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Indexing and Mining Time Sequences

Christos Faloutsos and Lei Li
CMU

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Outline

- ➡ Motivation
- Similarity Search and Indexing
- DSP (Digital Signal Processing)
- Linear Forecasting
- Kalman filters
- fractals and multifractals
- Non-linear forecasting
- Conclusions

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Problem definition

- Given: one or more sequences
 $x_1, x_2, \dots, x_t, \dots$
 $(y_1, y_2, \dots, y_p, \dots)$
- Find
 - similar sequences; forecasts
 - patterns; clusters; outliers

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Motivation - Applications

- Financial, sales, economic series
- Medical
 - reactions to new drugs
 - elderly care

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ECG - physionet.org



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EEG - epilepsy



KDD 2010 from wikipedia 6

Motivation - Applications (cont'd)

- ‘Smart house’
 - sensors monitor temperature, humidity, air quality
- video surveillance

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Motivation - Applications (cont'd)

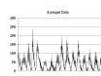
- civil/automobile infrastructure
 - bridge vibrations [Oppenheim+02]
 - road conditions / traffic monitoring



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Motivation - Applications (cont'd)

- Weather, environment/anti-pollution
 - volcano monitoring
 - air/water pollutant monitoring



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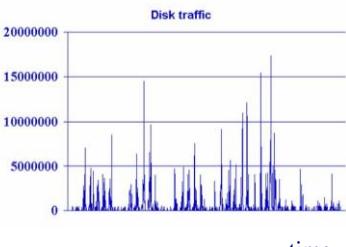
Motivation - Applications (cont'd)

- Computer systems
 - ‘Active Disks’ (buffering, prefetching)
 - web servers (ditto)
 - network traffic monitoring
 - ...

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Stream Data: Disk accesses

#bytes

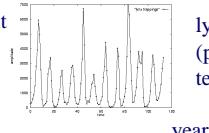


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Problem #1:

Goal: given a signal (eg., #packets over time)
 Find: patterns, periodicities, and/or compress

count



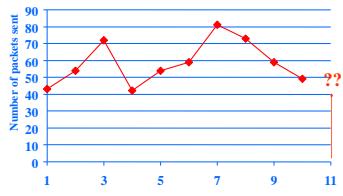
year

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Problem#2: Forecast

Given x_p, x_{t-1}, \dots , forecast x_{t+1}



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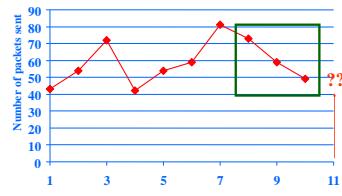
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Problem#2': Similarity search

Eg., Find a 3-tick pattern, similar to the last one



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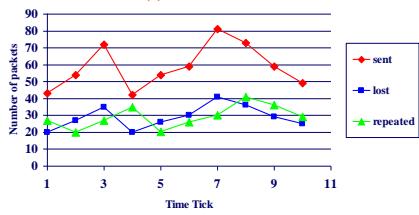
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Problem #3:

- Given: A set of **correlated** time sequences
- Forecast ‘**Sent(t)**’



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Important observations

Patterns, rules, forecasting and similarity indexing are closely related:

- To do forecasting, we need
 - to find patterns/rules
 - to find similar settings in the past
- to find outliers, we need to have forecasts
 - (outlier = too far away from our forecast)

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Important topics NOT in this tutorial:

- Continuous queries
 - [Babu+Widom] [Gehrke+] [Madden+]
- Categorical data streams
 - [Hatonen+96]
- Outlier detection (discontinuities)
 - [Breunig+00]

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- DSP
- Linear Forecasting
- Bursty traffic - fractals and multifractals
- Non-linear forecasting
- Conclusions

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Outline

- Motivation
- Similarity Search and Indexing
 - distance functions: Euclidean; Time-warping
 - indexing
 - feature extraction
- DSP
- ...

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Importance of distance functions

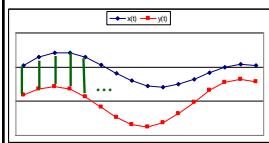
- Subtle, but **absolutely necessary**:
- A ‘must’ for similarity indexing (-> forecasting)
 - A ‘must’ for clustering
- Two major families
- Euclidean and L_p norms
 - Time warping and variations

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Euclidean and L_p



$$D(\vec{x}, \vec{y}) = \sum_{i=1}^n (x_i - y_i)^2$$

$$L_p(\vec{x}, \vec{y}) = \sum_{i=1}^n |x_i - y_i|^p$$

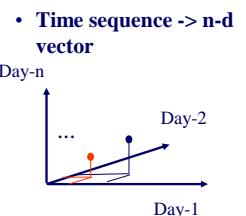
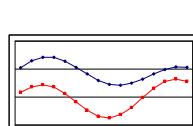
- L_1 : city-block = Manhattan
- L_2 = Euclidean
- L_∞

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Observation #1



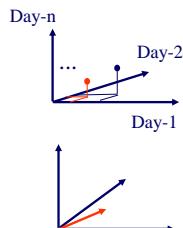
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Observation #2

- Euclidean distance is closely related to
- cosine similarity
 - dot product
 - ‘cross-correlation’ function



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Time Warping

- allow accelerations - decelerations – (with or w/o penalty)
- THEN compute the (Euclidean) distance (+ penalty)
- related to the string-editing distance

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Time Warping

'stutters':

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Time Warping

Q: how to compute it?

A: dynamic programming

$D(i, j)$ = cost to match prefix of length i of first sequence x with prefix of length j of second sequence y

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Time Warping

Thus, with no penalty for stutter, for sequences

$$x_1, x_2, \dots, x_i; \quad y_1, y_2, \dots, y_j$$

$$D(i, j) = \|x[i] - y[j]\| + \min \begin{cases} D(i-1, j-1) & \text{no stutter} \\ D(i, j-1) & \text{x-stutter} \\ D(i-1, j) & \text{y-stutter} \end{cases}$$

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Time Warping

- Time warping matrix & optimal path:

No stutters

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Time Warping

- Time warping matrix & optimal path:

All stutters
 $Y_1 \times N$ times;
 $X_N \times M$ times

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Time Warping - variations

- Time warping matrix & optimal path:

At most k stutters:
Sakoe-Chiba band

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Time Warping - variations

- Time warping matrix & optimal path:



The diagram illustrates the concept of a time warping matrix and an optimal path. On the left, there is a red wavy line labeled 'Y' at its bottom end. On the right, there is a blue wavy line labeled 'X' at its bottom end. Between them is a square frame containing a red parallelogram. The parallelogram represents the optimal path from point Y to point X, showing how points in sequence Y are mapped to points in sequence X over time.

At most x% stutters:
Itakura parallelogram

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Part2.1 #31



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Time warping

- Complexity: $O(M^*N)$ - quadratic on the length of the strings
- Many variations (penalty for stutters; limit on the number/percentage of stutters; ...)
- popular in voice processing
[Rabiner+Juang]
- Seems suitable for mo-cap



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A variation: Uniform axis scaling



- Stretch / shrink time axis of Y, up to p%, for free
- THEN compute Euclidean distance
- [Keogh+, VLDB04]

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Other Distance functions

- piece-wise linear/flat approx.; compare pieces [Keogh+01] [Faloutsos+97]
- ‘cepstrum’ (for voice [Rabiner+Juang])
 - do DFT; take log of amplitude; do DFT again!
- Allow for small gaps [Agrawal+95]

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More distance functions.

- Chen + Ng [vldb'04]: ERP ‘Edit distance with Real Penalty’: give a penalty to stutters
- Keogh+ [kdd'04]: VERY NICE, based on information theory: compress each sequence (quantize + Lempel-Ziv), using the **other** sequences’ LZ tables

*On The Marriage of L_p -norms and Edit Distance, Lei Chen,
Raymond T. Ng; VLDB'04*

*Towards Parameter-Free Data Mining, E. Keogh, S. Lonardi,
C.A. Ratanamahatana, KDD'04*

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Conclusions

Prevailing distances:

- Euclidean and
- time-warping

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Indexing

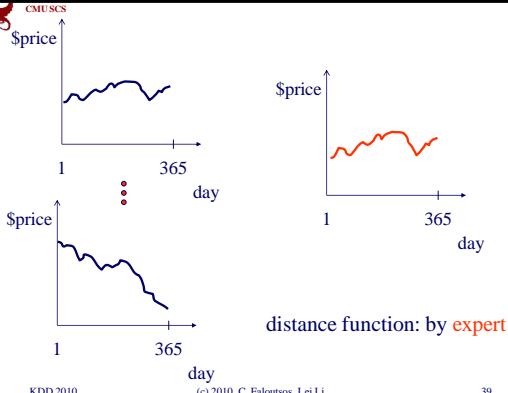
Problem:

- given a set of time sequences,
- find the ones similar to a desirable query sequence

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Idea: ‘GEMINI’

Eg., ‘find stocks similar to MSFT’

Seq. scanning: too slow

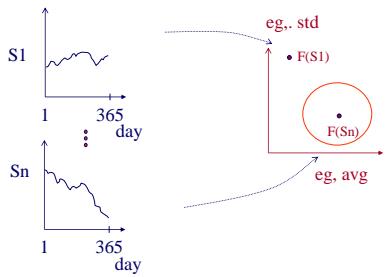
How to accelerate the search?

[Faloutsos96]

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‘GEMINI’ - Pictorially



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GEMINI

Solution: Quick-and-dirty' filter:

- extract n features (numbers, eg., avg., etc.)
- map into a point in n -d feature space
- organize points with off-the-shelf spatial access method ('SAM')
- discard false alarms

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Examples of GEMINI

- Time sequences: DFT (up to 100 times faster) [SIGMOD94];
- [Kanellakis+], [Mendelzon+]

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Examples of GEMINI

Even on other-than-sequence data:

- Images (QBIC) [JIIS94]
- tumor-like shapes [VLDB96]
- video [Informedia + S-R-trees]
- automobile part shapes [Kriegel+97]

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Indexing - SAMs

Q: How do Spatial Access Methods (SAMs) work?

A: they group nearby points (or regions) together, on nearby disk pages, and answer spatial queries quickly ('range queries', 'nearest neighbor' queries etc)

For example:

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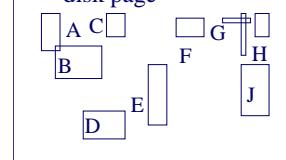
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R-trees

- [Guttman84] eg., w/ fanout 4: group nearby rectangles to parent MBRs; each group -> disk page



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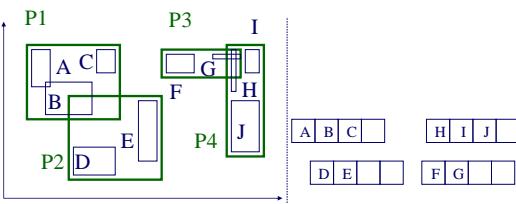
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R-trees



- eg., w/ fanout 4:



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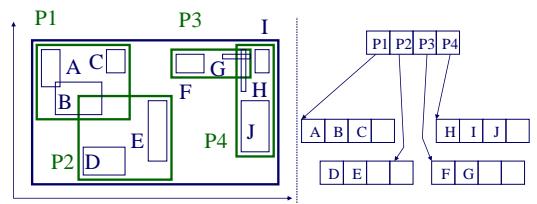
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R-trees

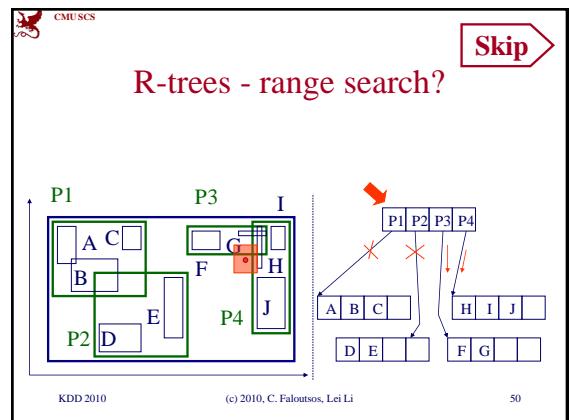
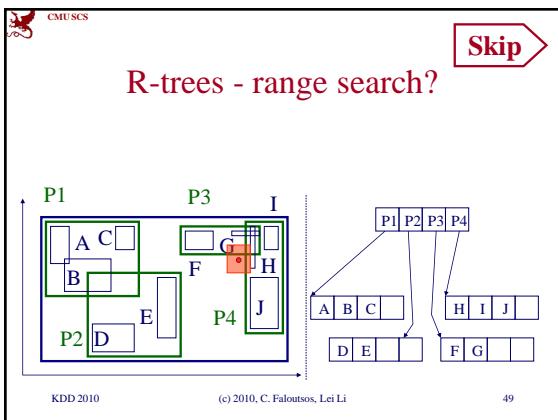
- eg., w/ fanout 4:



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Conclusions

- Fast indexing: through GEMINI
 - feature extraction and
 - (off the shelf) Spatial Access Methods [Gaede+98]

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 - SVD, etc (data dependent)
 - MDS, FastMap

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DFT and cousins

- very good for compressing real signals
- more details on DFT/DCT/DWT: later

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DFT and stocks

- Dow Jones Industrial index, 6/18/2001-12/21/2001

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DFT and stocks

- Dow Jones Industrial index, 6/18/2001-12/21/2001
- just 3 DFT coefficients give very good approximation

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SVD

- THE optimal method for dimensionality reduction
 - (under the Euclidean metric)

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Singular Value Decomposition (SVD)

- SVD (~LSI ~ KL ~ PCA ~ spectral analysis...)

LSI: S. Dumais; M. Berry
KL: eg, Duda+Hart
PCA: eg., Jolliffe
Details: [Press+], [Faloutsos96]

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SVD

- Extremely useful tool
 - (also behind PageRank/google and Kleinberg's algorithm for hubs and authorities)
- But may be slow: $O(N * M * M)$ if $N > M$
- any approximate, faster method?

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SVD shortcuts

- random projections (Johnson-Lindenstrauss thm [Papadimitriou+ pods98])

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Random projections

- pick ‘enough’ random directions (will be ~orthogonal, in high-d!!)
- distances are preserved probabilistically, within epsilon
- (also, use as a pre-processing step for SVD [Papadimitriou+ PODS98])

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 - SVD etc (data dependent), ICA
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→

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Citation

- AutoSplit: Fast and Scalable Discovery of Hidden Variables in Stream and Multimedia Databases*, Jia-Yu Pan, Hiroyuki Kitagawa, Christos Faloutsos and Masafumi Hamamoto

PAKDD 2004, Sydney, Australia

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Motivation:

(Q1) Find patterns in data

- Motion capture data (broad jumps)

Energy exerted

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PCA sometimes misses essential features

- Best SVD axis: not always meaningful!

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Motivation:
(Q1) Find patterns in data

- Human would say
 - Pattern 1: along diagonal
 - Pattern 2: along vertical axis
- How to find these automatically?

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Motivation:
(Q2) Find hidden variables

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Motivation:
(Q2) Find hidden variables

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Motivation:
(Q2) Find hidden variables

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Motivation:
(Q2) Find hidden variables

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Motivation:
Find hidden variables

- ICA: also known as ‘Blind Source Separation’
- ‘cocktail party problem’
 - in a party, we can hear two concurrent conversations,
 - but separate them (and tune-in on one of them only)
- http://www.cnl.salk.edu/~tewon/Blind/blind_audio.html
- (in stocks: one ‘discussion’ is the general economy trend; the other ‘discussion’ is the tech-stock boom

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Problem formulation

- Given n data items, each has m attributes
- Find the m hidden variables and the m bases

$$\begin{bmatrix} X_{11}, X_{12}, \dots, X_{1m} \\ \vdots \\ X_{n1}, X_{n2}, \dots, X_{nm} \end{bmatrix} = \begin{bmatrix} H_{11}, H_{12}, \dots, H_{1m} \\ \vdots \\ H_{n1}, H_{n2}, \dots, H_{nm} \end{bmatrix} \begin{bmatrix} B_{11}, B_{12}, \dots, B_{1m} \\ \vdots \\ B_{m1}, B_{m2}, \dots, B_{mm} \end{bmatrix}$$

$X = HB$

Samples of the m -th hidden variable

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Formulation: (Q1) Find patterns in data

$$\begin{bmatrix} X_{11}, X_{12}, \dots, X_{1m} \\ \vdots \\ X_{n1}, X_{n2}, \dots, X_{nm} \end{bmatrix} = \begin{bmatrix} H_{11}, H_{12}, \dots, H_{1m} \\ \vdots \\ H_{n1}, H_{n2}, \dots, H_{nm} \end{bmatrix} \begin{bmatrix} B_{11}, B_{12}, \dots, B_{1m} \\ \vdots \\ B_{m1}, B_{m2}, \dots, B_{mm} \end{bmatrix}$$

Basis 1

Left Knee Right Knee

Flight Phase

Autosplit Bases PCA Bases

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Q1: Find patterns

- Patterns found

Take-off Landing

60:1

$m=2, n=550$

1:1

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Q1: Find patterns

- Patterns found
 - Landing: both knees

Take-off Landing

60:1

$m=2, n=550$

1:1

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Q1: Find patterns

- Patterns found
 - Landing: both knees
 - Take-off: right knee
 - Right-handed actor

Take-off Landing

60:1

$m=2, n=550$

1:1

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Q2: Find hidden variables (DJIA stocks)

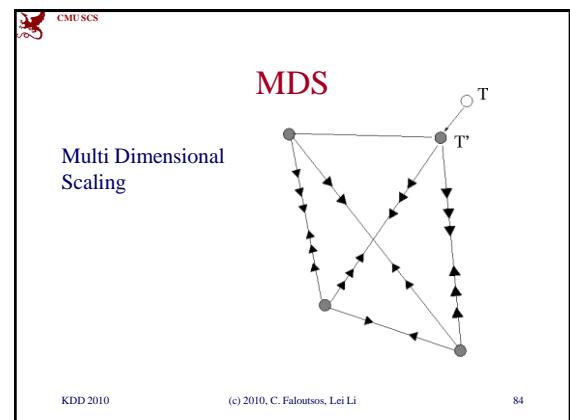
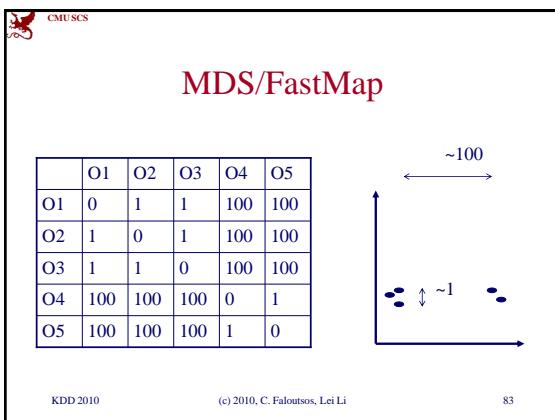
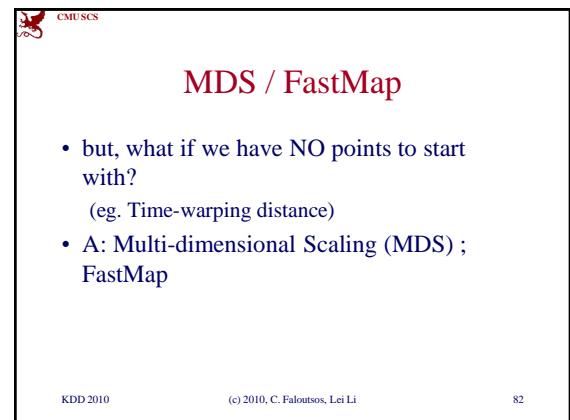
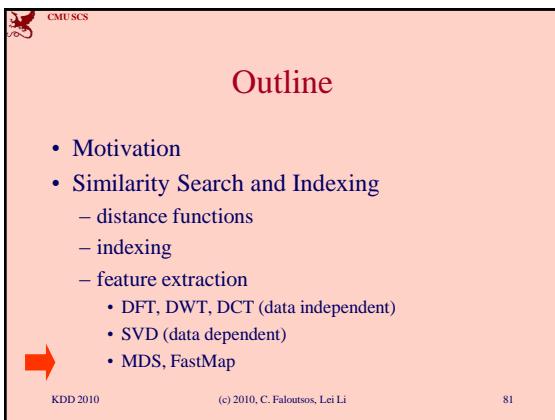
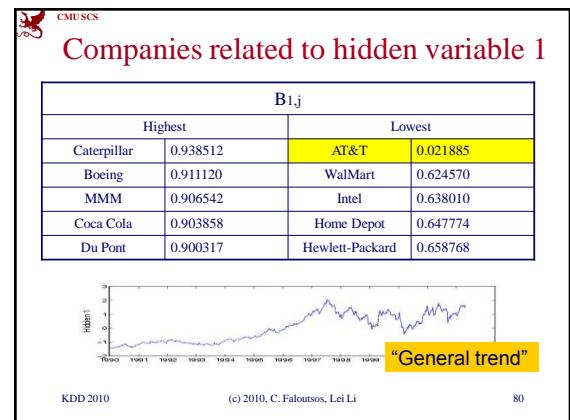
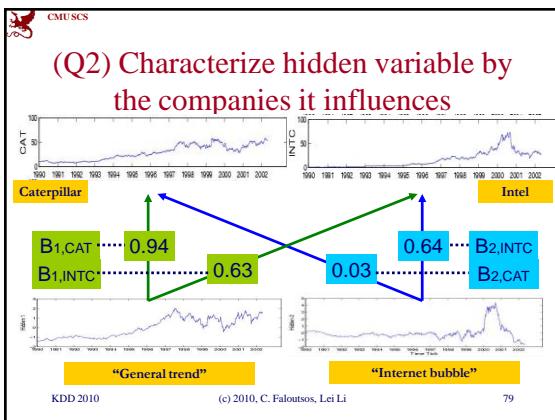
- Weekly DJIA closing prices
 - 01/02/1990-08/05/2002, $n=660$ data points
 - A data point: prices of 29 companies at the time

Alcoa
American Express
Boeing
Caterpillar
Citi Group

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FastMap

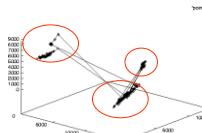
- Multi-dimensional scaling (MDS) can do that, but in $O(N^{**2})$ time
- FastMap [Faloutsos+95] takes $O(N)$ time

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FastMap: Application

VideoTrails [Kobla+97]




scene-cut detection (about 10% errors)

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 - SVD (data dependent)
 - MDS, FastMap, **IsoMap** etc



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Variations

- Isomap [Tenenbaum, de Silva, Langford, 2000]
- LLE (Local Linear Embedding) [Roweis, Saul, 2000]
- MVE (Minimum Volume Embedding) [Shaw & Jebara, 2007]



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Variations

- Isomap [Tenenbaum, de Silva, Langford, 2000]
- LLE (Local Linear Embedding) [Roweis, Saul, 2000]
- MVE (Minimum Volume Embedding) [Shaw & Jebara, 2007]



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Conclusions - Practitioner's guide

Similarity search in time sequences

- 1) establish/choose distance (Euclidean, time-warping,...)
- 2) extract features (SVD, DWT, MDS), and use an SAM (R-tree/variant) or a Metric Tree (M-tree)
- 2') for high intrinsic dimensionalities, consider sequential scan (it might win...)

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Books

- William H. Press, Saul A. Teukolsky, William T. Vetterling and Brian P. Flannery: *Numerical Recipes in C*, Cambridge University Press, 1992, 2nd Edition. (Great description, intuition and code for SVD)
- C. Faloutsos: *Searching Multimedia Databases by Content*, Kluwer Academic Press, 1996 (introduction to SVD, and GEMINI)

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- Rabiner, L. and B.-H. Juang (1993). Fundamentals of Speech Recognition, Prentice Hall.

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Part 2: DSP (Digital Signal Processing)

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CMU SCS

Outline

- Motivation
- Similarity Search and Indexing
- DSP (DFT, DWT)**
- Linear Forecasting
- Kalman filters
- Bursty traffic - fractals and multifractals
- Non-linear forecasting
- Conclusions

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CMU SCS

Outline

- DFT**
 - Definition of DFT and properties
 - how to read the DFT spectrum
- DWT**
 - Definition of DWT and properties
 - how to read the DWT scalogram

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CMU SCS

Introduction - Problem#1

Goal: given a signal (eg., packets over time)
Find: patterns and/or compress

count

lynx caught per year
(packets per day;
automobiles per hour)

year

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What does DFT do?

A: highlights the periodicities

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DFT: definition

• For a sequence x_0, x_1, \dots, x_{n-1}

• the (**n-point**) Discrete Fourier Transform is

• X_0, X_1, \dots, X_{n-1} :

$$X_f = 1/\sqrt{n} \sum_{t=0}^{n-1} x_t * \exp(-j2\pi tf/n) \quad f = 0, \dots, n-1$$

$$(j = \sqrt{-1})$$

$$x_t = 1/\sqrt{n} \sum_{f=0}^{n-1} X_f * \exp(+j2\pi tf/n)$$

inverse DFT

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DFT: definition

• **Good news:** Available in **all** symbolic math packages, eg., in ‘mathematica’

```
x = [1,2,1,2];
X = Fourier[x];
Plot[ Abs[X] ];
```

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DFT: Amplitude spectrum

Amplitude: $A_f^2 = \text{Re}^2(X_f) + \text{Im}^2(X_f)$

count

year

Ampl.

freq=0 freq=12

Freq.

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DFT: examples

flat

Amplitude

time freq

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DFT: examples

Skip

Low frequency sinusoid

time freq

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DFT: examples

Skip

- Sinusoid - symmetry property: $X_f = X_{n-f}^*$

time freq

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DFT: examples

• Higher freq. sinusoid

time freq

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DFT: examples

examples

=

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DFT: examples

examples

Ampl. Freq.

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Outline

- Motivation
- Similarity Search and Indexing
- DSP
- Linear Forecasting
- Bursty traffic - fractals and multifractals
- Non-linear forecasting
- Conclusions

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Outline

- Motivation
- Similarity Search and Indexing
- DSP
 - DFT
 - Definition of DFT and properties
 - how to read the DFT spectrum
 - DWT

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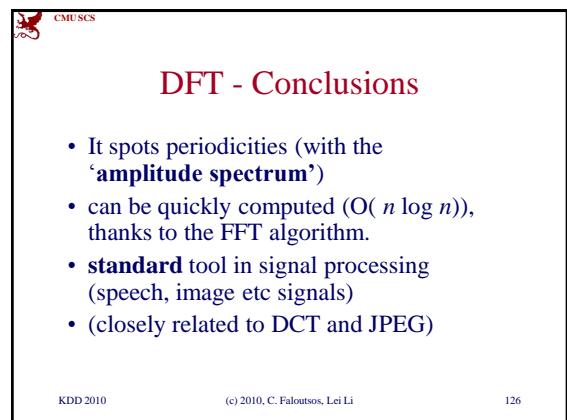
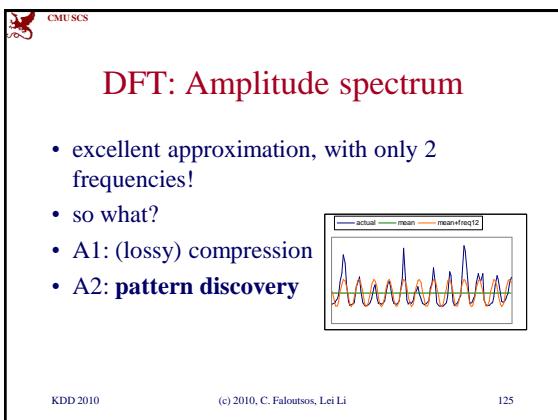
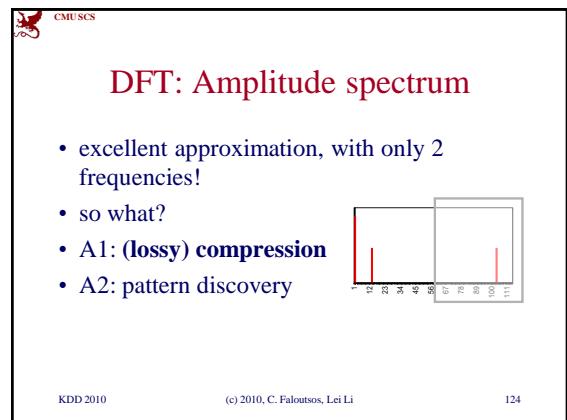
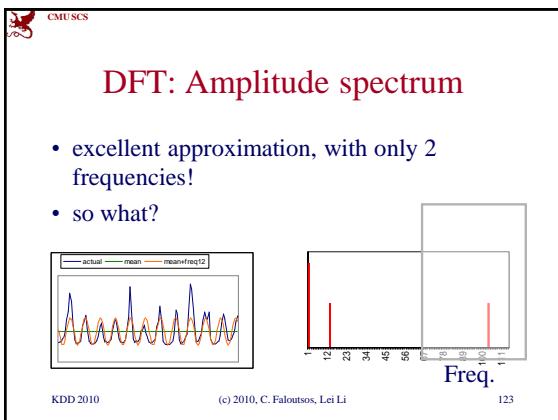
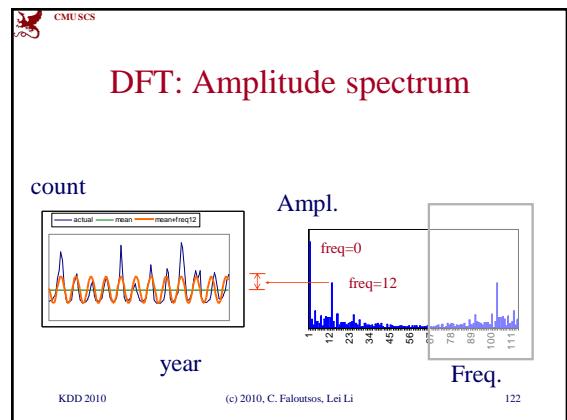
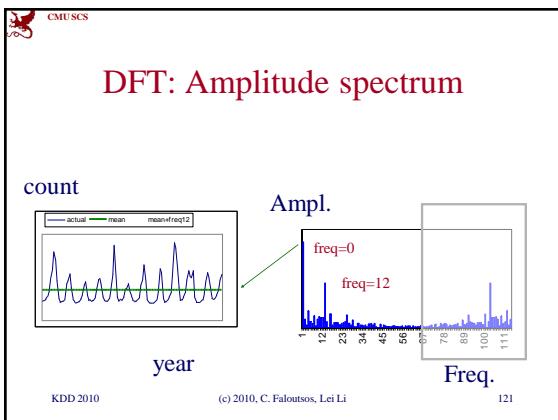
DFT: Amplitude spectrum

Amplitude: $A_f^2 = \text{Re}^2(X_f) + \text{Im}^2(X_f)$

count

year

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Outline

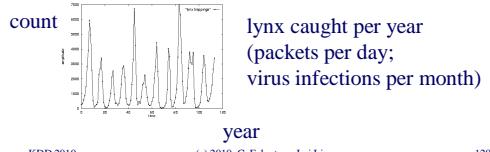
- Motivation
- Similarity Search and Indexing
- DSP
 - DFT
 - DWT
- Definition of DWT and properties
 - how to read the DWT scalogram

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Problem #1:

Goal: given a signal (eg., #packets over time)
 Find: patterns, periodicities, and/or compress



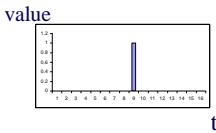
count year
 lynx caught per year
 (packets per day;
 virus infections per month)

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 CMU SCS

Wavelets - DWT

- DFT is great - but, how about compressing a spike?

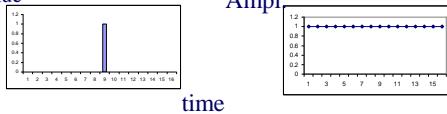


value time
 KDD 2010 (c) 2010, C. Faloutsos, Lei Li 129

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Wavelets - DWT

- DFT is great - but, how about compressing a spike?
- A: Terrible - all DFT coefficients needed!



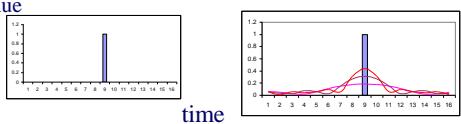
value time Ampl.
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Freq₁₃₀

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Wavelets - DWT

- DFT is great - but, how about compressing a spike?
- A: Terrible - all DFT coefficients needed!

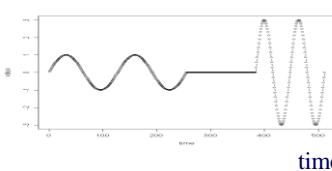


value time
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Wavelets - DWT

- Similarly, DFT suffers on short-duration waves (eg., baritone, silence, soprano)



value time
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Wavelets - DWT

- Solution#1: Short window Fourier transform (SWFT)
- But: how short should be the window?

freq ↑
time →

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Wavelets - DWT

- Answer: **multiple** window sizes! \rightarrow DWT

Time domain	DFT	SWFT	DWT
freq ↑	Vertical bars	Horizontal bars	Vertical and horizontal bars
time →			

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Haar Wavelets

- subtract sum of left half from right half
- repeat recursively for quarters, eighths, ...

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Wavelets - construction

Skip

x0 x1 x2 x3 x4 x5 x6 x7

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Wavelets - construction

Skip

level 1 d1,0 s1,0 d1,1 s1,1
 $x_0 \ x_1 \ x_2 \ x_3 \ x_4 \ x_5 \ x_6 \ x_7$

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Wavelets - construction

Skip

level 2 d2,0 s2,0
d1,0 s1,0 d1,1 s1,1
 $x_0 \ x_1 \ x_2 \ x_3 \ x_4 \ x_5 \ x_6 \ x_7$

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Wavelets - construction

Skip

etc ...

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Wavelets - construction

Skip

Q: map each coefficient on the time-freq. plane

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Wavelets - construction

Skip

Q: map each coefficient on the time-freq. plane

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Haar wavelets - code

```
#!/usr/bin/perlS
# expects a file with numbers
# and prints the dwt transform
# The number of time-ticks should be a power of 2
# USAGE:
# haarr.pl <filename>

my $len = scalar(@vals);
my $shift = int($len/2);
while($shift >= 1) {
    for my $i(0..$shift-1) {
        my $smooth = ($vals[2*$i] + $vals[2*$i+1]) / sqrt(2);
        my $diff = ($vals[2*$i] - $vals[2*$i+1]) / sqrt(2);
        print "i\t", $shift, "\t";
        print "$smooth\t$diff\n";
        $smooth = ($vals[2*$i] + $vals[2*$i+1]) / sqrt(2);
    }
    print "\n";
    @vals = @smooth;
    $shift = int($shift/2);
}
print "i\t", $shift, "\t";
@vals = @smooth;
$shift = int($shift/2);
}
print "\n";
```

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Wavelets - construction

Observation1:

- '+' can be some weighted addition
- '-' is the corresponding weighted difference ('Quadrature mirror filters')

Observation2: unlike DFT/DCT,

there are *many* wavelet bases: Haar, Daubechies-4, Daubechies-6, Coifman, Morlet, Gabor, ...

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Wavelets - how do they look like?

- E.g., Daubechies-4

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Wavelets - how do they look like?

- E.g., Daubechies-4

?

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Wavelets - how do they look like?

- E.g., Daubechies-4

?

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Outline

- Motivation
- Similarity Search and Indexing
- DSP
 - DFT
 - DWT
- Definition of DWT and properties
- how to read the DWT scalogram

→

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Wavelets - Drill#1:

- Q: baritone/silence/soprano - DWT?

f t
value time

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Wavelets - Drill#1:

- Q: baritone/silence/soprano - DWT?

f t
value time

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Wavelets - Drill#2:

- Q: spike - DWT?

f t
value time

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Wavelets - Drill#2:

- Q: spike - DWT?

0.00	0.00	0.71	0.00
0.00	0.50	-0.35	0.35

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Wavelets - Drill#3:

- Q: weekly + daily periodicity, + spike - DWT?

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Wavelets - Drill#3:

- Q: **weekly** + daily periodicity, + spike - DWT?

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Wavelets - Drill#3:

- Q: weekly + **daily** periodicity, + spike - DWT?

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Wavelets - Drill#3:

- Q: weekly + daily periodicity, + **spike** - DWT?

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Wavelets - Drill#3:

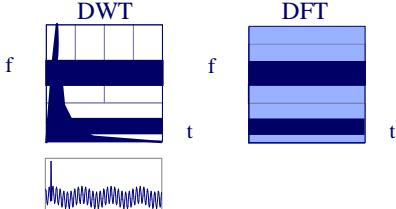
- Q: weekly + daily periodicity, + spike - DWT?

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Wavelets - Drill#3:

- Q: DFT?



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Advantages of Wavelets

- Better compression (better RMSE with same number of coefficients - used in JPEG-2000)
- fast to compute (usually: $O(n)!$)
- very good for ‘spikes’
- mammalian eye and ear: Gabor wavelets

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Overall Conclusions

- DFT, DCT spot periodicities
- DWT** : multi-resolution - matches processing of mammalian ear/eye better
- All three: powerful tools for **compression, pattern detection** in real signals
- All three: included in math packages
 - (matlab, ‘R’, mathematica, ... - often in spreadsheets!)

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Overall Conclusions

- DWT : very suitable for self-similar traffic
- DWT: used for summarization of streams [Gilbert+01], db histograms etc

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Resources - software and urls

- http://www.dsptutor.freeuk.com/jسانالایسر/_FFT Spectrum Analyser.html : Nice java applets for FFT
- <http://www.relisoft.com/freeware/freq.html> voice frequency analyzer (needs microphone)

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Resources: software and urls

- xwpl*: open source wavelet package from Yale, with excellent GUI
- <http://monet.me.ic.ac.uk/people/gavin/java/waveletDemos.html> : wavelets and scalograms

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Books

- William H. Press, Saul A. Teukolsky, William T. Vetterling and Brian P. Flannery: *Numerical Recipes in C*, Cambridge University Press, 1992, 2nd Edition. (Great description, intuition and code for DFT, DWT)
- C. Faloutsos: *Searching Multimedia Databases by Content*, Kluwer Academic Press, 1996 (introduction to DFT, DWT)

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Additional Reading

- [Gilbert+01] Anna C. Gilbert, Yannis Kotidis and S. Muthukrishnan and Martin Strauss, *Surfing Wavelets on Streams: One-Pass Summaries for Approximate Aggregate Queries*, VLDB 2001

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Part 3: Linear Forecasting

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Outline

- Motivation
- Similarity Search and Indexing
- DSP
- Linear Forecasting
 - Kalman filters
 - Bursty traffic - fractals and multifractals
 - Non-linear forecasting
 - Conclusions

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Forecasting

"Prediction is very difficult, especially about the future." - Nils Bohr
<http://www.hfac.uh.edu/MediaFutures/thoughts.html>

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Outline

- Motivation
- ...
- Linear Forecasting
 - Auto-regression: Least Squares; RLS
 - Co-evolving time sequences
 - Examples
 - Conclusions

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Problem#2: Forecast

- Example: give x_{t-1}, x_{t-2}, \dots , forecast x_t

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Forecasting: Preprocessing

MANUALLY:

- remove trends
- spot periodicities

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Problem#2: Forecast

- Solution: try to express x_t as a linear function of the past: x_{t-2}, x_{t-3}, \dots , (up to a window of w)

Formally:

$$x_t \approx a_1 x_{t-1} + \dots + a_w x_{t-w} + \text{noise}$$

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(Problem: Back-cast; interpolate)

- Solution - interpolate: try to express x_t as a linear function of the past AND the future: $x_{t+1}, x_{t+2}, \dots, x_{t+w\text{future}}; x_{t-1}, \dots, x_{t-w\text{past}}$ (up to windows of $w_{\text{past}}, w_{\text{future}}$)
- EXACTLY the same algo's

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Linear Regression: idea

patient	weight	height
1	27	43
2	43	54
3	54	72
...	...	
N	25	??

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Linear Auto Regression:

Time	packets Sent(t)
1	43
2	54
3	72
...	...
N	??

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Linear Auto Regression:

Time	Packets Sent (t-1)	Packets Sent(t)
1	-	43
2	43	54
3	54	72
...
N	(25)	??

• lag $w=1$
 • Dependent variable = # of packets sent ($S[t]$)
 • Independent variable = # of packets sent ($S[t-1]$)

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Outline

- Motivation
- ...
- Linear Forecasting
 - Auto-regression: Least Squares; RLS
 - Co-evolving time sequences
 - Examples
 - Conclusions

→

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More details:

- Q1: Can it work with window $w>1$?
- A1: YES!

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More details:

- Q1: Can it work with window $w>1$?
- A1: YES! (we'll fit a hyper-plane, then!)

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More details:

- Q1: Can it work with window $w>1$?
- A1: YES! (we'll fit a hyper-plane, then!)

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Skip

More details:

- Q1: Can it work with window $w>1$?
- A1: YES! The problem becomes:

$$\mathbf{X}_{[N \times w]} \times \mathbf{a}_{[w \times 1]} = \mathbf{y}_{[N \times 1]}$$
- OVER-CONSTRAINED
 - \mathbf{a} is the vector of the regression coefficients
 - \mathbf{X} has the N values of the w indep. variables
 - \mathbf{y} has the N values of the dependent variable

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Skip

More details:

- $\mathbf{X}_{[N \times w]} \times \mathbf{a}_{[w \times 1]} = \mathbf{y}_{[N \times 1]}$

Ind-var1 Ind-var-w

time

$$\begin{bmatrix} X_{11}, X_{12}, \dots, X_{1w} \\ X_{21}, X_{22}, \dots, X_{2w} \\ \vdots \\ \vdots \\ X_{N1}, X_{N2}, \dots, X_{Nw} \end{bmatrix} \times \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_w \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix}$$

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Skip

More details:

- $\mathbf{X}_{[N \times w]} \times \mathbf{a}_{[w \times 1]} = \mathbf{y}_{[N \times 1]}$

Ind-var1 Ind-var-w

time

$$\begin{bmatrix} X_{11}, X_{12}, \dots, X_{1w} \\ X_{21}, X_{22}, \dots, X_{2w} \\ \vdots \\ \vdots \\ X_{N1}, X_{N2}, \dots, X_{Nw} \end{bmatrix} \times \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_w \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix}$$

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More details

- Q2: How to estimate $a_1, a_2, \dots, a_w = \mathbf{a}^*$?
- A2: with Least Squares fit

$$\boxed{\mathbf{a} = (\mathbf{X}^T \times \mathbf{X})^{-1} \times (\mathbf{X}^T \times \mathbf{y})}$$

- (Moore-Penrose pseudo-inverse)
- \mathbf{a} is the vector that minimizes the RMSE from \mathbf{y}

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Even more details

- Q3: Can we estimate \mathbf{a} incrementally?
- A3: Yes, with the brilliant, classic method of ‘Recursive Least Squares’ (RLS) (see, e.g., [Yi+00], for details) - pictorially:

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Even more details

- Given:

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Even more details

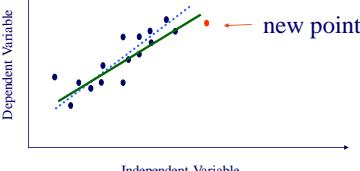
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Skip

Even more details

RLS: quickly compute new best fit



Dependent Variable
Independent Variable

Skip

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Skip

Even more details

- **Straightforward Least Squares**
 - Needs huge matrix (**growing** in size) $O(N \times w)$
 - Costly matrix operation $O(N \times w^2)$
- **Recursive LS**
 - Need much smaller, fixed size matrix $O(w \times w)$
 - Fast, incremental computation $O(1 \times w^2)$

$N = 10^6, w = 1-100$

Skip

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Skip

Even more details

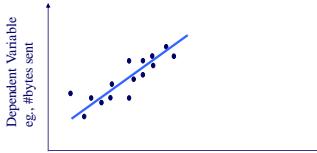
- Q4: can we ‘forget’ the older samples?
- A4: Yes - RLS can easily handle that [Yi+00]:

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Adaptability - ‘forgetting’



Dependent Variable eg., #bytes sent
Independent Variable eg., #packets sent

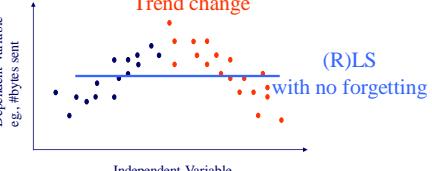
Skip

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Skip

Adaptability - ‘forgetting’



Dependent Variable eg., #bytes sent
Independent Variable eg., #packets sent

Skip

Trend change
(R)LS with no forgetting

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Skip

Adaptability - ‘forgetting’



Dependent Variable
Independent Variable

Skip

Trend change
(R)LS with no forgetting
(R)LS with forgetting

- RLS: can *trivially* handle ‘forgetting’

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How to choose ‘w’?

- goal: capture arbitrary periodicities
- with NO human intervention
- on a semi-infinite stream

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Answer:

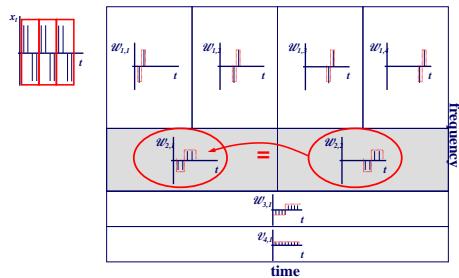
- ‘AWSOM’ (Arbitrary Window Stream fOrecasting Method) [Papadimitriou+, vldb2003]
- idea: do AR on each wavelet level
- in detail:

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AWSOM

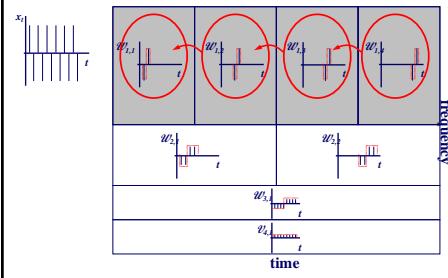


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AWSOM

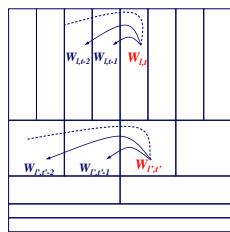


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AWSOM - idea



$$w_{l,t} = \beta_{l,1}w_{l,t,1} + \beta_{l,2}w_{l,t,2} + \dots$$

$$w_{l,t'} = \beta_{l,t'}w_{l,t',1} + \beta_{l,t'}w_{l,t',2} + \dots$$

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More details...

- Update of wavelet coefficients (incremental)
- Update of linear models (incremental; RLS)
- Feature selection (single-pass)
 - Not all correlations are significant
 - Throw away the insignificant ones (“noise”)

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Results - Synthetic data

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- Triangle pulse
- Mix (sine + square)
- AR captures wrong trend (or none)
- Seasonal AR estimation fails

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Results - Real data

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- Automobile traffic
 - Daily periodicity
 - Bursty “noise” at smaller scales
- AR fails to capture any trend
- Seasonal AR estimation fails

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Results - real data

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- Sunspot intensity
 - Slightly time-varying “period”
- AR captures wrong trend
- Seasonal ARIMA
 - wrong downward trend, despite help by human!

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Complexity

Skip

- Model update
 - Space: $O(\lg N + mk^2) \approx O(\lg N)$
 - Time: $O(k^2) \approx O(1)$
- Where
 - N : number of points (so far)
 - k : number of regression coefficients; fixed
 - m : number of linear models; $O(\lg N)$

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Outline

- Motivation
- ...
- Linear Forecasting
 - Auto-regression: Least Squares; RLS
 - Co-evolving time sequences
 - Examples
 - Conclusions

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Co-Evolving Time Sequences

- Given: A set of **correlated** time sequences
- Forecast ‘**Repeated(t)**’

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Solution:

Q: what should we do?

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Solution:

Least Squares, with

- Dep. Variable: Repeated(t)
- Indep. Variables: Sent(t-1) ... Sent(t-w); Lost(t-1) ... Lost(t-w); Repeated(t-1), ...
- (named: 'MUSCLES' [Yi+00])

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Time Series Analysis - Outline

- Auto-regression
- Least Squares; recursive least squares
- Co-evolving time sequences
- Examples
- ➡ • Conclusions

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Conclusions - Practitioner's guide

- AR(IMA) methodology: prevailing method for linear forecasting
- Brilliant method of Recursive Least Squares for fast, incremental estimation.
- See [Box-Jenkins]
- very recently: AWSOM (no human intervention)

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Resources: software and urls

- MUSCLES: Prof. Byoung-Kee Yi:
<http://www.postech.ac.kr/~bkyi/>
or christos@cs.cmu.edu
- free-ware: 'R' for stat. analysis
(clone of Splus)
<http://cran.r-project.org/>

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Books

- George E.P. Box and Gwilym M. Jenkins and Gregory C. Reinsel, *Time Series Analysis: Forecasting and Control*, Prentice Hall, 1994 (the classic book on ARIMA, 3rd ed.)
- Brockwell, P. J. and R. A. Davis (1987). Time Series: Theory and Methods. New York, Springer Verlag.

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Additional Reading

- [Papadimitriou+ vldb2003] Spiros Papadimitriou, Anthony Brockwell and Christos Faloutsos *Adaptive, Hands-Off Stream Mining* VLDB 2003, Berlin, Germany, Sept. 2003
- [Yi+00] Byoung-Kee Yi et al.: *Online Data Mining for Co-Evolving Time Sequences*, ICDE 2000. (Describes MUSCLES and Recursive Least Squares)

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BREAK!

Next: Kalman filters

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Part 5: Bursty traffic and multifractals

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Outline

- Motivation
- Similarity Search and Indexing
- DSP
- Linear Forecasting
- Kalman filters
- ➡ Bursty traffic - fractals and multifractals
- Non-linear forecasting
- Conclusions

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Outline

- Motivation
- ...
- Linear Forecasting
- Bursty traffic - fractals and multifractals
 - ➡ Problem
 - Main idea (80/20, Hurst exponent)
 - Results

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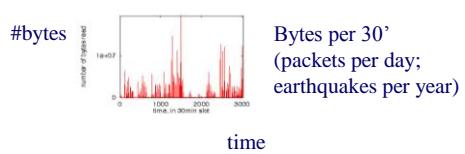
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Recall: Problem #1:

Goal: given a signal (eg., #bytes over time)
 Find: patterns, periodicities, and/or compress



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Problem #1

- model bursty traffic
- generate realistic traces
- (Poisson does not work)

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Motivation

- predict queue length distributions (e.g., to give probabilistic guarantees)
- “learn” traffic, for buffering, prefetching, ‘active disks’, web servers

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Q: any ‘pattern’?

- Not Poisson
- spike; silence; more spikes; more silence...
- any rules?

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solution: self-similarity

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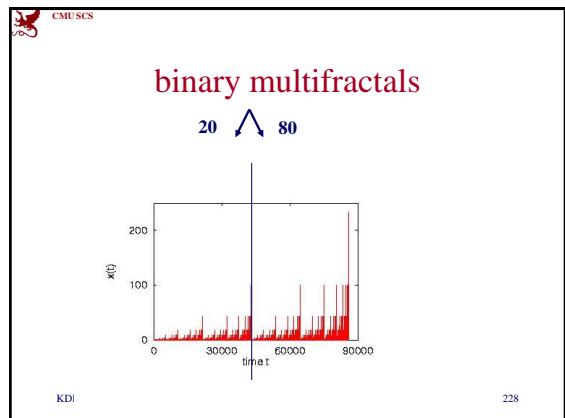
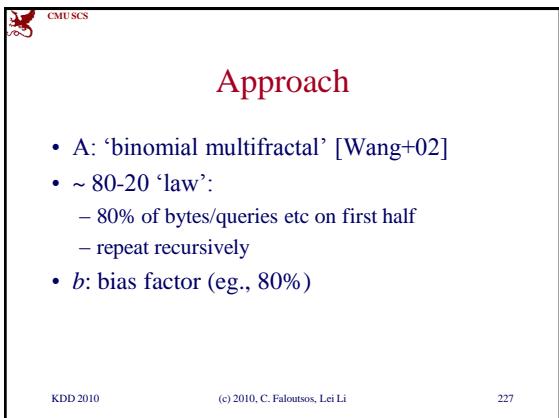
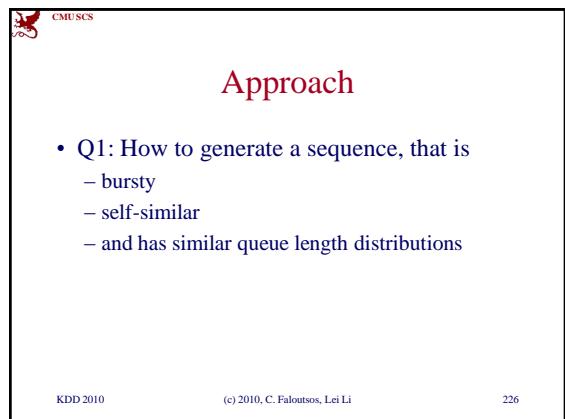
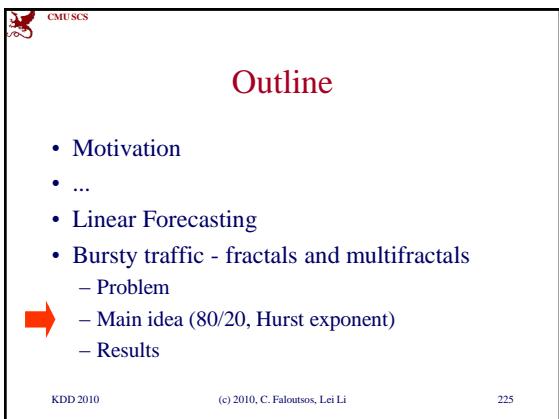
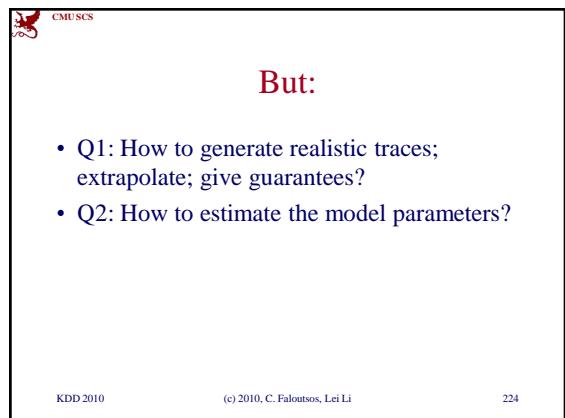
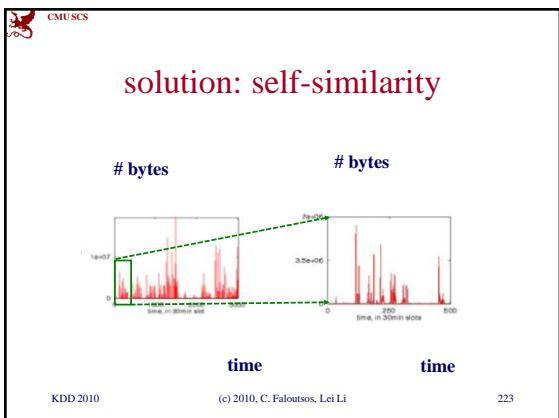
solution: self-similarity

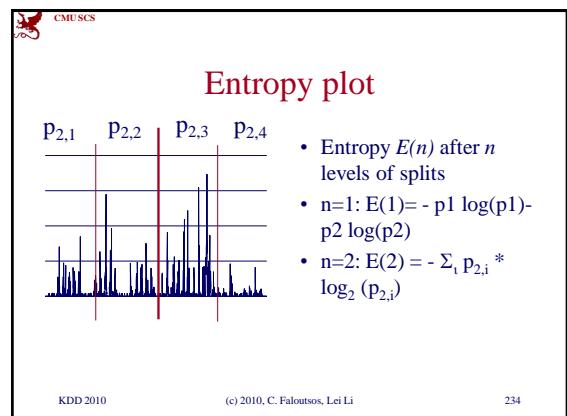
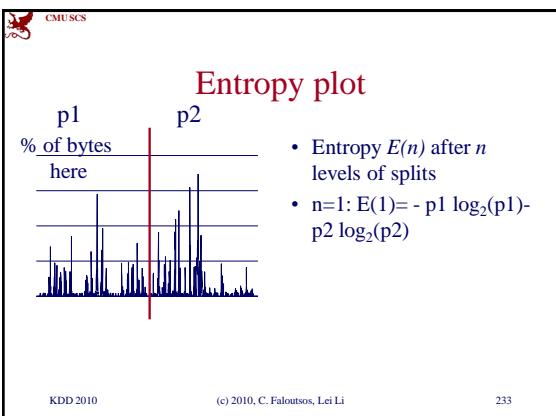
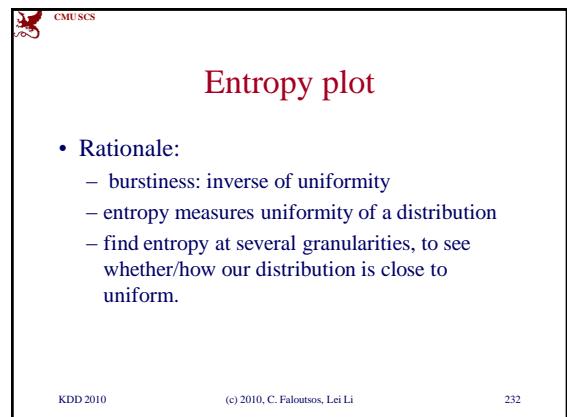
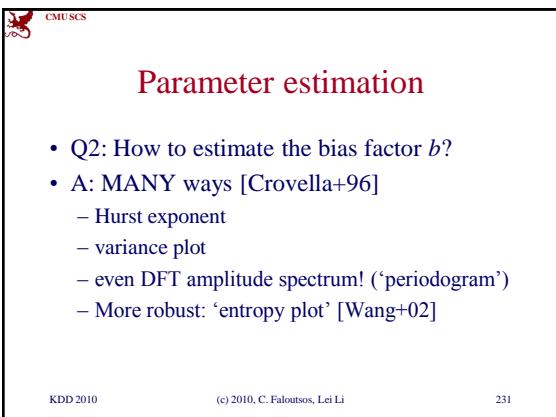
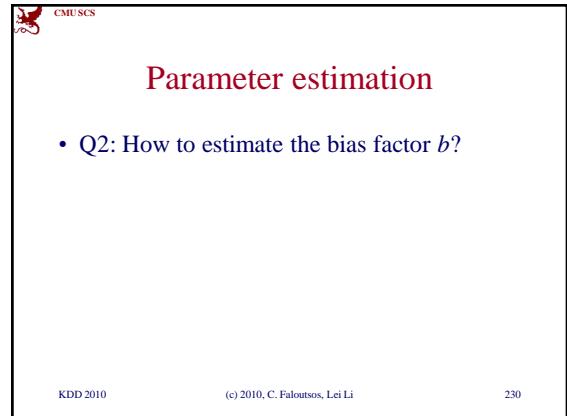
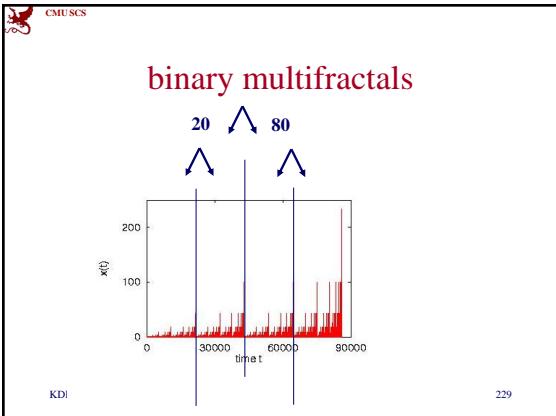
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solution: self-similarity

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Real traffic

- Has linear entropy plot (-> self-similar)

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Skip

Observation - intuition:

- intuition: slope = intrinsic dimensionality = info-bits per coordinate-bit
 - unif. Dataset: slope = 1
 - multi-point: slope = 0

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Skip

Entropy plot - Intuition

- Slope ~ intrinsic dimensionality (in fact, ‘Information fractal dimension’)
- = info bit per coordinate bit - eg

Dim = 1 —•••••••—
Pick a point;
reveal its coordinate bit-by-bit -
how much info is each bit worth to me?

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Entropy plot

- Slope ~ intrinsic dimensionality (in fact, ‘Information fractal dimension’)
- = info bit per coordinate bit - eg

Dim = 1 —•••••••—
↑ Is MSB 0?
‘info’ value = $E(1)$: 1 bit

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Entropy plot

- Slope ~ intrinsic dimensionality (in fact, ‘Information fractal dimension’)
- = info bit per coordinate bit - eg

Dim = 1 —•••••••—
↑ Is MSB 0?
↑ Is next MSB = 0?

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Entropy plot

- Slope ~ intrinsic dimensionality (in fact, ‘Information fractal dimension’)
- = info bit per coordinate bit - eg

Dim = 1 —•••••••—
Info value = 1 bit
 $= E(2) - E(1) =$
slope!
↑ Is MSB 0?
↑ Is next MSB = 0?

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Entropy plot

Skip

- Repeat, for all points at same position:

Dim=0 

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Entropy plot

Skip

- Repeat, for all points at same position:
- we need 0 bits of info, to determine position
- > slope = 0 = intrinsic dimensionality

Dim=0 

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Entropy plot

Skip

- Real (and 80-20) datasets can be in-between: bursts, gaps, smaller bursts, smaller gaps, at every scale

Dim = 1 

Dim=0 

0<Dim<1 

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(Fractals)

- What set of points could have behavior between point and line?

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Cantor dust

- Eliminate the middle third
- Recursively!

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Cantor dust

Dimensionality?
(no length; infinite # points!)
Answer: $\log_2 / \log_3 = 0.6$

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Some more entropy plots:

- Poisson vs real

Poisson: slope = ~1 \rightarrow uniformly distributed

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B-model

$E(n)$

- b-model traffic gives perfectly linear plot
- Lemma: its slope is $slope = -b \log_2 b - (1-b) \log_2 (1-b)$
- Fitting: do entropy plot; get slope; solve for b

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Outline

- Motivation
- ...
- Linear Forecasting
- Bursty traffic - fractals and multifractals
 - Problem
 - Main idea (80/20, Hurst exponent)
 - Experiments - Results

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Experimental setup

- Disk traces (from HP [Wilkes 93])
- web traces from LBL
[http://repository.cs.vt.edu/
lbl-conn-7.tar.Z](http://repository.cs.vt.edu/lbl-conn-7.tar.Z)

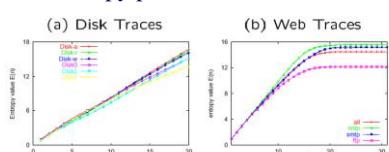
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Model validation

- Linear entropy plots

(a) Disk Traces (b) Web Traces



Bias factors b : 0.6-0.8
smallest b / smoothest: nntp traffic

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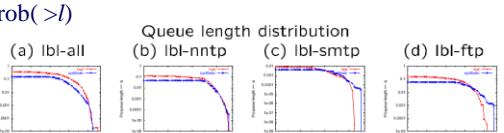
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Web traffic - results

- LBL, NCDF of queue lengths (log-log scales)

Prob($>l$) Queue length distribution

(a) lbl-all (b) lbl-nntp (c) lbl-smtp (d) lbl-ftp



How to give guarantees? (queue length l)

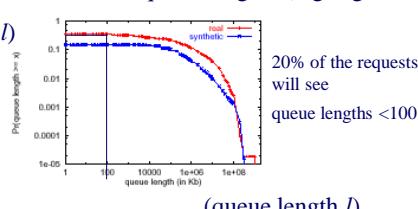
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Web traffic - results

- LBL, NCDF of queue lengths (log-log scales)

Prob($>l$)



20% of the requests will see queue lengths <100

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Conclusions

- Multifractals (80/20, ‘b-model’, Multiplicative Wavelet Model (MWM)) for analysis and synthesis of bursty traffic
- can give (probabilistic) guarantees

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Recall: Problem #1

Given a time series $\{x_t\}$, predict its future course, that is, x_{t+1}, x_{t+2}, \dots

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How to forecast?

- ARIMA - but: linearity assumption
- ANSWER: ‘Delayed Coordinate Embedding’ = Lag Plots [Sauer92]

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General Intuition (Lag Plot)

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Questions:

- Q1: How to choose lag L ?
- Q2: How to choose k (the # of NN)?
- Q3: How to interpolate?
- Q4: why should this work at all?

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Q1: Choosing lag L

- Manually (16, in award winning system by [Sauer94])

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Q2: Choosing number of neighbors k

- Manually (typically ~ 1-10)

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Q3: How to interpolate?

How do we interpolate between the k nearest neighbors?

A3.1: Average

A3.2: Weighted average (weights drop with distance - how?)

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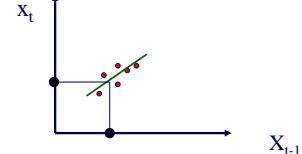
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Q3: How to interpolate?

A3.3: Using SVD - seems to perform best ([Sauer94] - first place in the Santa Fe forecasting competition)



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Q4: Any theory behind it?

A4: YES!

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Theoretical foundation

- Based on the “Takens’ Theorem” [Takens81]
- which says that long enough delay vectors can do prediction, even if there are unobserved variables in the dynamical system (= diff. equations)

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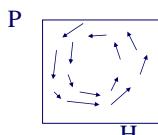
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Theoretical foundation

Example: Lotka-Volterra equations

$$\begin{aligned} dH/dt &= r H - a H^*P \\ dP/dt &= b H^*P - m P \end{aligned}$$



H is count of prey (e.g., hare)

P is count of predators (e.g., lynx)

Suppose only P(t) is observed ($t=1, 2, \dots$).

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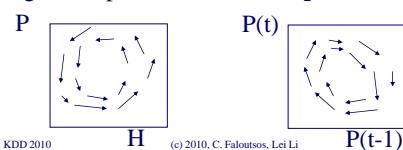
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Theoretical foundation

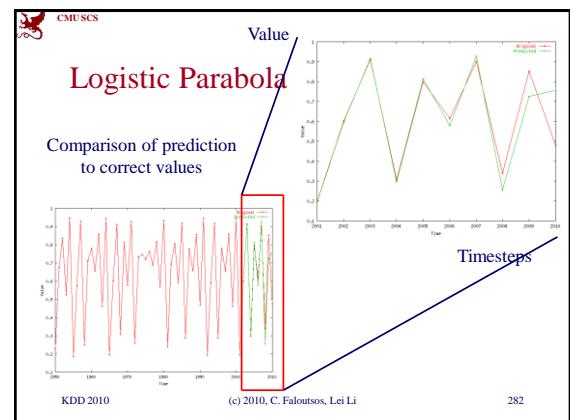
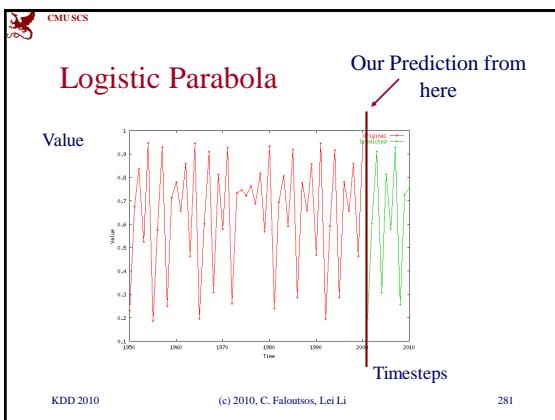
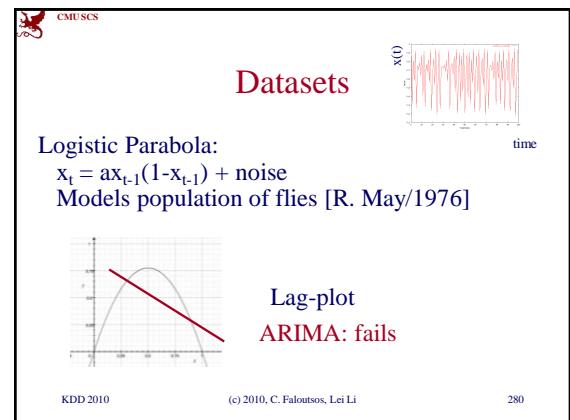
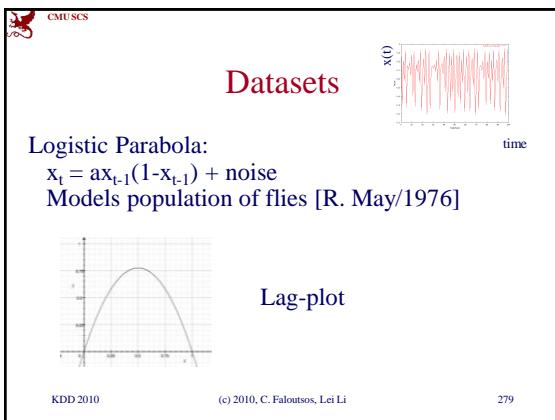
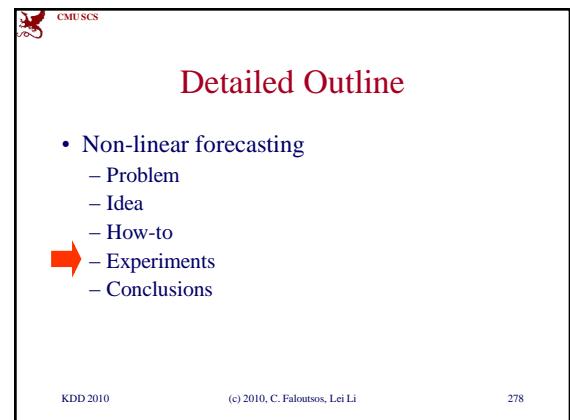
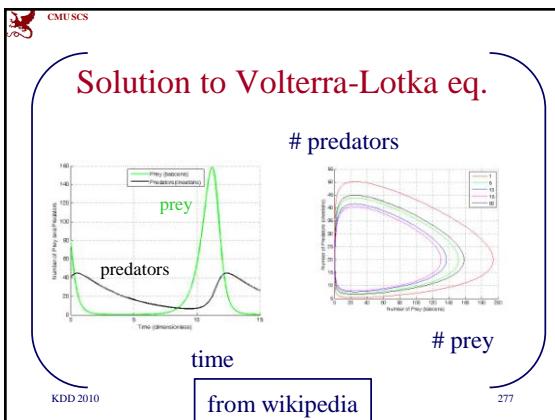
- But the delay vector space is a faithful reconstruction of the internal system state
- So prediction in **delay vector space** is as good as prediction in **state space**



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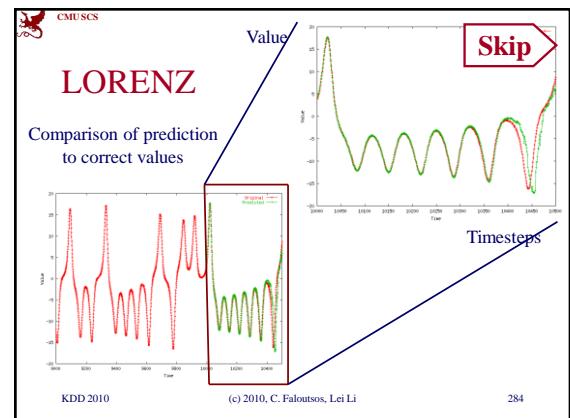
Datasets

Skip

LORENZ: Models convection currents in the air
 $dx / dt = a(y - x)$
 $dy / dt = x(b - z) - y$
 $dz / dt = xy - cz$



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Datasets

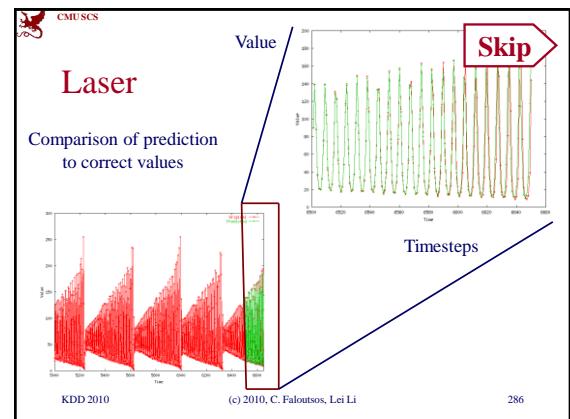
Skip

- LASER: fluctuations in a Laser over time (used in Santa Fe competition)



Value Time

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Conclusions

- Lag plots for non-linear forecasting (Takens' theorem)
- suitable for ‘chaotic’ signals

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 - Sauer, T. (1994). *Time series prediction using delay coordinate embedding*. (in book by Weigend and Gershenfeld, below) Addison-Wesley.
 - Takens, F. (1981). *Detecting strange attractors in fluid turbulence*. Dynamical Systems and Turbulence. Berlin: Springer-Verlag.
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References

- Weigend, A. S. and N. A. Gerschenfeld (1994). *Time Series Prediction: Forecasting the Future and Understanding the Past*, Addison Wesley. (Excellent collection of papers on chaotic/non-linear forecasting, describing the algorithms behind the winners of the Santa Fe competition.)

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Overall conclusions

- Similarity search: **Euclidean/time-warping; feature extraction and SAMs**

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Overall conclusions

- Similarity search: **Euclidean/time-warping; feature extraction and SAMs**
- Signal processing: **DWT** is a powerful tool

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Overall conclusions

- Similarity search: **Euclidean/time-warping; feature extraction and SAMs**
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- Linear Forecasting: **AR** (Box-Jenkins)

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Overall conclusions

- Similarity search: **Euclidean/time-warping; feature extraction and SAMs**
- Signal processing: **DWT** is a powerful tool
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- Kalman** filters & extensions: forecasting, pattern discovery, segmentation

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Overall conclusions

- Similarity search: **Euclidean/time-warping; feature extraction and SAMs**
- Signal processing: **DWT** is a powerful tool
- Linear Forecasting: **AR** (Box-Jenkins)
- Kalman** filters & extensions: forecasting, pattern discovery, segmentation
- Bursty traffic: **multifractals** (80-20 ‘law’)

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Overall conclusions

- Similarity search: **Euclidean**/time-warping; **feature extraction** and SAMs
- Signal processing: **DWT** is a powerful tool
- Linear Forecasting: **AR** (Box-Jenkins)
- **Kalman** filters & extensions: forecasting, pattern discovery, segmentation
- Bursty traffic: **multifractals** (80-20 ‘law’)
- Non-linear forecasting: **lag-plots** (Takens)

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THANK YOU!



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