

## Iterative binary searching

```
int bsearch(Type key, Type a[], int n) {
    int low = 0, high = n-1, middle;
    while (low <= high) {
        middle = (low + high) / 2;
        if (key == a[middle])
            return middle; /* success */
        if (key > a[middle]) low = middle + 1;
        else high = middle - 1;
    }
    return -1; /* unsuccessful */
}
```

- Both versions take  $\log_2 n$  steps on average to find a value or find out the value is not in the array

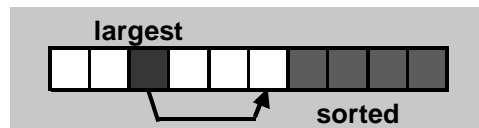
## Towers of Hanoi and 8 Queens

- Move  $n$  disks from  $a$  to  $c$ ; use  $b$  to hold [\(demo\)](#)  
`void tower(int n, int a, int b, int c)`
    - Base case: just one disk – trivial  
`if (n==1) moveOneDisk(a->c);`
    - General case: *assume* a method that can move a tower of height  $n-1$ . This method!!!  
`else {`
      - `tower(size n-1, a->b with c holding);`
      - `moveOneDisk(a->c);`
      - `tower(size n-1, b->c with a holding);`
- One more example – [8 queens problem](#)

## Sorting

- Probably *the* most expensive common operation
  - And maybe the most studied CS problem
- Problem: arrange  $a[0..n-1]$  by some ordering
  - e.g., in ascending order:  $a[i-1] \leq a[i]$ ,  $0 < i < n$
- Two general types of strategies
  - Comparison-based sorting – includes most strategies
    - Lots of simple, inefficient algorithms
    - Some not-so-simple, but more efficient algorithms
  - Address calculation sorting – rarely used in practice
    - But very fast if the data are suitable

## Selection sort

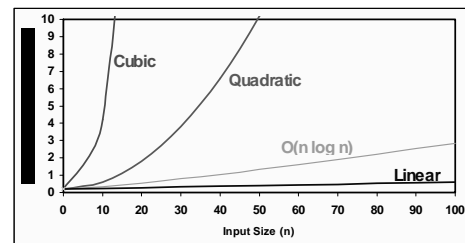


- Idea: build sorted sequence at end of array
- At each step:
  - Find largest value in not-yet-sorted portion
  - Exchange this value with the one at end of unsorted portion (now beginning of sorted portion)
- Easy to do (see text p. 629), but complexity is  $O(n^2)$ 
  - Huh?

## Big-Oh notation

- A way to compare algorithms – *just* algorithms
- All but the “dominant” term are ignored
  - e.g., say algorithm takes  $3n^2 + 15n + 100$  steps (problem of size  $n$ ) – 1<sup>st</sup> term dominates for large  $n$
- Constants are due to processor speed, compiler, language features, ... – so ignore the 3
- Means this example algorithm is  $O(n^2)$ 
  - Pronounced “Oh of  $n$ -squared” – a.k.a., it is in the “quadratic complexity” class of algorithms

## Some complexity classes



- Linear -  $O(n)$ ; Quadratic -  $O(n^2)$ ; Cubic -  $O(n^3)$ 
  - Also slower than cubic – e.g., Exponential -  $O(2^n)$
  - And faster than linear –  $O(\log n)$ , and Constant -  $O(1)$

## mergeSort

- A “divide and conquer” sorting strategy
  - Idea: (1) divide array in two; (2) sort each part; (3) combine two parts to overall solution
- mergeSort – has a naturally recursive solution

```
if (more than one item in array):
    divide array into left half and right half;
    mergeSort(left half); mergeSort(right half);
    merge(left half and right half together);
```

  - Requires helper method to merge two halves
    - Actually where all the work is done (p. 640)
- Complexity is  $O(n \log n)$ 
  - i.e., *lots faster* than selectionSort

## How much faster is *lots faster*?

- Use a stopwatch to get some idea
  - See `SelectionSortTimer`
  - Of course – actual times depend on ...
  - But `MergeSortTimer` is clearly much faster
- Moral: sometimes it pays to apply a better algorithm – despite the extra effort.

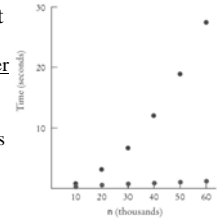


Figure 2  
Merge Sort Timing (blue) versus Selection Sort (red)