

OverSEA

Synchronous Remote Maintenance Systems

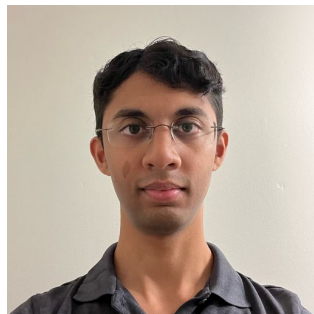
Meet the Team



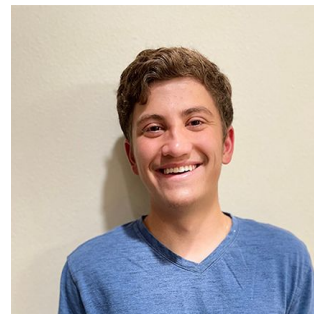
Fluellen Arman Umali
(Team Lead)



Yvonne Liu
(Scribe)



Rahul Dharmaji



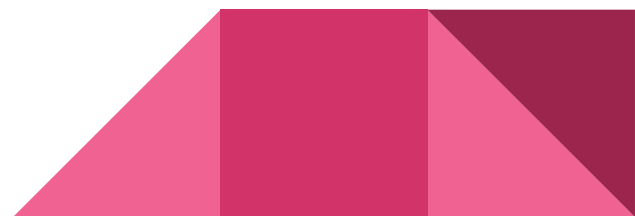
Daniel Eskander



Jason Em



Sponsor: NAVSEA
Mentor: Alan Jaeger

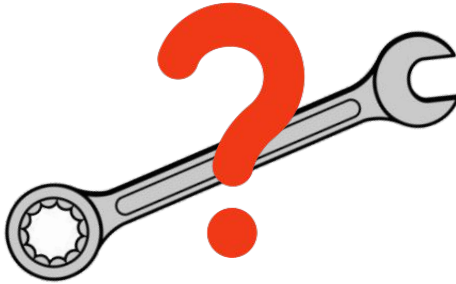


Scenario

Ship Worker: Xavier Gomez (19yo)

Background: He is a young recruit tasked with fixing equipment on the ship.

Problem: The equipment has an issue that Gomez has no expertise on.

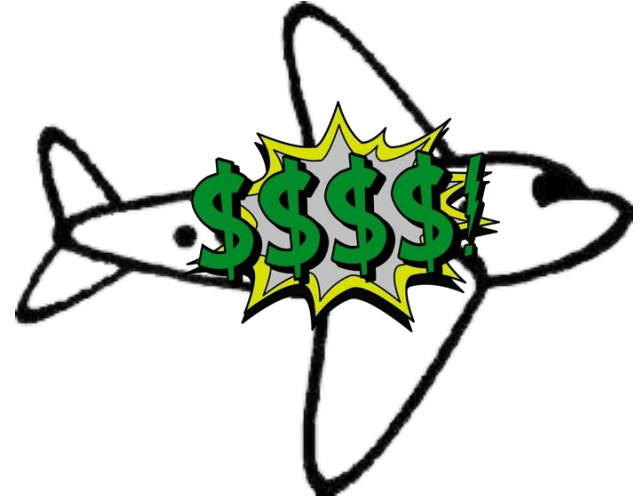


How would he get help?




Problem Statement

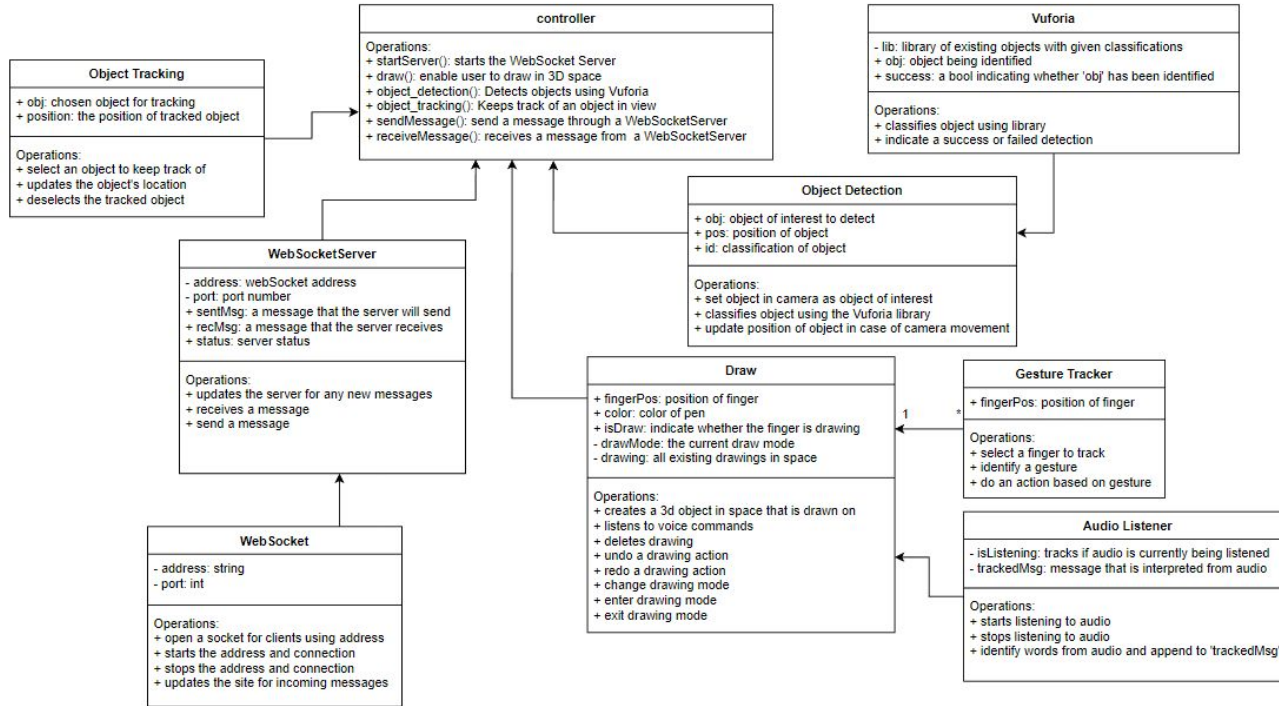
- Maintenance requires flying experts on-site
- Negative impacts on system reliability
 - Costly
 - Resource inefficient
 - Logistically challenging
- Unstable operation in times of war or turmoil
- Specialized personnel are a liability in combat



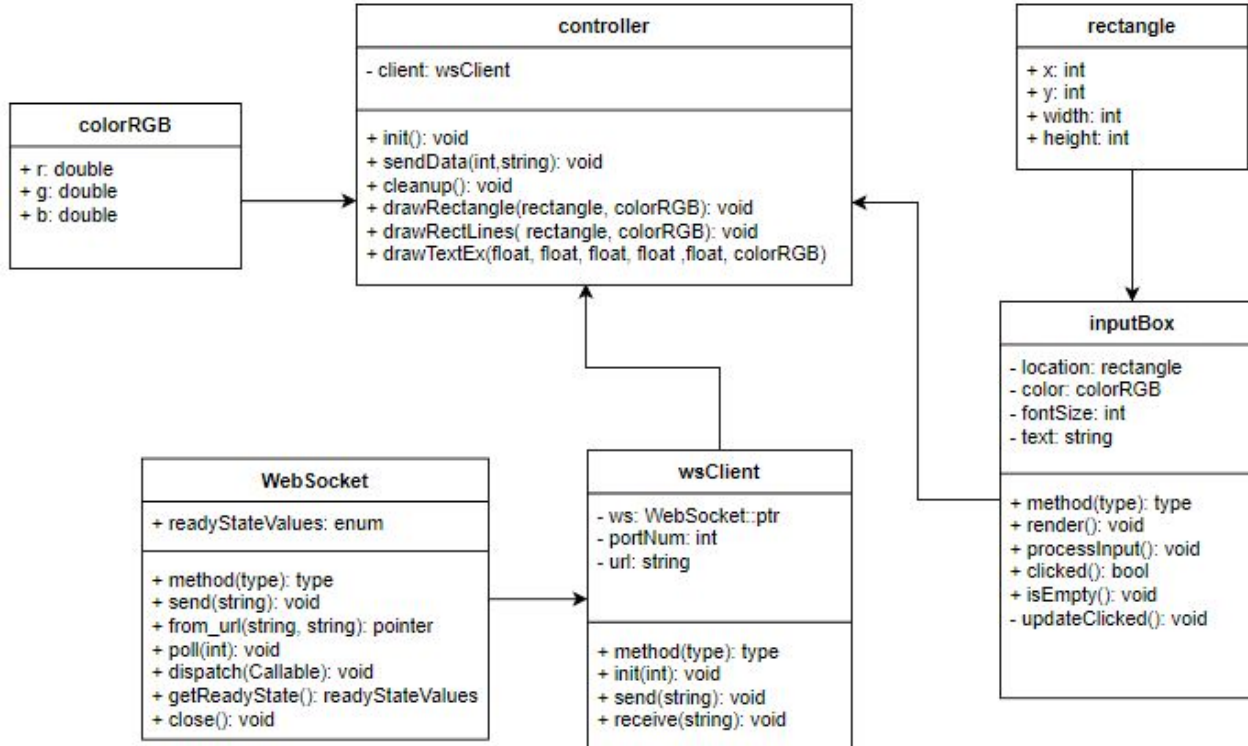
Our Solution

- We use AR headsets, allowing the specialist to communicate with the sailor via a remote computer application
 - Development of three components/interfaces
 - HoloLens drawing and object detection,
 - Remote Client application
 - A server-client connection between the HoloLens and the Client
 - Seamless experience for remote specialist to help sailors
 - Low-cost solution to the remote maintenance problem
- 

System Architecture Overview - Server



System Architecture Overview - Client



Two Separate Applications

Application Server

- ❖ HoloLens user (mechanic)
- ❖ Broadcasts video to client
- ❖ AR drawing capabilities
- ❖ Communication via WebSockets
- ❖ Broadcasts video to Client

Client

- ❖ Remote user (specialist)
- ❖ Allows viewing and interaction with the HoloLens user's environment
- ❖ Communication via WebSockets
- ❖ Receives video from Server



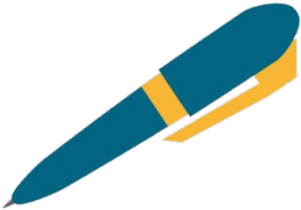
Communication Diagram



~ 3,500 miles away ~

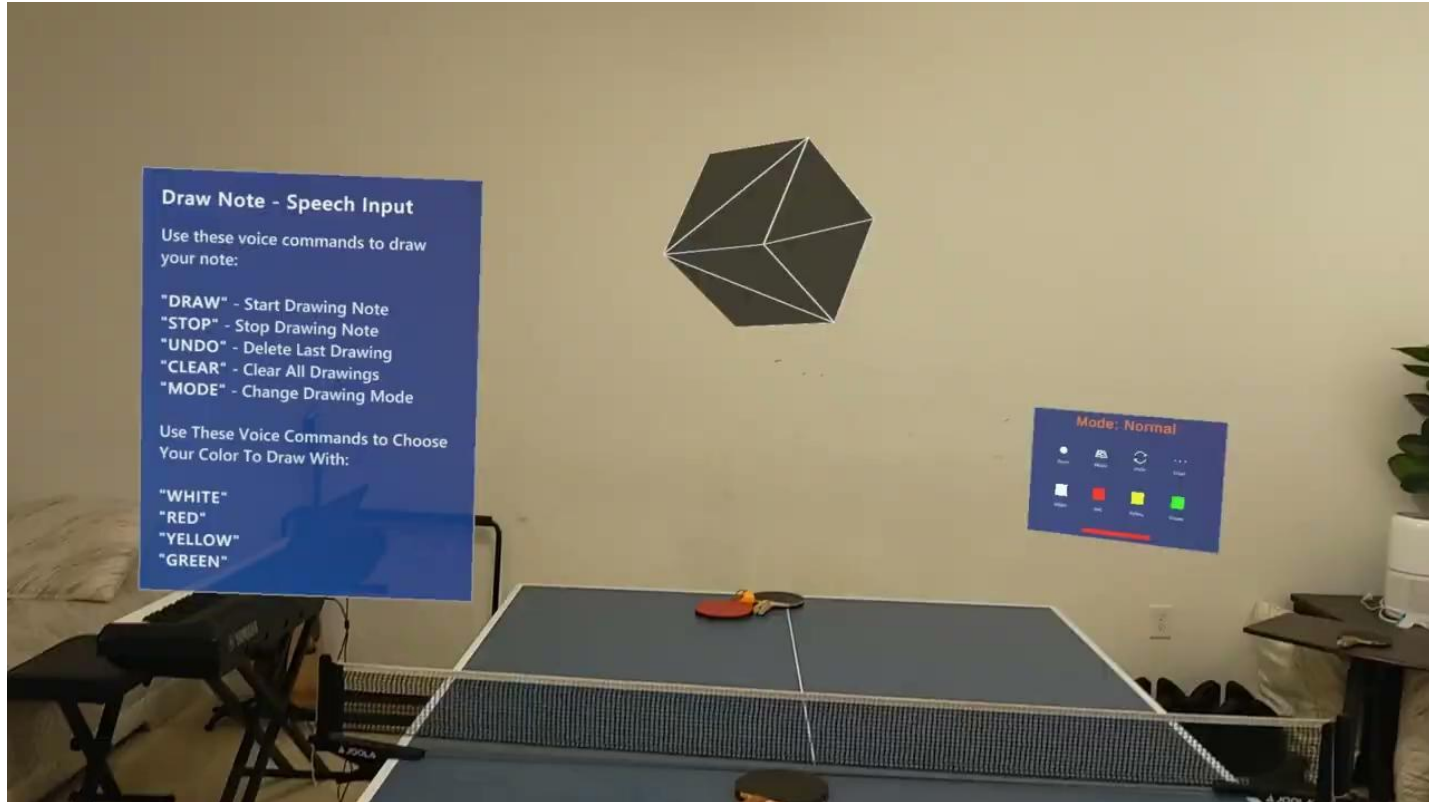


Xavier Gomez
(Application Server)



Specialist
(Client)

Demonstration - AR Drawing Component



Demonstration - Object Detection Component

Bottle v7

Distance: 0.469m

X	-43.5°	0.259m
Y	49.4°	0.323m
Z	120.5°	0.109m

0.06m

0.06m

0.23m

Guide Views

GuideView_0000

⚠ Object is too far from the camera!

GuideView_0001

⚠ Object is too far from the camera!

GuideView_0002

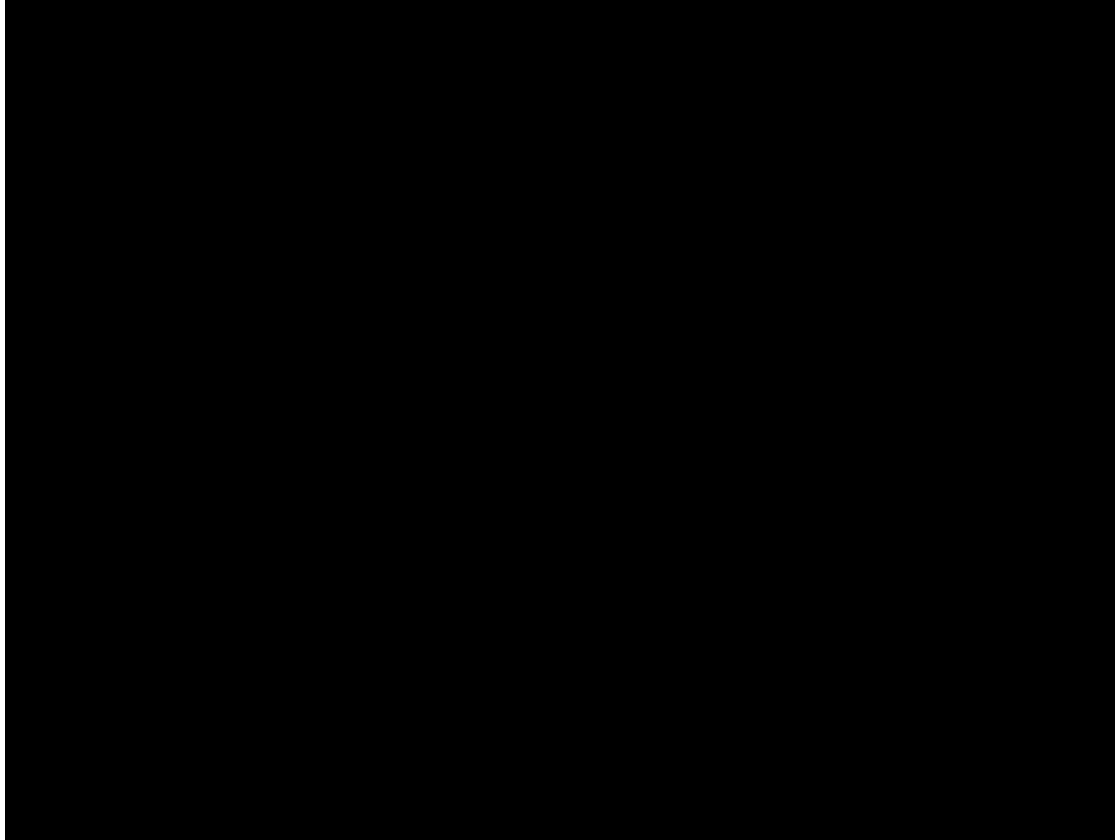
⚠ Object is too far from the camera!

Delete Views

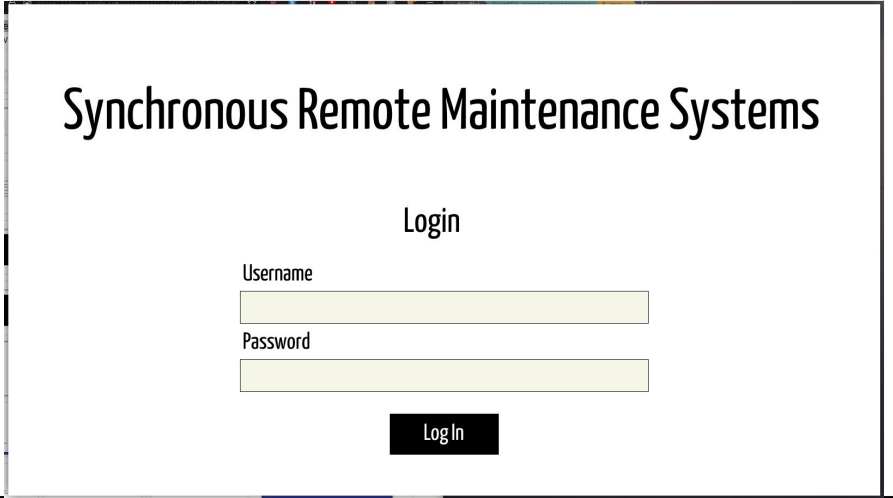
Add View

Generate Standard Model Target

Demonstration - Object Detection Component



Demonstration - Receiver



Synchronous Remote Maintenance Systems

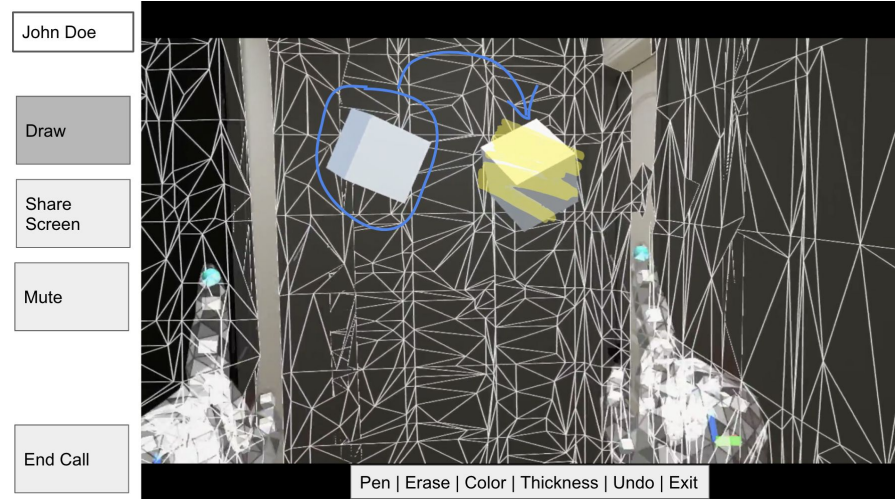
Login

Username

Password

Login

This is the login page on the receiver side. They will have a given username and password in order to ensure security.



This is the main page, in a call, that the receiver will see. They have the ability to draw on the hololens camera stream and talk to the hololens user directly.

Novelties and Challenges

- Delays in obtaining equipment
 - Received second HoloLens in week 5
- Steep HoloLens learning curve
- Integrating cross-app communication
 - Video components are in progress
- WebSocket protocol challenges
 - Header information inconsistent
- HoloLens video export is quite complicated
 - Our existing solution for video export is not feasible
 - Limitation with HoloLens to overcome with external libraries

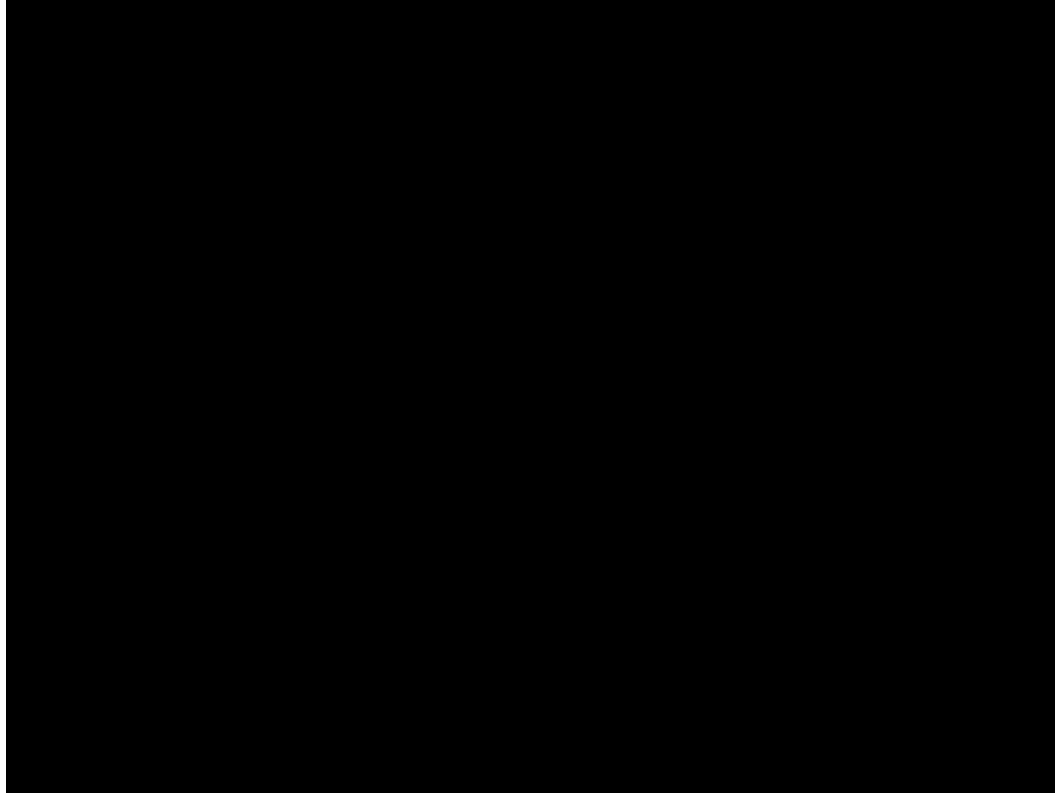


Next Steps

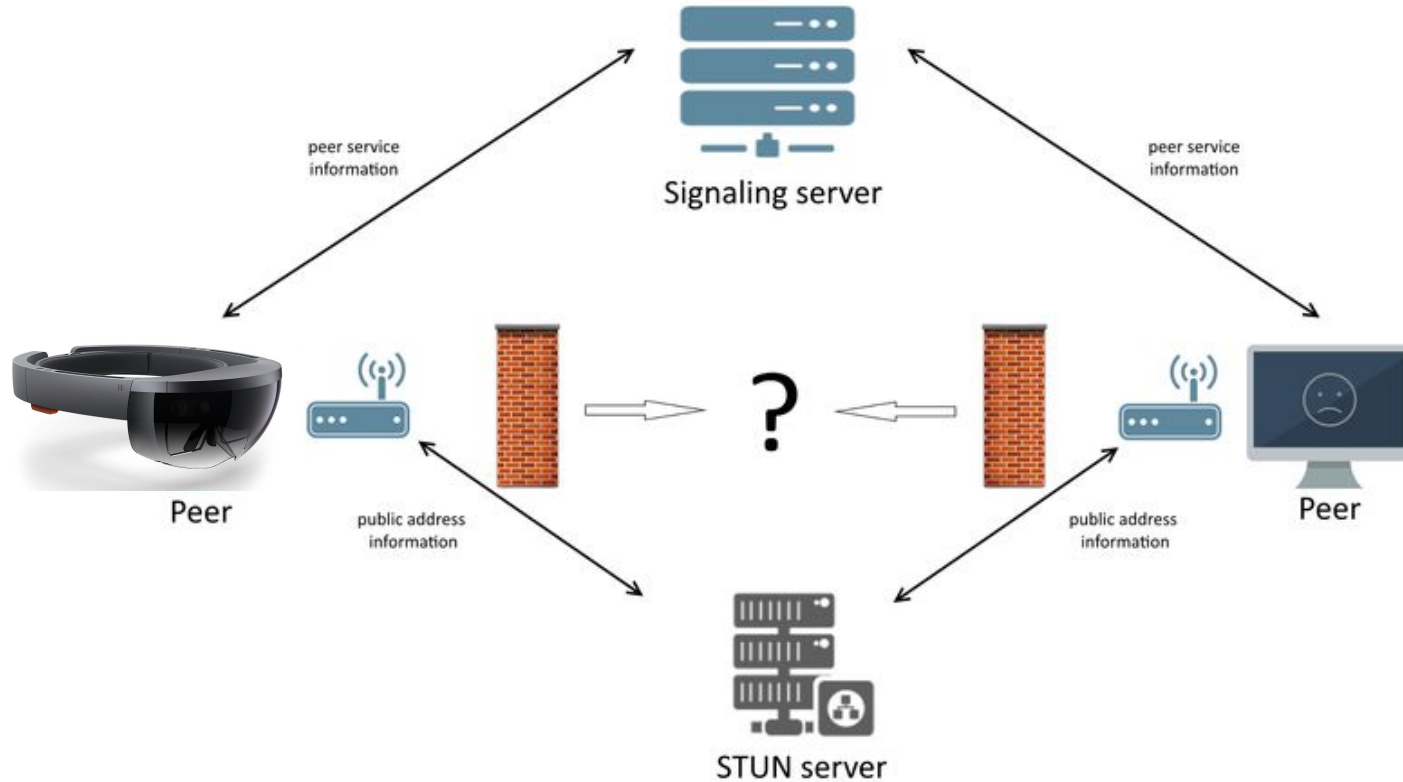
- Further integration with WebSocket technology
- HoloLens broadcasts video to Client
 - Using new technologies to broadcast directly from HoloLens server
- Drawing ability for client-side application
- Further integration of all components
 - Client, Server (Drawing), Server (Object Detection)



Next Steps - Render Streaming



Next Steps - Signalling Server



Thank you!
Questions?

