

Lecture #2.

A Model of Distributed Computation

Distributed System Model:

- a set of processes connected by a communication network.

System Model:

- provides the facility to exchange information among processors.
- finite but unpredictable communication delay.
- no common global memory and communicate solely by passing messages.
- no physical global clock.
- messages may be delivered out-of-order, may be lost, garbled, or duplicated
- processors may fail
- communication links may go down.

⇒ System can be modeled as a graph

vertices: processes.

edges: links

A distributed Program.

is composed of a set of n asynchronous
Processes labelled

$P_1, P_2, \dots, P_n$

WLOG: assume each P_i on a different processor.

C_{ij} : communication channel between P_i & P_j

m_{ij} : denotes a message sent from P_i to P_j .

Global state :

$$\{\text{states of } P_i\} \cup \{\text{states of } C_{ij}\}$$



local memory



messages in transit.

A model of distributed executions,

- the execution of a process consists of a sequential execution of its actions.

- actions are atomic and are of three types:

1. Internal events
2. message send events
3. message receive events.

event e_i^x : x^{th} event at P_i .

msg m : $\text{send}(m)$
 $\text{recv}(m)$

Events cause:

state transition of processes

state transition of channels

$\Rightarrow$ affect the global state.

Internal event : only affect the process.

send event : affects the sender and the ~~end~~ channel.

receive event : affects the receiver and the channel.

events @ P_i : linear sequence.

$e_i^1, e_i^2, \dots, e_i^x, e_i^{x+1}, \dots$

$$H_i = (h_i, \rightarrow_i)$$

ordering relation

$$e_i^x \rightarrow e_i^{x+1}$$

$\rightarrow_i$: causal ordering or dependence.

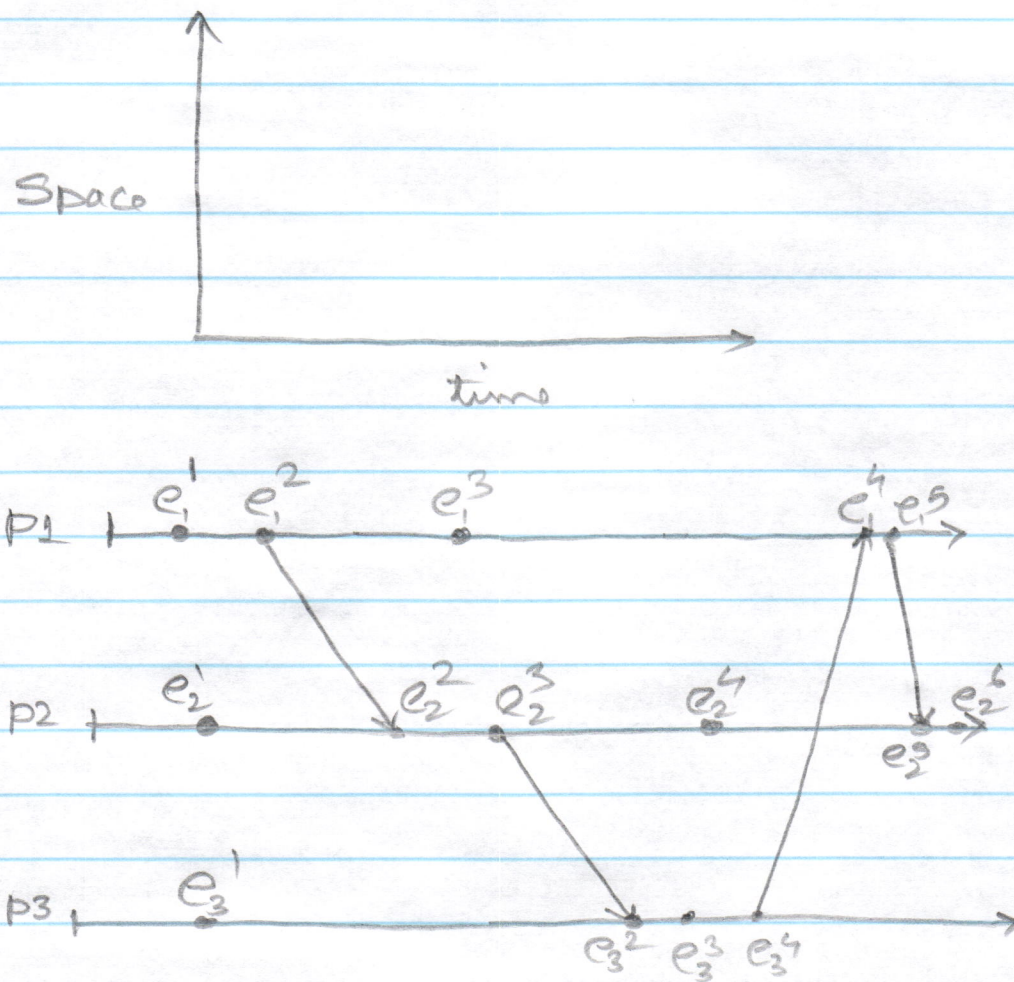
send and receive events capture the flow of information between processes

$\rightarrow_{msg}$: causal dependency due to messages.

For every m :

$$\text{send}(m) \xrightarrow{msg} \text{recv}(m)$$

A natural way to visualize the evolution of distributed computation is to use space-time diagrams.



Causal Precedence Relation

$$H = \bigcup_i h_i$$

Define a binary relation

$$(H, \rightarrow)$$

$$\forall e_i^x, \forall e_j^y \in H \quad e_i^x \rightarrow e_j^y$$

iff.

$$1. \quad e_i^x \rightarrow e_i^y \text{ (i.e., } i=j \wedge x < y \text{)}, \text{ or}$$

$$2. \quad e_i^x \rightarrow_{\text{msg}} e_j^y, \text{ or}$$

$$3. \quad \exists e_k^z \text{ s.t. } e_i^x \rightarrow e_k^z \wedge e_k^z \rightarrow e_j^y.$$

Called the happens-before relation.

Concurrent events:

e_i and e_j are concurrent $e_i \parallel e_j$

iff

$$e_i \nrightarrow e_j \wedge e_j \nrightarrow e_i$$

For any two events $e_i \nrightarrow e_j$:

either

$$e_i \rightarrow e_j$$

or

$$e_j \rightarrow e_i$$

$$\text{or } e_i \parallel e_j$$

Models of Communication NWS.

FIFO : channel is a queue

non-FIFO : channel is a set

Causal Order: channels satisfy happen-before
 $m_{ij} + m_{kj}$

if $\text{send}(m_{ij}) \rightarrow \text{send}(m_{kj})$

then $\text{recv}(m_{ij}) \rightarrow \text{recv}(m_{kj})$.

Causally related messages destined to the same destination are delivered in an order consistent with the causality.

$CO \subset FIFO \subset \text{NON-FIFO}$.

CO considerably simplifies the design of distributed algorithms.

e.g. updates to replica

Global State of a distributed system.

$$\{\text{state of } p_i\} \cup \{\text{state of } c_i\}.$$

↓

LS_i^x : state of p_i after e_i^x . (initial state: LS_i^0).

$$SC_{ij}^{x,y} = \{m_{ij} \mid \text{send}(m_{ij}) < LS_i^x \wedge \text{recv}(m_{ij}) \leq LS_j^y\}$$

denotes all messages that p_i sent up to event e_i^x and p_j has not received until e_j^y .

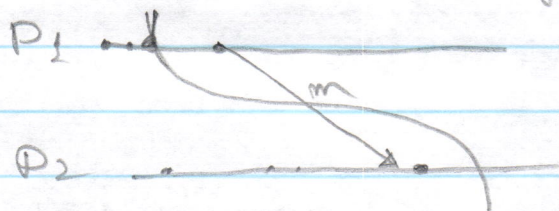
$$GS = \left\{ \bigcup_i LS_i^{x_i}, \bigcup_{j,k} SC_{jk}^{y_j, z_k} \right\}$$

Meaningful GS : ~~all~~ states of all components must be recorded at a single instant.



This is generally not possible.

So what can go wrong? Construct an example



⇒ PR says m is record
but P_1 has no
memory of it being sent.

$\Rightarrow$ when a snapshot is taken

$\downarrow$

not all snapshots be consistent.

GS is consistent iff

$$\forall m_{ij} : \text{send}(m_{ij}) \leq LS_i^{x_i} \Rightarrow m_{ij} \notin S_{ij}^{x_i, y_j} \\ \wedge \\ \text{recv}(m_{ij}) \notin LS_j^y$$

CUTS