

Iterative binary searching

```
int bsearch(Type key, Type a[], int n) {
    int low = 0, high = n-1, middle;
    while (low <= high) {
        middle = (low + high) / 2;
        if (key == a[middle])
            return middle; /* success */
        if (key > a[middle]) low = middle + 1;
        else high = middle - 1;
    }
    return -1; /* unsuccessful */
}
```

- Both versions take $\log_2 n$ steps on average to find a value or find out the value is not in the array

Towers of Hanoi and 8 Queens

- Move n disks from a to c ; use b to hold (demo)

```
void tower(int n, int a, int b, int c)
```

- Base case: just one disk – trivial

```
    if (n==1) moveOneDisk(a→c);
```

- General case: *assume* a method that can move a tower of height $n-1$. This method!!!

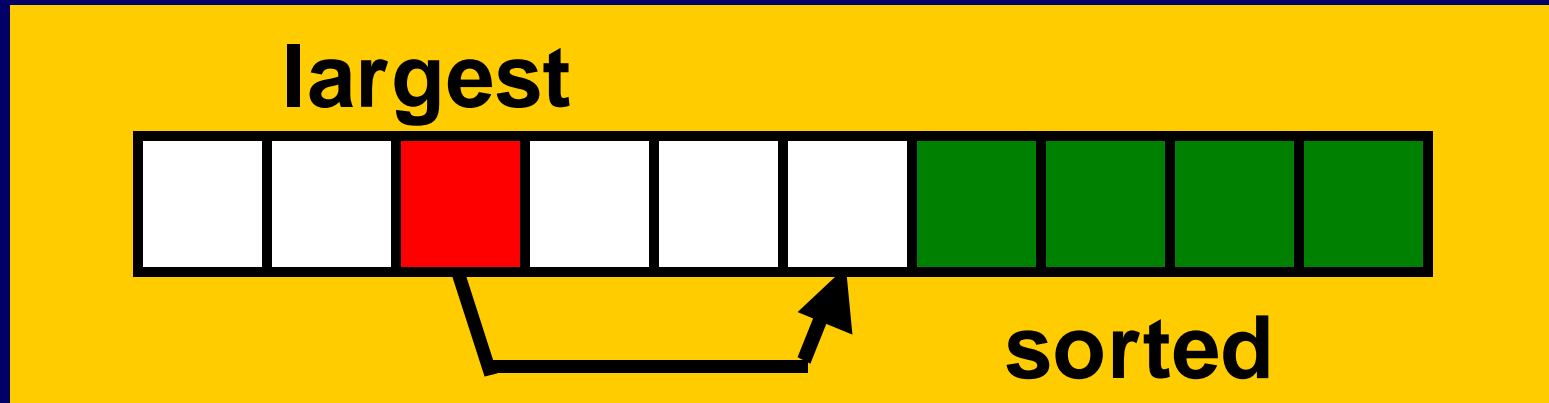
```
    else {
        tower(size n-1, a→b with c holding);
        moveOneDisk(a→c);
        tower(size n-1, b→c with a holding);
    }
```

- One more example – 8 queens problem

Sorting

- Probably *the* most expensive common operation
 - And maybe the most studied CS problem
- Problem: **arrange** $a[0..n-1]$ by some ordering
 - e.g., in ascending order: $a[i-1] \leq a[i]$, $0 < i < n$
- Two general types of strategies
 - Comparison-based sorting – includes most strategies
 - Lots of simple, inefficient algorithms
 - Some not-so-simple, but more efficient algorithms
 - Address calculation sorting – rarely used in practice
 - But very fast if the data are suitable

Selection sort

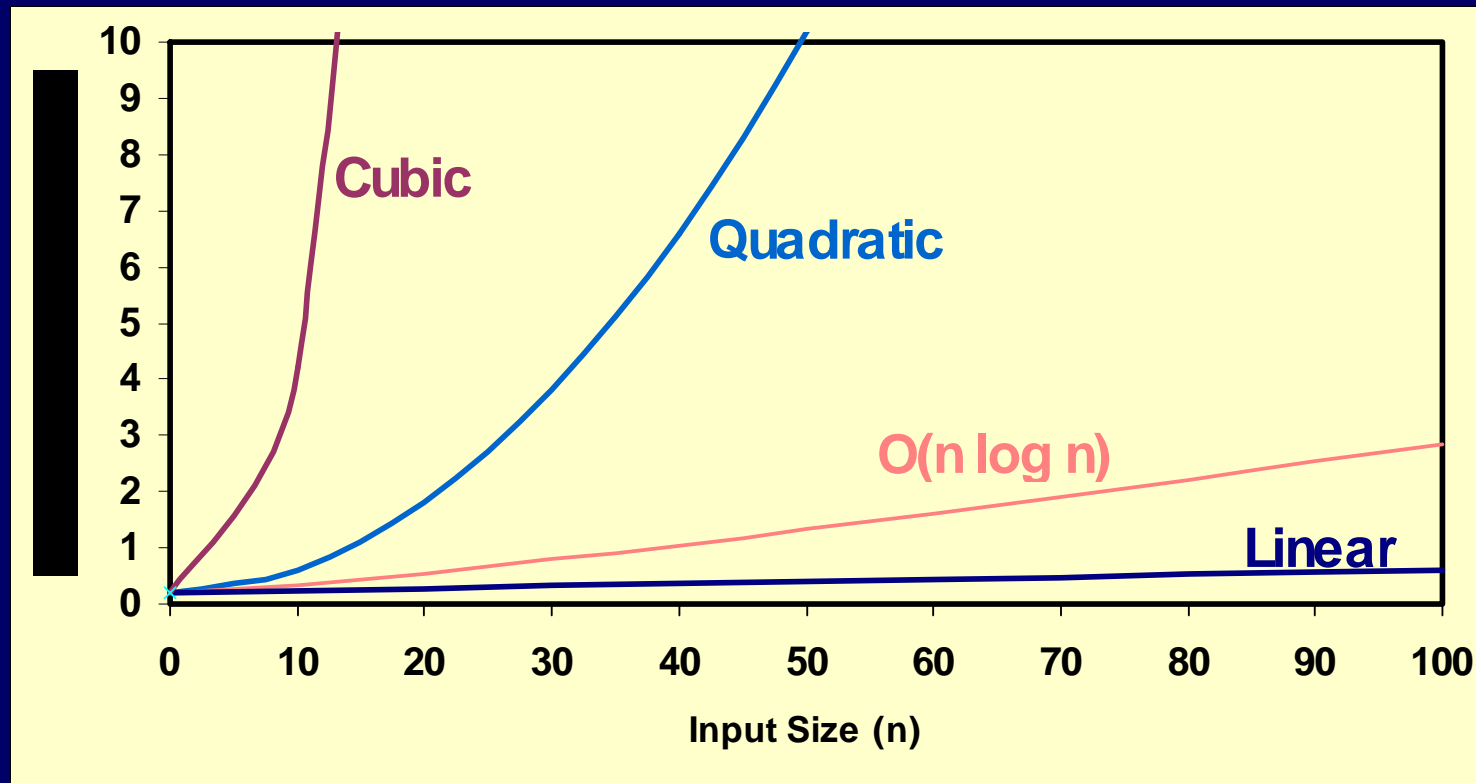


- Idea: build sorted sequence at end of array
- At each step:
 - *Find largest* value in not-yet-sorted portion
 - *Exchange* this value with the one at end of unsorted portion (now beginning of sorted portion)
- Easy to do (see text [p. 629](#)), but complexity is $O(n^2)$
 - Huh?

Big-Oh notation

- A way to compare algorithms – *just* algorithms
- All but the “dominant” term are ignored
 - e.g., say algorithm takes $3n^2 + 15n + 100$ steps (problem of size n) – 1st term dominates for large n
- Constants are due to processor speed, compiler, language features, ... – so ignore the 3
- Means this example algorithm is $O(n^2)$
 - Pronounced “Oh of n-squared” – a.k.a., it is in the “quadratic complexity” class of algorithms

Some complexity classes



- Linear - $O(n)$; Quadratic - $O(n^2)$; Cubic - $O(n^3)$
 - Also slower than cubic – e.g., Exponential - $O(2^n)$
 - And faster than linear – $O(\log n)$, and Constant - $O(1)$

mergeSort

- A “divide and conquer” sorting strategy
 - Idea: (1) divide array in two; (2) sort each part; (3) combine two parts to overall solution
- **mergeSort** – has a naturally recursive solution
 - if (more than one item in array):
 - divide array into left half and right half;
 - mergeSort(left half); mergeSort(right half);
 - merge(left half and right half together);
 - Requires helper method to merge two halves
 - Actually where all the work is done ([p. 640](#))
- Complexity is $O(n \log n)$
 - i.e., *lots faster* than selectionSort

How much faster is *lots faster*?

- Use a stopwatch to get some idea
 - See [SelectionSortTimer](#)
 - Of course – actual times depend on ...
 - But [MergeSortTimer](#) is clearly much faster
- Moral: sometimes it pays to apply a better algorithm – despite the extra effort.

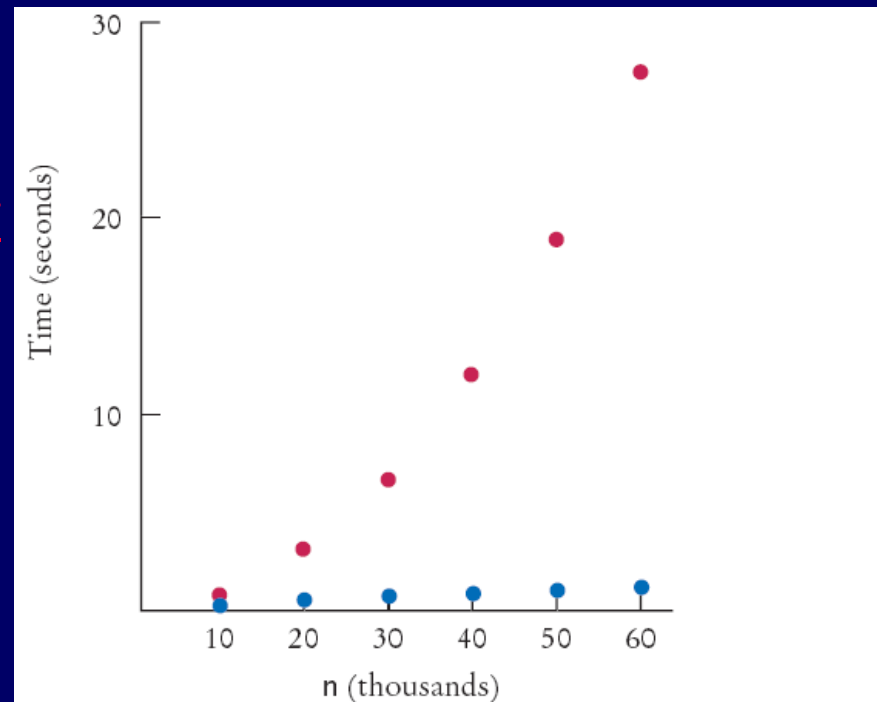


Figure 2

Merge Sort Timing (blue) versus Selection Sort (red)