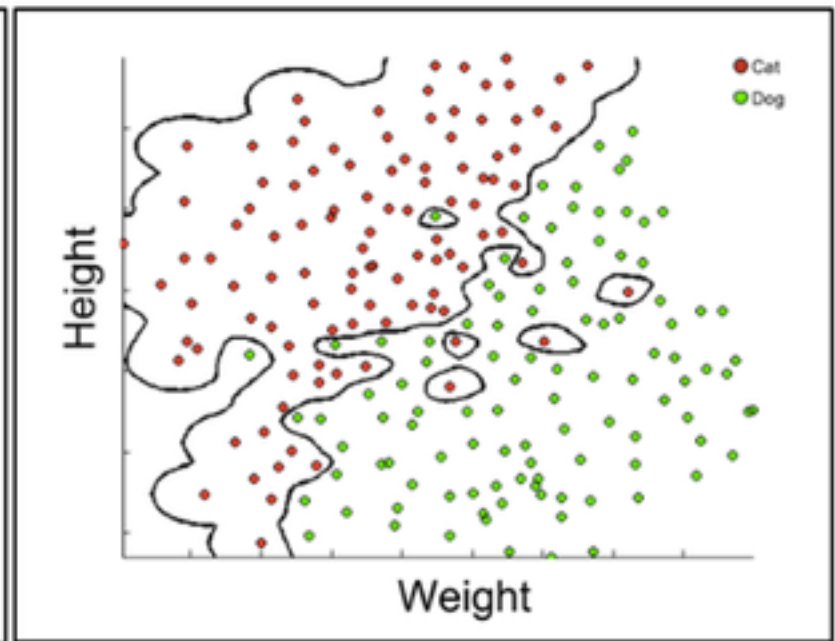
Private information compressed.



Overfitting

f memorizes the dataset

Knowing f breaches privacy



Plan today

- Revisiting “What can be learned privately?”
 - Vapnik’s General Learning Setting
 - Characterizing private learnability
- To what extent can we weaken DP?
 - But still preserve the basic property that “privacy => generalization”.
 - A characterization of on-avg generalization.

Notations

- Data domain \mathcal{Z} or $\mathcal{X} \times \mathcal{Y}$
- Hypothesis class \mathcal{H}
- Loss Function: $\ell : \mathcal{H} \times \mathcal{Z} \rightarrow \mathbb{R}$
- Task: find $h \in \mathcal{H}$ with low risk.

PAC Learning vs. General Learning Setting

(Agnostic) PAC Learning:
Binary classification.

- Logistic Regression
- Stochastic convex optimization
- Generalized Linear model
- Linear Regression
- RKHS Learning
- K-means clustering
- Kernel SVM
- Matrix factorization
- Recommender system
- Multiclass classification
- Density estimation

General Learning Setting

- Reinforcement Learning
 - Online learning

Problems in general learning setting

An illustration of problems in the General Learning setting.

| Problem | Hypothesis class \mathcal{H} | \mathcal{Z} or $\mathcal{X} \times \mathcal{Y}$ | Loss function ℓ |
|---------------------|---|---|--|
| PAC Learning | $\mathcal{H} \subset \{f : \{0, 1\}^d \rightarrow \{0, 1\}\}$ | $\{0, 1\}^d \times \{0, 1\}$ | $1(h(x) \neq y)$ |
| Regression | $\mathcal{H} \subset \{f : [0, 1]^d \rightarrow \mathbb{R}\}$ | $[0, 1]^d \times \mathbb{R}$ | $ h(x) - y ^2$ |
| Density Estimation | Bounded distributions on \mathcal{Z} | $\mathcal{Z} \subset \mathbb{R}^d$ | $-\log(h(z))$ |
| K-means Clustering | $\{S \subset \mathbb{R}^d : S = k\}$ | $\mathcal{Z} \subset \mathbb{R}^d$ | $\min_{c \in \mathcal{H}} \ c - z\ ^2$ |
| RKHS classification | Bounded RKHS | $\text{RKHS} \times \{0, 1\}$ | $\max\{0, 1 - y\langle x, h \rangle\}$ |
| RKHS regression | Bounded RKHS | $\text{RKHS} \times \mathbb{R}$ | $ \langle x, h \rangle - y ^2$ |
| Sparse PCA | Rank- r projection matrices | \mathbb{R}^d | $\ hz - z\ ^2 + \lambda \ h\ _1$ |
| Robust PCA | All subspaces in \mathbb{R}^d | \mathbb{R}^d | $\ \mathcal{P}_h(z) - z\ _1 + \lambda \text{rank}(h)$ |
| Matrix Completion | All subspaces in \mathbb{R}^d | $\mathbb{R}^d \times \{1, 0\}^d$ | $\min_{b \in \mathcal{H}} \ y \circ (b - x)\ ^2 + \lambda \text{rank}(h)$ |
| Dictionary Learning | All dictionaries $\in \mathbb{R}^{d \times r}$ | \mathbb{R}^d | $\min_{b \in \mathbb{R}^r} \ hb - z\ ^2 + \lambda \ b\ _1$ |
| Non-negative MF | All dictionaries $\in \mathbb{R}_+^{d \times r}$ | \mathbb{R}^d | $\min_{b \in \mathbb{R}_+^r} \ hb - z\ ^2$ |
| Subspace Clustering | A set of k rank- r subspaces | \mathbb{R}^d | $\min_{b \in \mathcal{H}} \ \mathcal{P}_b(z) - z\ ^2$ |
| Topic models (LDA) | $\{\mathbb{P}(\text{word} \text{topic})\}$ | Documents | $-\max_{b \in \{\mathbb{P}(\text{Topic})\}} \sum_{w \in z} \log \mathbb{P}_{b,h}(w)$ |

Learnability and Private Learnability

A learning algorithm: $\mathcal{A} : \mathcal{Z}^n \rightarrow \mathcal{H}$ is **consistent** for distribution \mathcal{D} if

$$\mathbb{E}_{Z \sim \mathcal{D}^n, z \sim \mathcal{D}} \mathbb{E}_{h \sim \mathcal{A}(Z^n)} \ell(h, z) \rightarrow \min_{h \in \mathcal{H}} \mathbb{E}_z \ell(h, z).$$

Definition 1 (Learnability) *A learning problem $(\mathcal{Z}, \mathcal{H}, \ell)$ is learnable if there exists an algorithm \mathcal{A} and rate $\xi(n)$, such that \mathcal{A} is consistent with rate $\xi(n)$ for any distribution \mathcal{D} defined on \mathcal{Z} . [Note: this is agnostic, distribution-free learning!]*

Private Learnability: Learnable by an ϵ -DP algorithm,
for an $\epsilon < \infty$

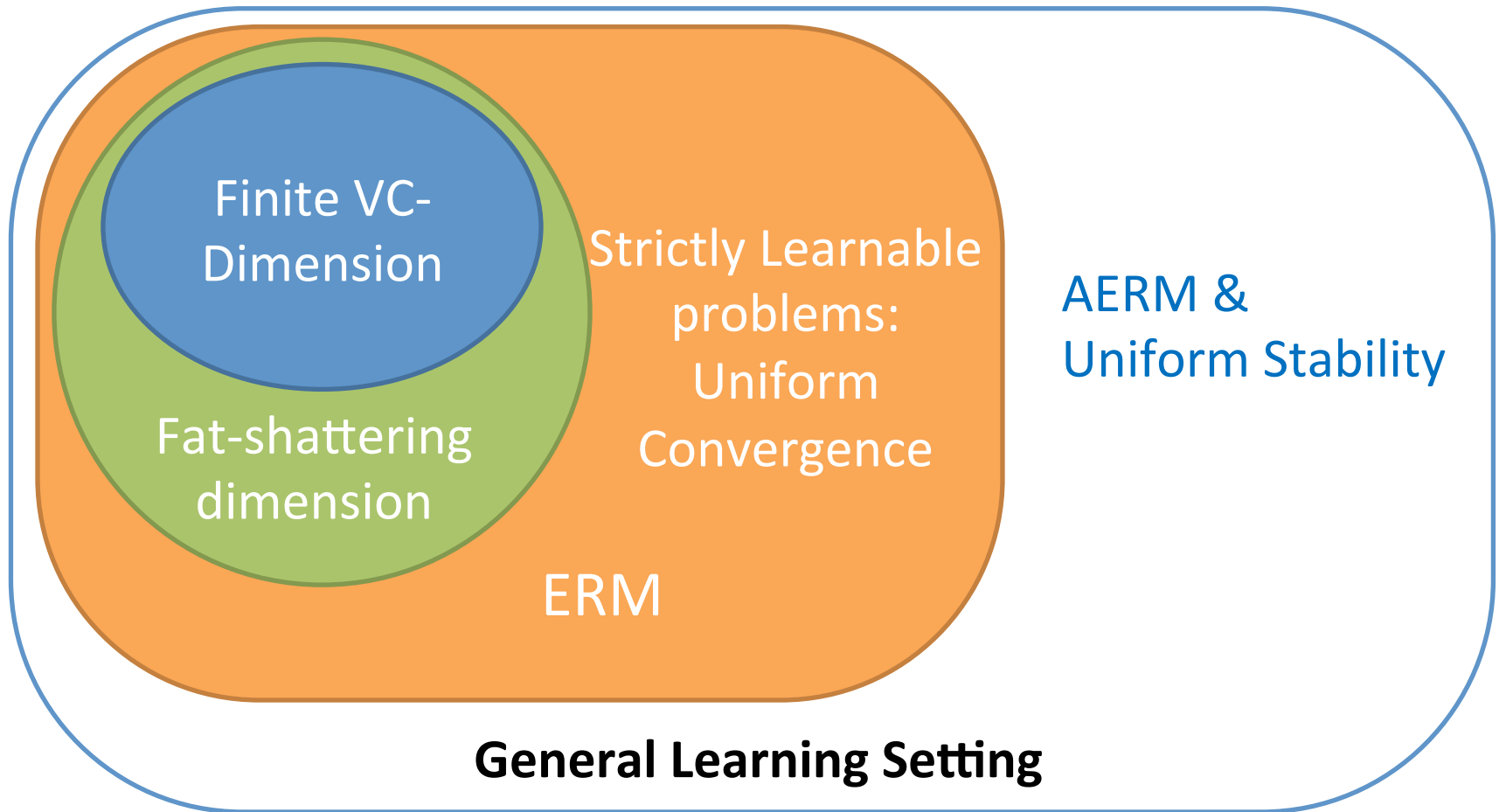
Defining Stability and AERM

- **Stability**: Any adjacent Z and Z' , the difference in the expected risk $\rightarrow 0$ as $n \rightarrow \infty$.
- **AERM**: the estimate minimizes empirical risk as $n \rightarrow \infty$.

What is known in non-private setting?

- PAC Learning (Binary Classification)
 - finite VC-dimension \Leftrightarrow Learnability (BEHW-89)
 - Achieved by ERM.
- General Learning Setting
 - Strict Learnable by ERM \Leftrightarrow Uniform Convergence (Vapnik-95)
 - \exists a problem learnable, but ERM fails. (SSSS-10)
 - AERM + Stability \Leftrightarrow Learnability (SSSS-10)

What is known in non-private setting?



What is known about private learnability?

- PAC Learning (on discrete domain):
 - SQ = Private SQ (BDMN-08)
 - PAC = Private PAC (KLNRS-08)
 - sample complexity on realizable setting (BNS-13).
- DP extensions of specific problems, or classes of problems.
 - (CMS-11, KST-12, BST-14) and many more.

What is known about private learnability?

SQ = PSQ. ("SuLQ", Blum et. al. 05)

PAC = PPAC
"What can we
SQ learn
privately?"

• Logistic Regression

• Stochastic convex optimization

• Generalized Linear model

• Linear Regression

• RKHS Learning
Kernel SVM

• K-means clustering

• Multiclass classification
• Density estimation

• Matrix factorization
• Recommender system

General Learning Setting

• Reinforcement Learning

• Online learning

Our result

PAC = PPAC

("What can be learned privately?",
Kasiviswanathan et. al., 08)

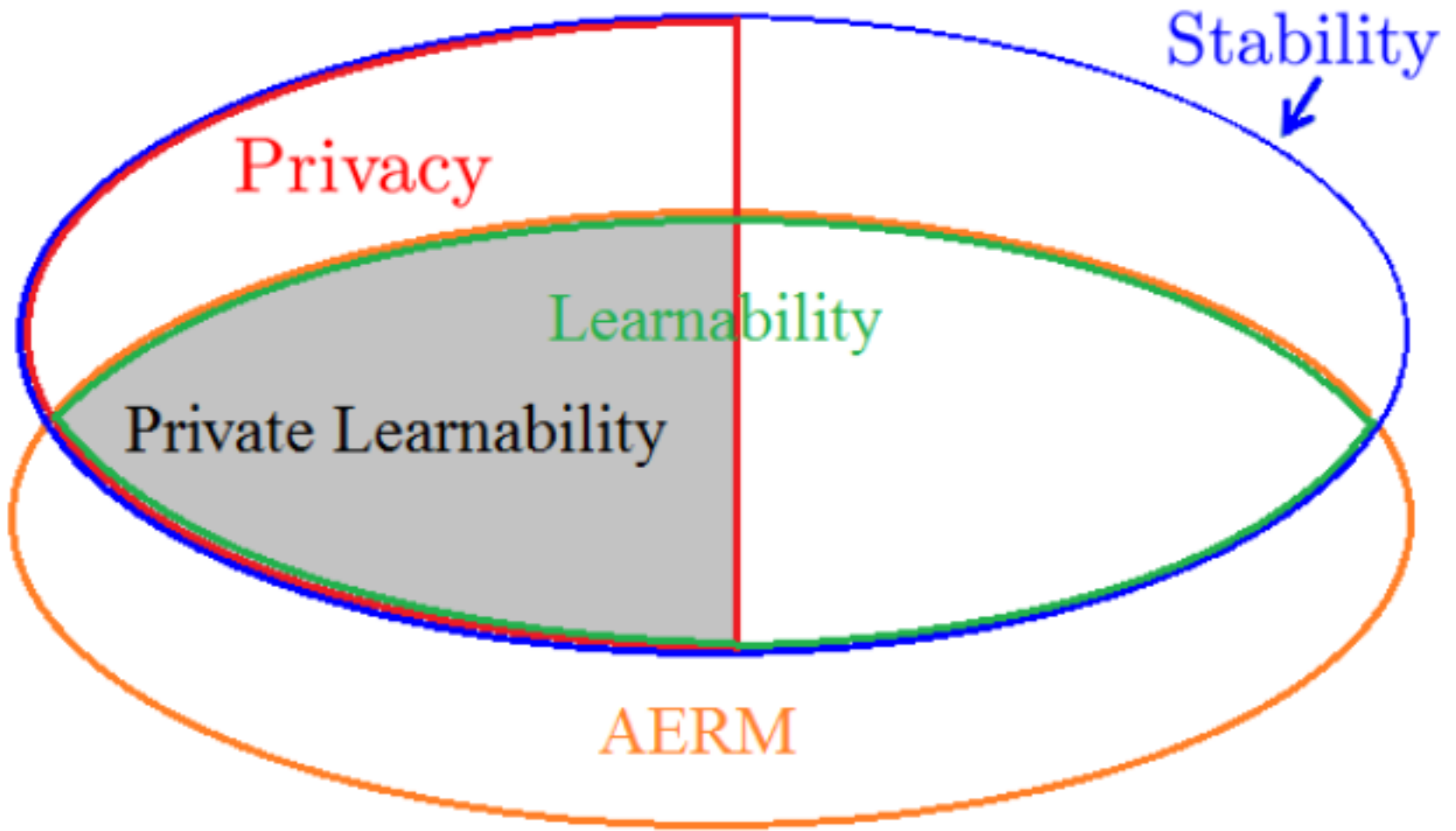
SQ=PSQ

Private Learnability = \exists Private AERM

NOT Privately Learnable = \nexists Private AERM

General Learning Setting

Characterizing Private Learnability



Key ideas of the proof

Subsampling Lemma [BKN-13]:

If A is ϵ -DP on Z of size n .

Then running A on a random subsample of Z with γn data points is $2\gamma \exp(\epsilon)$ -DP.

Take $\gamma = 1/\sqrt{n}$

Key ideas of the proof

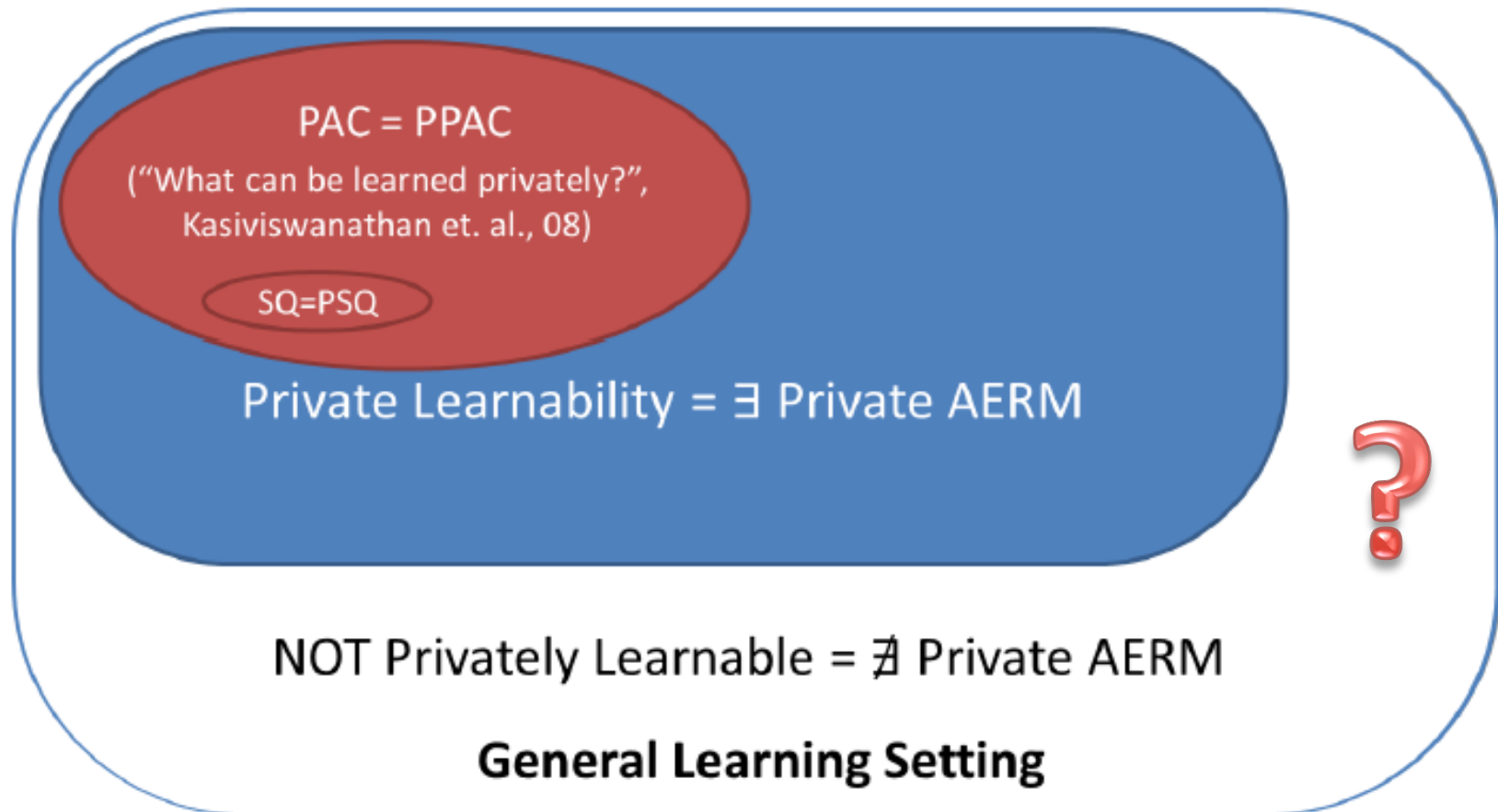
- Forward direction:
 - Private and AERM
 - Random subsample data (so that Privacy $\rightarrow 0$)
 - **Privacy \Rightarrow Stability \Rightarrow Generalization** (appeared in quite a few recent work, e.g., DFHPRR-14)
- Backward direction:
 - Given a private learning algorithm
 - Construct a new one by random subsampling
 - Show it's **AERM via distribution-free assumption.**

Implications

- The task reduces to finding a private ERM
- A generic procedure that produces a learning algorithm for **all privately learnable problems**:

$$\operatorname{argmin}_{\substack{(\mathcal{A}, \epsilon) : \\ \mathcal{A} : \mathcal{Z}^n \rightarrow \mathcal{H}, \\ \mathcal{A} \text{ is } \epsilon\text{-DP}}} \left[\epsilon + \sup_{Z \in \mathcal{Z}^n} \left(\mathbb{E}_{h \sim \mathcal{A}(Z)} \hat{R}(h, Z) - \inf_{h \in \mathcal{H}} \hat{R}(h, Z) \right) \right]$$

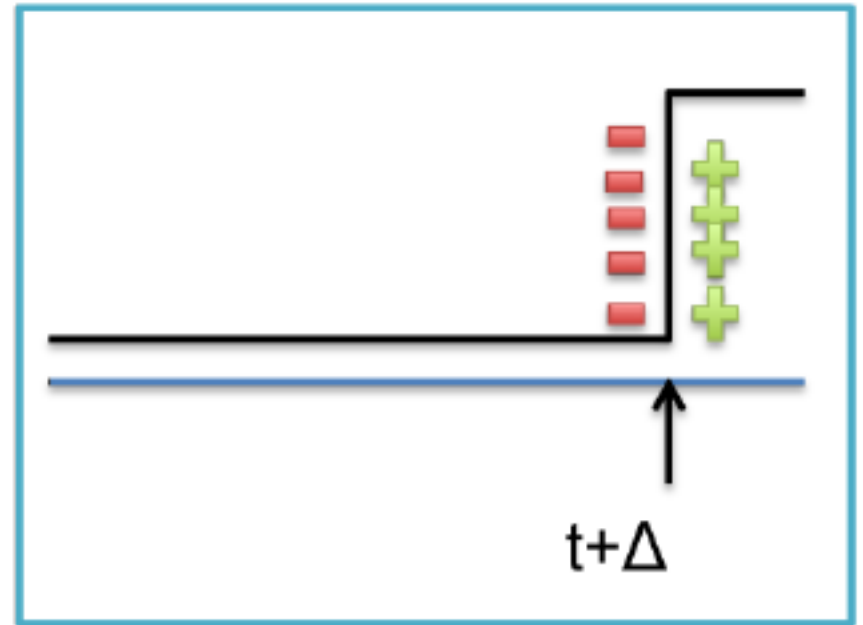
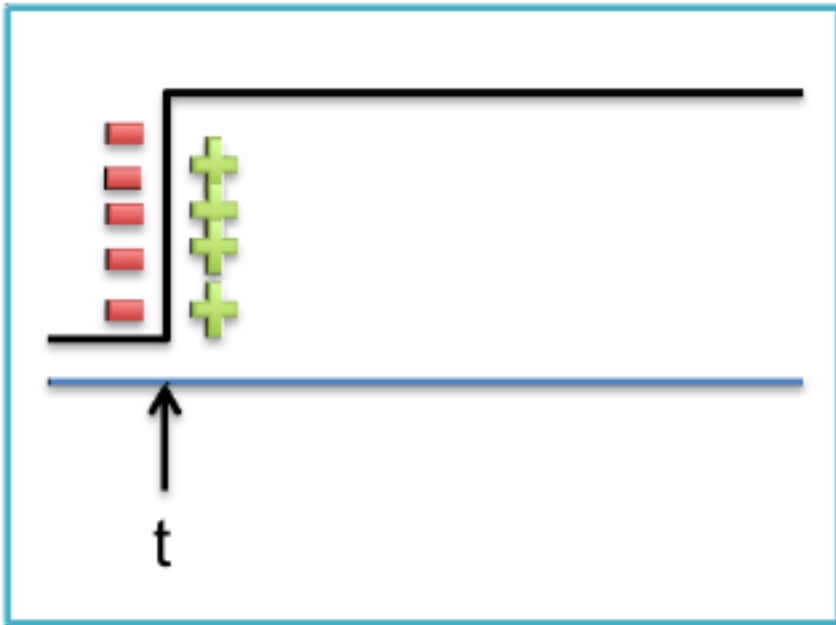
When can we learn but not privately learn?



Example in Chaudhuri and Hsu, 2011.

The difficulty of private classification in continuous domain (Chaudhuri and Hsu)

$$\frac{p(\mathcal{A}(Z))}{p(\mathcal{A}(Z'))} \leq \exp(n\epsilon).$$



Also, implicitly implied by sample complexity lower bound in [BKN13]

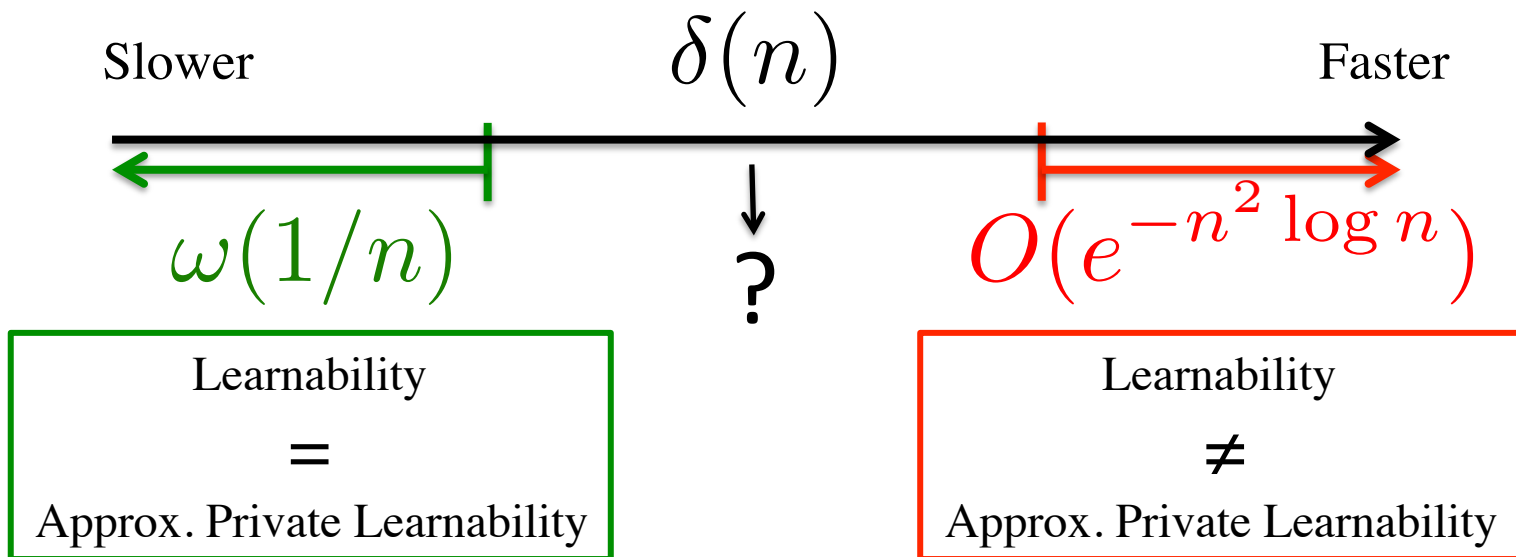
How to fix this?

- Lipschitz loss function, e.g., hinge loss.
- Drop the distribution-free requirement.
 - Private \mathcal{D} -learnability.

(ϵ, δ) -private learnability

- Extend subsampling lemma and stability lemma to (ϵ, δ) -DP.
- Results:
 - If we require $\delta = o(1/n)$,
 - Or if we require $\delta = o(1/\text{poly}(n))$,
 - Approx. Private AERM = Approx. Private Learnability.

Are all learnable problems (ϵ, δ) -privately learnable?



Story so far

- In general learning setting:
 - Private ERM learns all learnable problems.
 - Many problems are not privately learnable.
 - (ϵ, δ) -DP does not seem to solve the problem.
- Even if a problem is privately learnable...
 - might not be practical.

Practical frustrations with DP

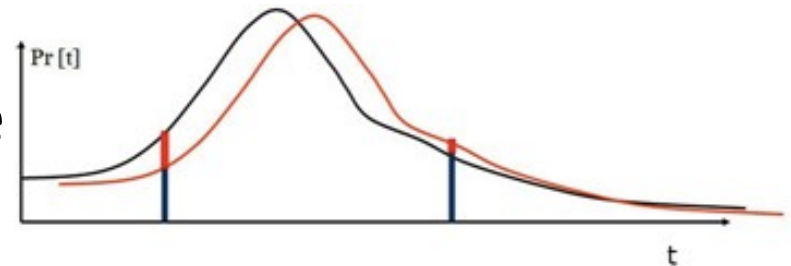
- Need to add too much noise/ruin inferences.
 - Resulting in poor utility.
 - E.g., Contingency Table (Fienberg et. al. 2010), GWAS data (Yu et. al., 15), etc.
- Need a lot of tricks/hacks to work
 - E.g., “clipping” “rescaling” as in the Netflix data.
- Worst-case guarantee
 - Protects the worst possible data set.
 - Sensitive to outliers.

Same randomization, many interpretations

- How small needs ϵ be?
 - ϵ -DP = 100
 - ϵ -Personal DP for each person. $\epsilon < 0.2$ for 95% of them.
 - On avg privacy: $\epsilon = 0.1$

Weakening the privacy definition

- “A” outputs two distributions from Z and Z' .
- Any privacy definition should require the two distributions to be close.
 - ϵ -DP \Leftrightarrow ϵ -Max-Divergence



- Use weaker distance measure?

Divergence privacy and f-divergence

- First seen in Barber & Duchi (2014).

$$D_f(P \parallel Q) \equiv \int_{\Omega} f \left(\frac{dP}{dQ} \right) dQ.$$

- With P, Q being $A(Z), A(Z')$
- When $f = x \log x$, this becomes **KL-divergence**.

$$D_{KL}(P \parallel Q) = \int_{\Omega} \frac{dP}{dQ} \log \frac{dP}{dQ} dQ$$

On-Average KL-Privacy

- Differential Privacy:

$$\sup_{Z, Z': d(Z, Z') \leq 1} \sup_{h \in \mathcal{H}} \log \frac{p_{h \sim \mathcal{A}(Z)}(h)}{p_{h \sim \mathcal{A}(Z')}(h)} \leq \epsilon$$

- On-Average KL-Privacy:

$$\mathbb{E}_{Z \sim \mathcal{D}^n, z \sim \mathcal{D}} \mathbb{E}_{h \sim \mathcal{A}(Z)} \left[\log \frac{p_{h \sim \mathcal{A}(Z)}(h)}{p_{h \sim \mathcal{A}([Z_{-1}, z])}(h)} \right] \leq \epsilon.$$

On-Average KL-Privacy

- Measures the **average privacy loss** for a particular data generating distribution.
- Unaffected by rare pathological cases.
- Adapt to easy distributions.

Properties of on-average KL-Privacy

- Inherent properties of DP
 - Small group composition
 - Adaptive Composition (caveat:
 - Closed to post-processing
- Does not need bounded loss function!
- When the loss function is bounded, the same algorithm guarantees DP.

Reusable Holdout/Adaptive Data Analysis

- A: learning algorithm output h .

A is ϵ -DP \Rightarrow A has generalization error bound ϵ

Definition:

Generalization error = $E | \text{Risk} - \text{Empirical Risk} |$.

Dwork et al. "Preserving statistical validity in adaptive data analysis." FOCS'14.

Dwork et al. "The reusable holdout: Preserving validity in adaptive data analysis." Science 349.6248 (2015): 636-638.

Dwork et al. "Generalization in adaptive data analysis and holdout reuse." NIPS (2015).

Characterizing the generalization

$$p(h) \propto \exp(-\mathcal{L}(Z))\pi(h)$$

Theorem: If **A** is a **posterior sampling** algorithm for some model:

ϵ -on-average KL-Privacy \Leftrightarrow ϵ -on-avg-generalizing

For each distribution separately

Definition:

On-avg-generalization = **| Risk - E Empirical risk |**

W., Lei, and Fienberg (2016). "On-Average KL-Privacy and its equivalence to Generalization for Max-Entropy Mechanisms." arXiv:1605.02277.

Why posterior sampling?

- A variational justification:
 - It arises out of a **maximum entropy** framework.

$$\min_{\mathcal{A}} \underbrace{-H(\mathcal{A}(Z)|Z)}_{\text{An information criterion}} + \underbrace{\mathbb{E}\mathcal{L}(\mathcal{A}(Z), Z)}_{\text{The utility measure}}$$

- The optimal solution:

$$\mathcal{A}^*(Z) \sim p(h|Z) \propto \exp(-\mathcal{L}(h, Z))$$

Tishby, Pereira & Bialek (2000). The information bottleneck method.
Mir (2012). Information-theoretic foundation of differential privacy.

Why posterior sampling?

$$\begin{array}{l} \operatorname{argmin}_{(\mathcal{A}, \epsilon) :} \\ \mathcal{A} : \mathcal{Z}^n \rightarrow \mathcal{H}, \\ \mathcal{A} \text{ is } \epsilon\text{-DP} \end{array} \left[\epsilon + \sup_{Z \in \mathcal{Z}^n} \left(\mathbb{E}_{h \sim \mathcal{A}(Z)} \hat{R}(h, Z) - \inf_{h \in \mathcal{H}} \hat{R}(h, Z) \right) \right]$$

Softer privacy *Replacing with E*

$$\min_{\mathcal{A}} -H(\mathcal{A}(Z)|Z) + \mathbb{E} \mathcal{L}(\mathcal{A}(Z), Z)$$

Why posterior sampling?

- A statistical justification:
 - Near optimal efficiency
 - Asymptotic normality
 - Works even under model misspecification.

Wang, Fienberg and Smola. "Privacy for Free: Posterior Sampling and Stochastic Gradient Monte Carlo." ICML'15.

Implication to adaptive data analysis

- Dwork et. al. 2015: Max-Information

k-max-information \Rightarrow k/n-on-average KL-Privacy

For any distribution

- Russo & Zou 2015: Mutual information

$$I(\mathcal{A}(Z), Z) \leq \text{On-Avg-Gen.} \leq \sigma \sqrt{2I(\mathcal{A}(Z), Z)}$$

For each distribution separately

The first lower bound of this form.

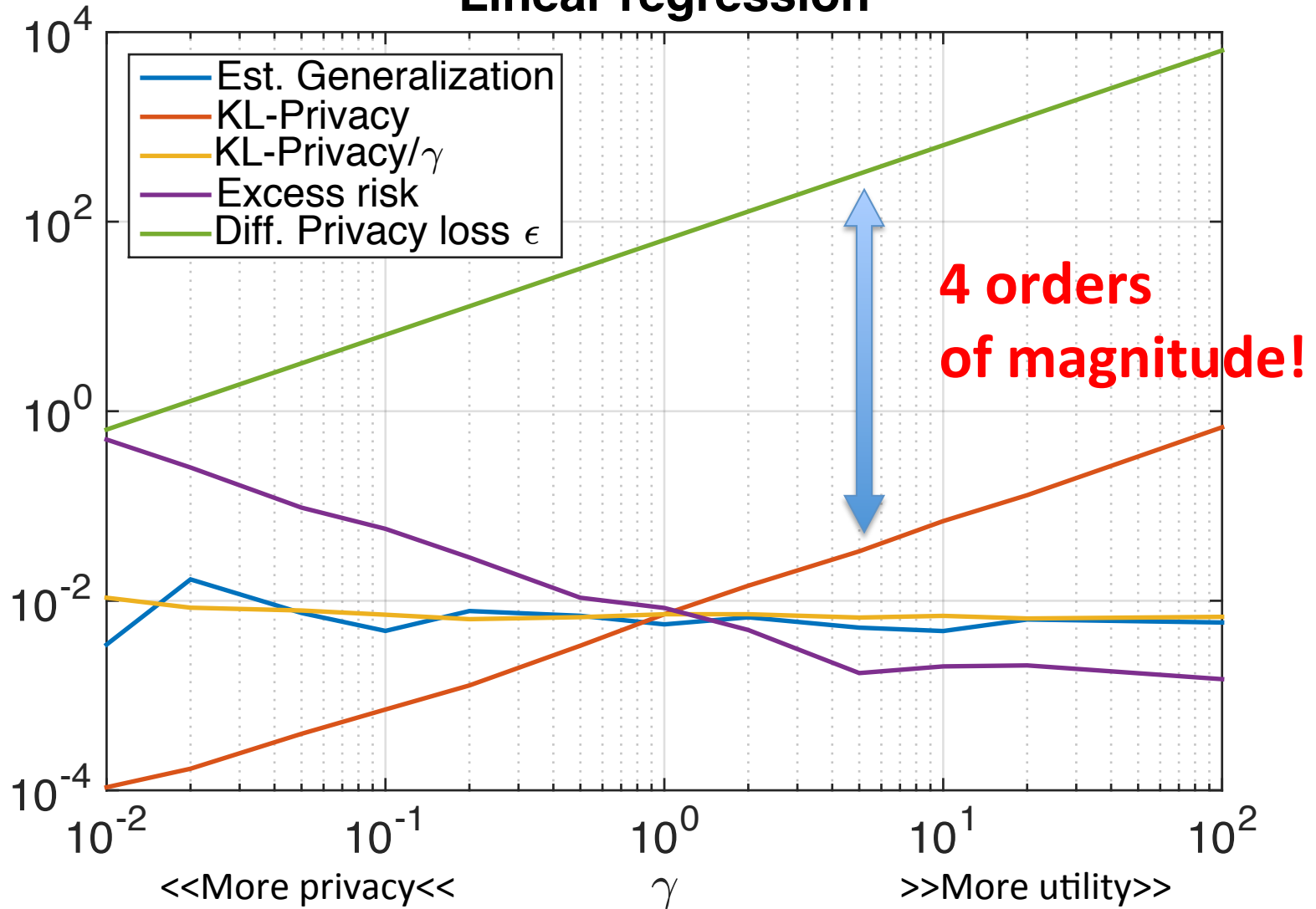
An example on Linear Regression

- Each user is (x,y) . We have 100 of them.
- Assume (x,y) are inside $[-2,2] \times [-1,1]$
- We want to privately fit a linear regression
 - $y = x \beta_1 + \beta_0$
 - From a bounded space (β_1, β_0) in $[-2,2]^2$
- Loss function is $(y - x \beta_1 - \beta_0)^2$
- Privately release through posterior sampling

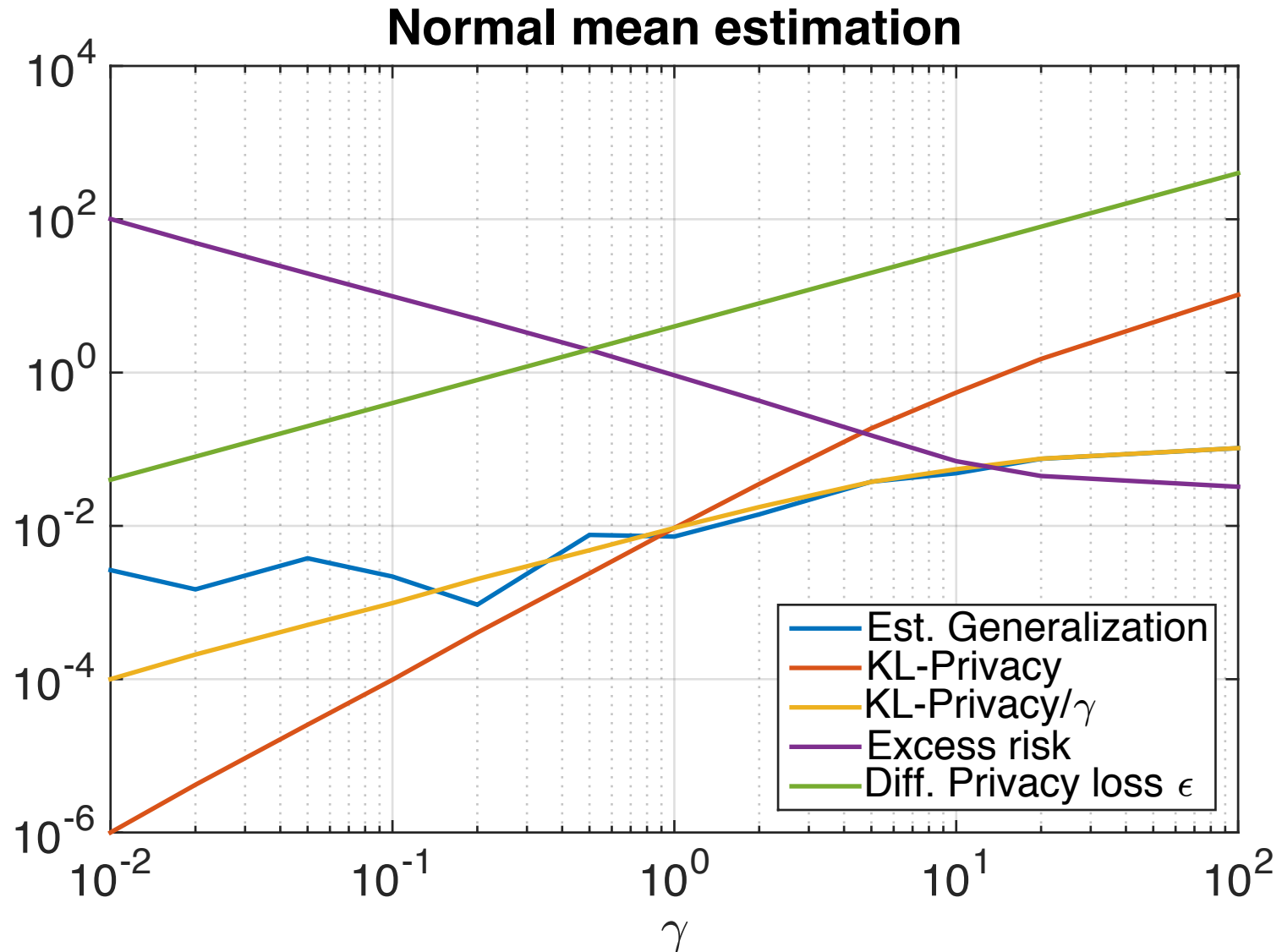
$$(\hat{\beta}_0, \hat{\beta}_1) \sim \frac{1}{K} e^{-\gamma \sum_{i=1}^n (y_i - \beta_0 - x_i \beta_1)^2}$$

Experiment on Linear Regression

Linear regression



Experiment: normal mean



Summary of On-Avg-KL Privacy

- No changes in algorithm
 - Average case privacy guarantee.
 - Practically meaningful
 - Esp. , when ϵ is too large.
- Characterizing the on-average generalization
 - Lower bounds of bias in terms of mutual information.

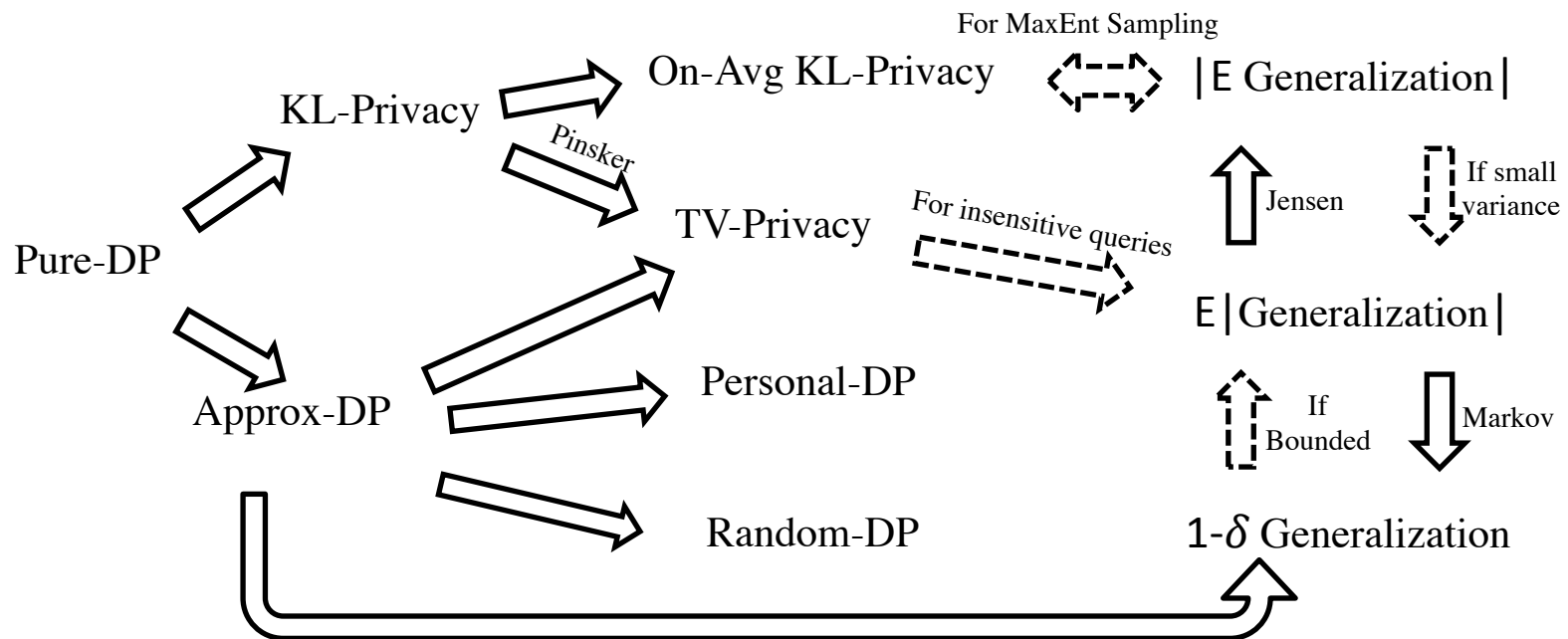
Variants of Differential Privacy

| Privacy definition | Z | z | Distance (pseudo)metric |
|--------------------|--|--|---|
| Pure DP | $\sup_{Z \in \mathcal{Z}^n}$ | $\sup_{z \in \mathcal{Z}}$ | $D_\infty(P Q)$ |
| Approx-DP | $\sup_{Z \in \mathcal{Z}^n}$ | $\sup_{z \in \mathcal{Z}}$ | $D_\infty^\delta(P Q)$ |
| Personal-DP | $\sup_{Z \in \mathcal{Z}^n}$ | for each z | $D_\infty(P Q)$ or $D_\infty^\delta(P Q)$ |
| KL-Privacy | $\sup_{Z \in \mathcal{Z}^n}$ | $\sup_{z \in \mathcal{Z}}$ | $D_{\text{KL}}(P Q)$ |
| TV-Privacy | $\sup_{Z \in \mathcal{Z}^n}$ | $\sup_{z \in \mathcal{Z}}$ | $\ P - Q\ _{\text{TV}}$ |
| Rand-Privacy | $1 - \delta_1$ any \mathcal{D}^n | $1 - \delta_1$ any \mathcal{D} | $D_\infty^{\delta_2}(P Q)$ |
| On-Avg KL-Privacy | $\mathbb{E}_{Z \sim \mathcal{D}^n}$ for each \mathcal{D} | $\mathbb{E}_{Z \sim \mathcal{D}}$ for each \mathcal{D} | $D_{\text{KL}}(P Q)$ |

Table 1. Summary of different privacy definitions.

For references of these privacy notions, please refer to the paper:
<http://arxiv.org/abs/1605.02277>

Their connections to generalization



In summary

- Two recent work that investigates the connections of privacy and learning.
- Formalize the equivalence of generalization with some notion of privacy (for MaxEnt mechanisms).
- A practically useful interpretation of DP-algorithms.
- Towards practical privacy protection.