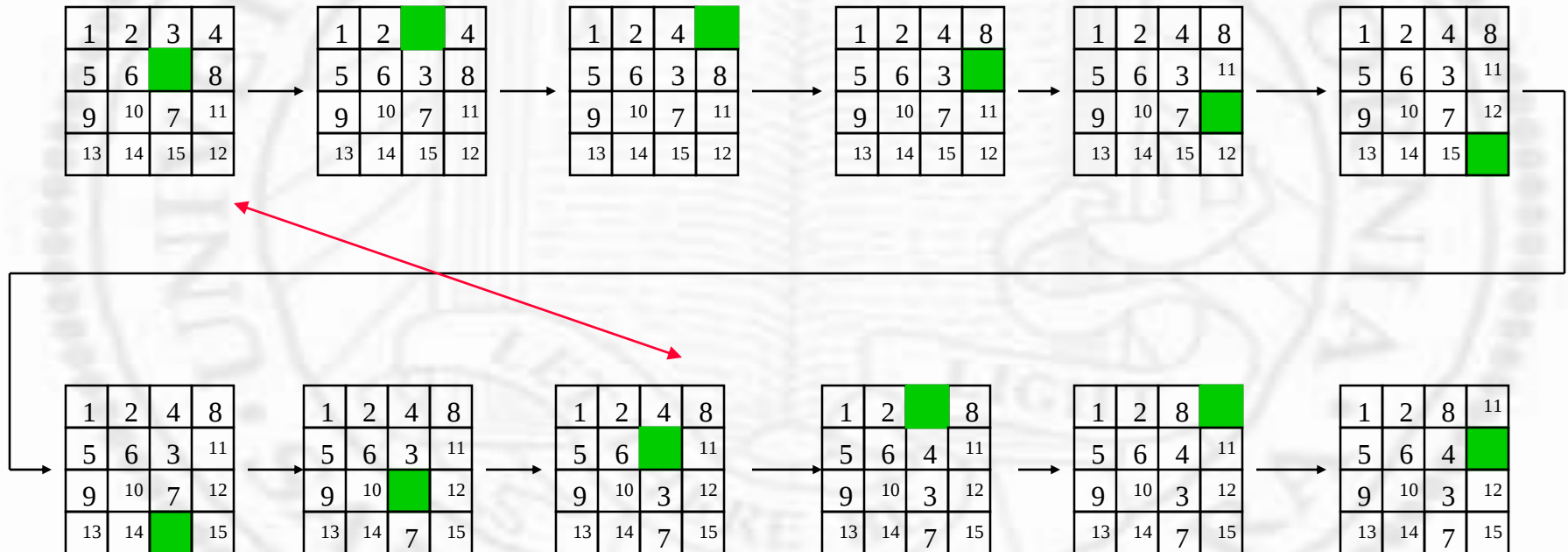


Branch and Bound

- The 15 puzzle
 - Input: 15 numbered tiles (1-15) and a blank one on a 4x4 square
 - Legal moves: a numbered tile, which is a 4-neighbor of the blank tile, can move into the location of the blank tile
 - Output: an ordered final configuration

- Depth first search

- up, right, down, left order
- do not undo the last move



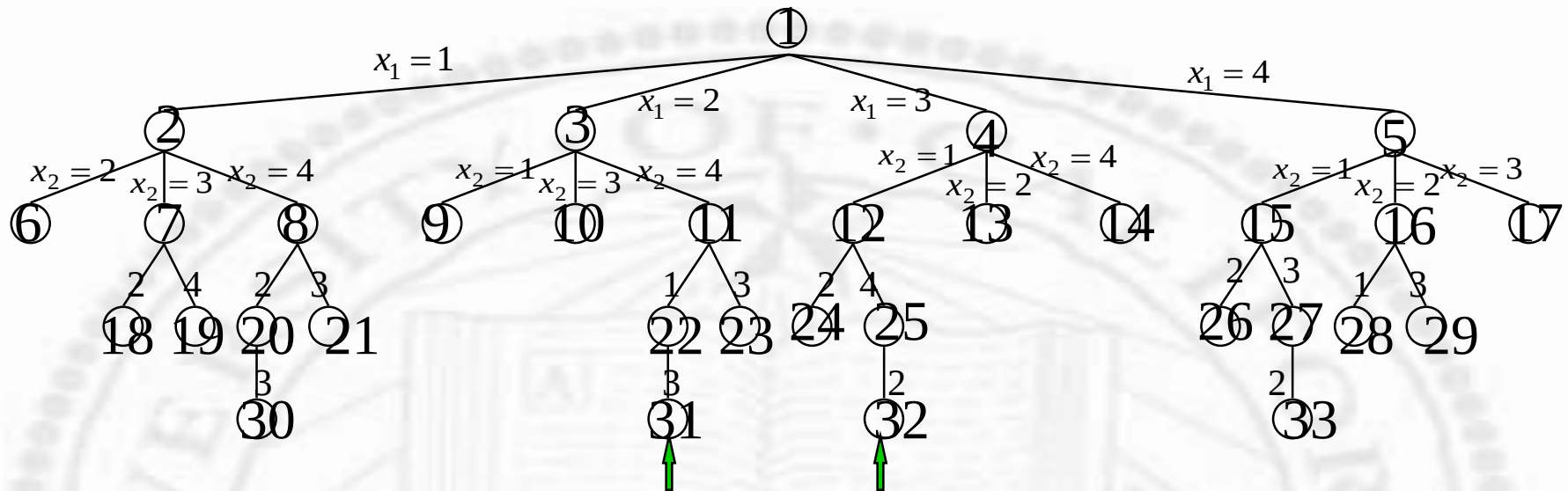
□ Depth first search

- Always go left as deep as possible
- The left path
 - ♦ may be very long for large search problems
 - ♦ may contain a cycle and never terminate
 - ♦ the optimal solution may not be found there
 - ♦ may not be the natural way of searching
 - e.g. playing chess (many alternatives are considered simultaneously with a small number of look-ahead)

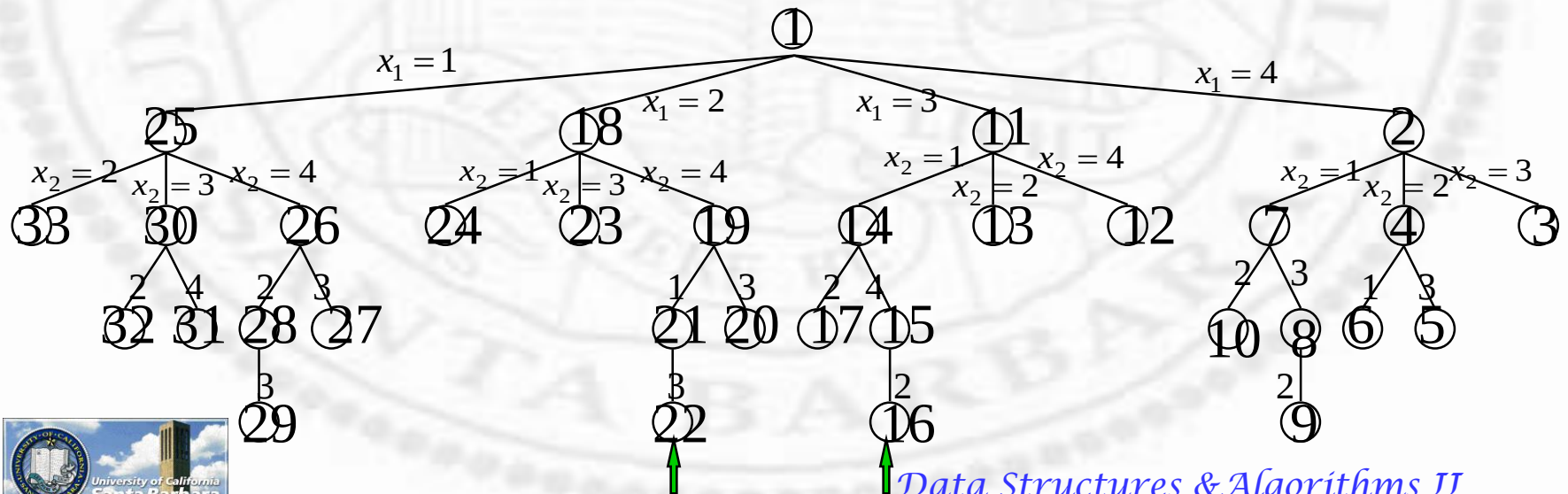
□ Breadth search

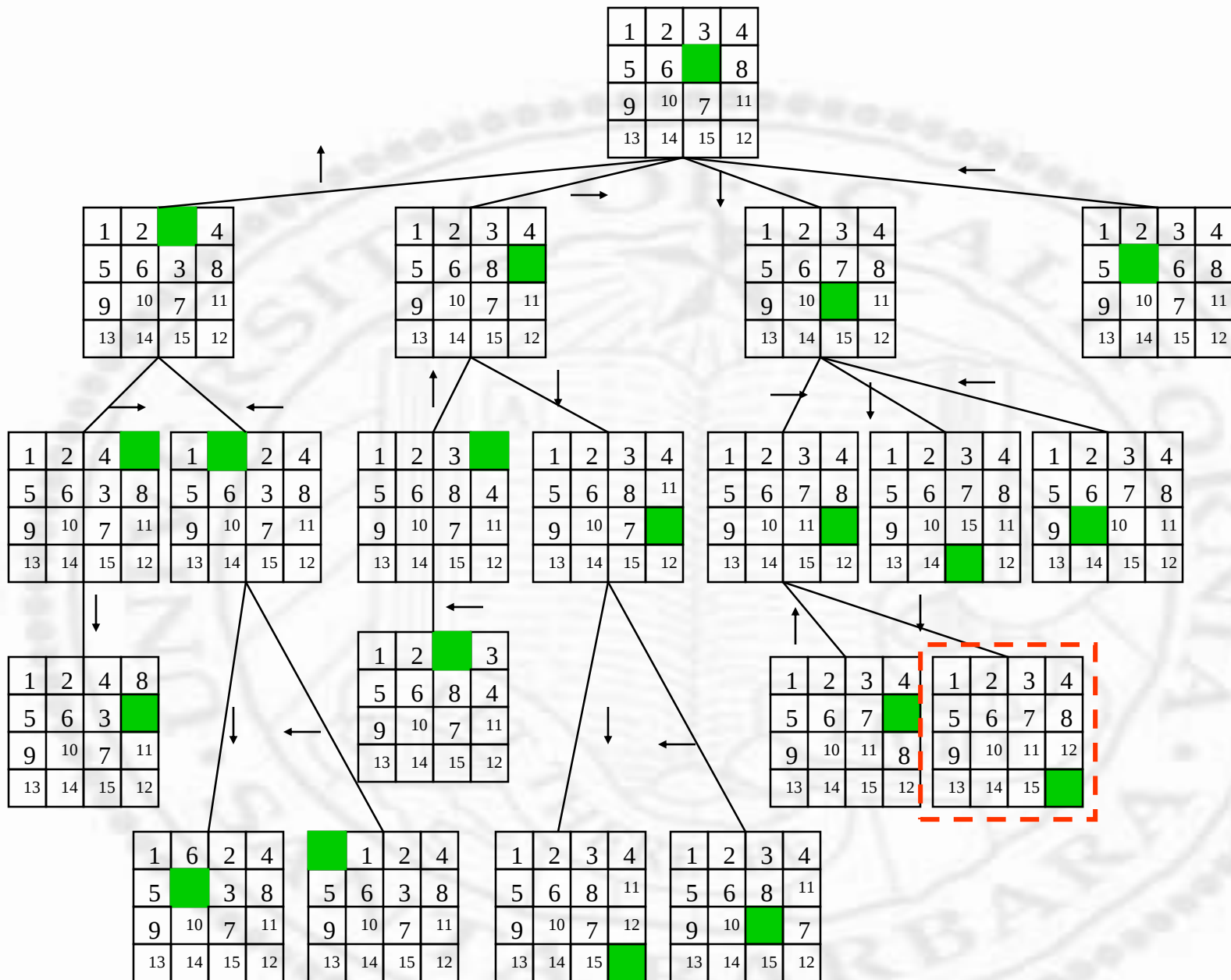
- An E-node stays an E-node until all its children are generated
- How to organize all the children?
 - ♦ FIFO (breadth first)
 - ♦ FILO (D-search)

FIFO breadth first search for 4-queen



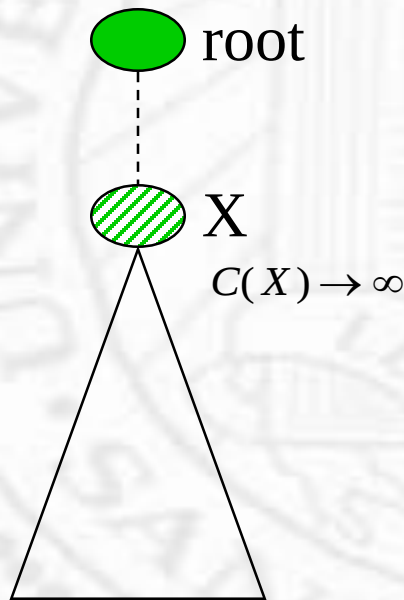
FILO breadth first search for 4-queen



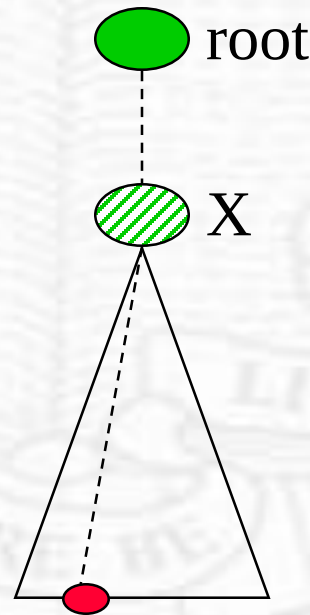


- Problems with depth, breadth searches
 - They have *rigid rules*
- If during the search it becomes apparent that a solution is near, search pattern should be altered to the path(s) that lead quickly to that solution

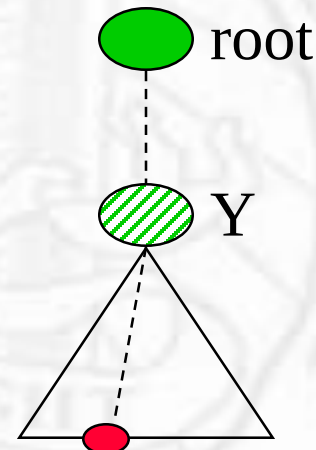
- Q: How to know which path is “better” and should be explored first?
- A: A cost function that is based on the cost of the solution states reachable



no answer state



$C(X) > C(Y)$



- Q: How do we know the cost of a partial problem state X ?
- A: Trace out the subtree rooted at X
- But then the subtree has already been explored, no use of the cost function
- ⇒ Ideal cost function is useless, need an *estimate* without generating the subtree

- How to generate an *educated* guess?
 - current position: cost of reaching current node from root (*known*)
 - estimated distance to an answer state: cost of reaching a solution (*unknown*)

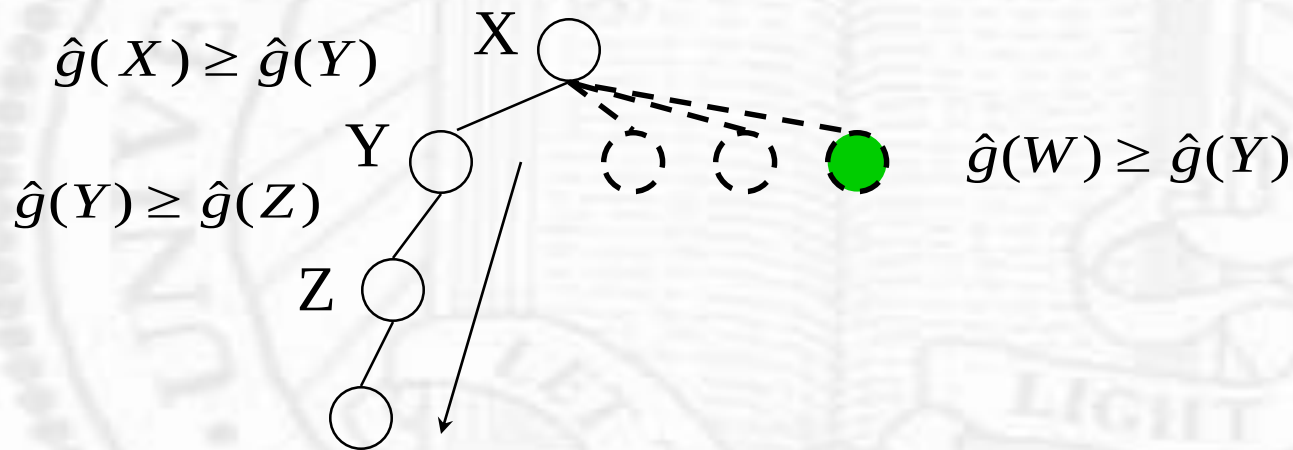
$$\hat{C}(X) = f(h(X)) + \hat{g}(X)$$

$h(X)$: distance from root to X

$f(\cdot)$: nondecreasing function

$\hat{g}(X)$: *estimated* cost to reach an answer from X

- Use only $\hat{g}(X)$
 - normally, we expect search to make progress, i.e., exploring deeper into the state space tree leads us closer to an answer



- may turn into a depth first search

□ Use only $f(h(x))$

– level ↓

– distance to root ↓

– effort to get there $h(x)$ ↓

– cost $f(h(x))$ ↓

– expand earlier

⇒ breadth first search

□ A *balanced* cost function should have both components

- A search based on the least-cost-first principle is called *LC branch-and-bound* search
 - Can be more efficient
 - Will it find the optimal solution?

- cost



Trade-off in Search Pattern

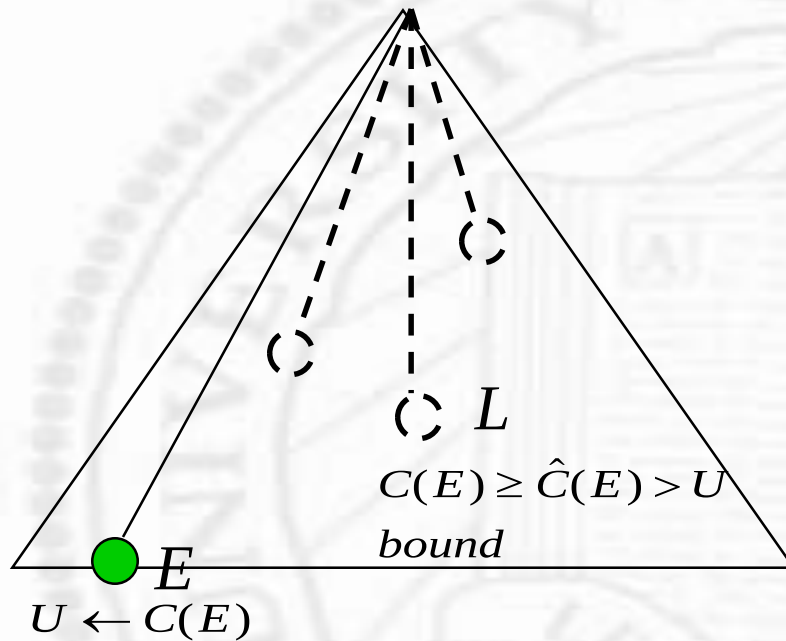
- Depth, breadth, etc.
 - rigid ordering
 - applicable to all
 - no need for a cost function
- LC branch-and-bound
 - more flexible
 - applicable if a good cost function is available

Trade-off in Bounding

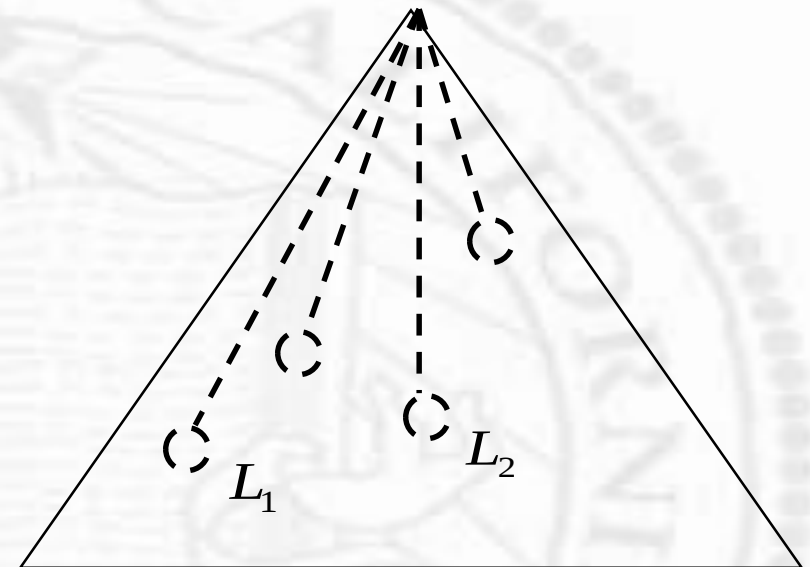
- Depth first
 - feasibility
 - optimality
- Breadth and LC branch-and-bound
 - feasibility
 - optimality (?)



- In back tracking



- In breadth and LC branch and bound

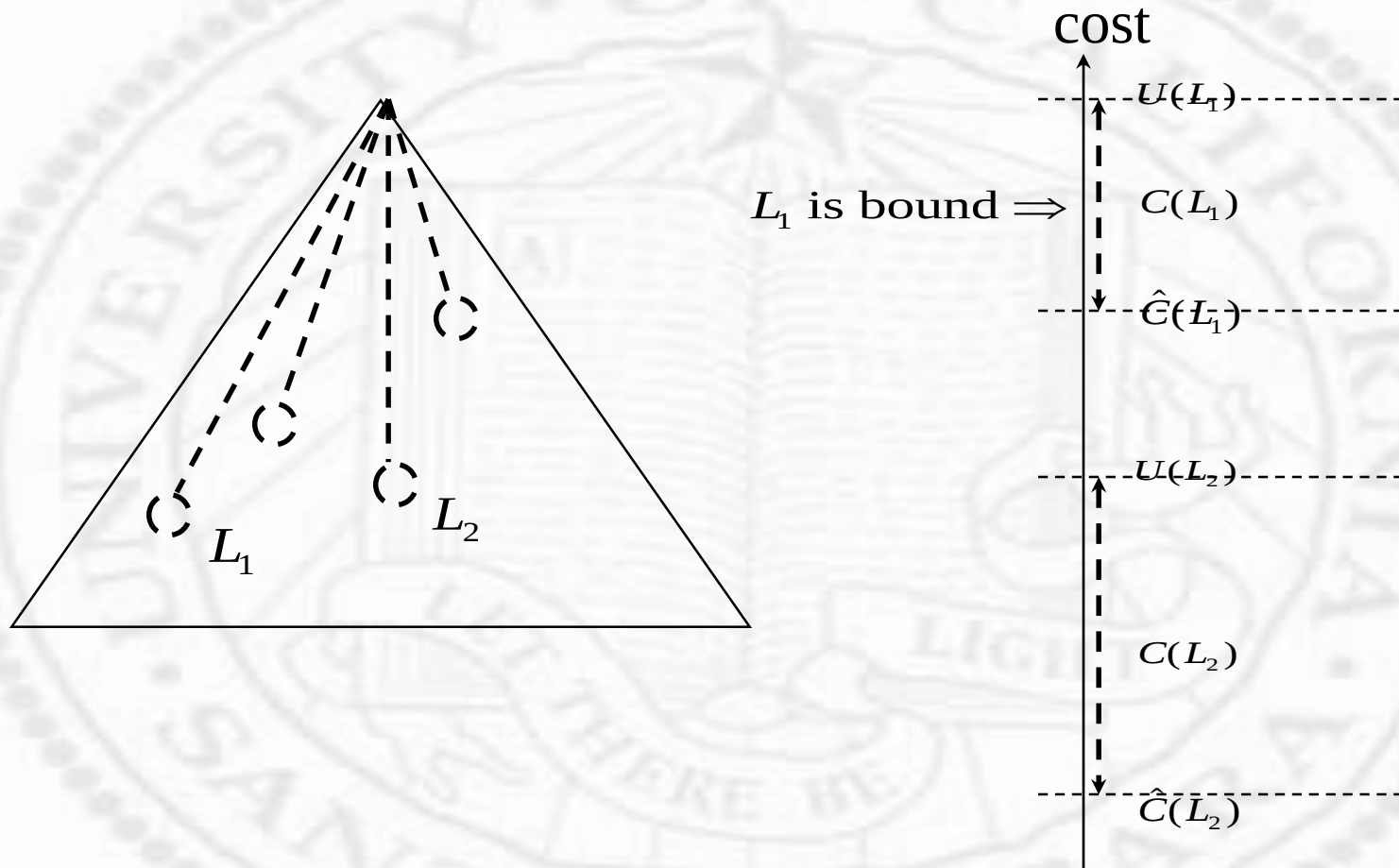


$\hat{C}(L_2) \quad \hat{C}(L_1) \quad C(L_2) \quad C(L_1)$
 → cost

$\hat{C}(L_2) \quad C(L_2) \quad \hat{C}(L_1) \quad C(L_1)$
 → cost

$\hat{C}(L_2) \quad \hat{C}(L_1) \quad C(L_1) \quad C(L_2)$
 → cost

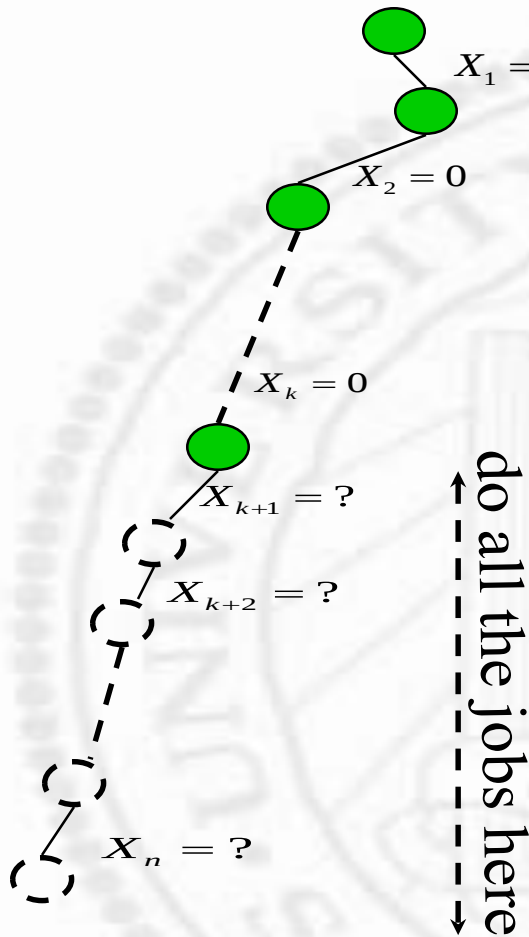
Bounding in Branch-and-Bound



Job Sequencing with Deadline

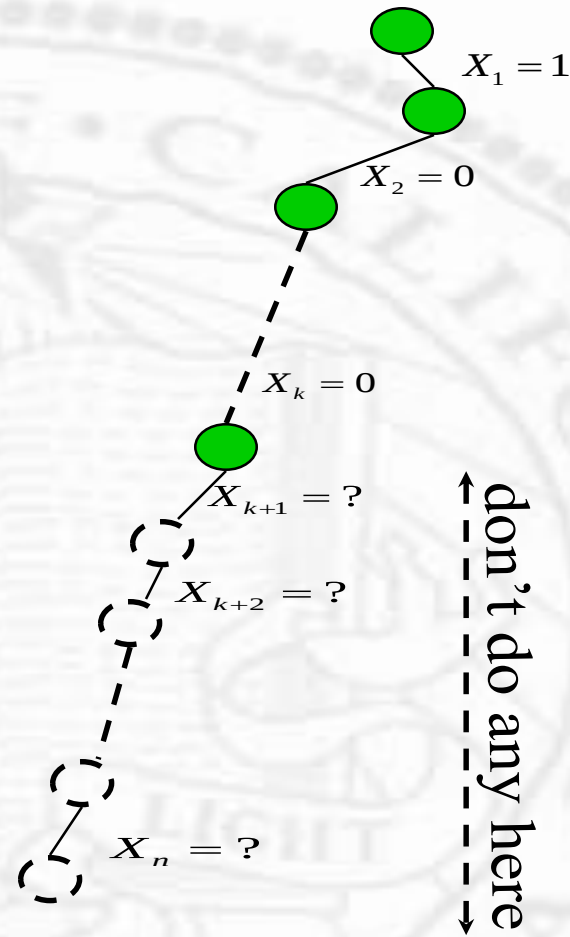
- Input:
 - a set of n jobs with deadlines and penalty
 - a single machine to execute all jobs
- Output: A subset of jobs, each completed before the deadline with least penalty

□ Lower bound



$$\sum_{1 \leq i \leq k} P_i (1 - X_i) = \sum_{\substack{i \leq k \\ i \notin J}} P_i$$

□ Upper bound



$$\sum_{1 \leq i \leq k} P_i (1 - X_i) + \sum_{i > k} P_i = \sum_{\substack{i \leq k \\ i \notin J}} P_i + \sum_{i > k} P_i$$

$$k, \sum_{\substack{i < k \\ i \notin J}} \hat{C}, \sum_{i \notin J} \hat{U}$$

$$X_k = 1$$

$$X_k = 0$$

$$k + 1, \hat{C}' = \hat{C}, \hat{U}' = \hat{U} - P_k$$

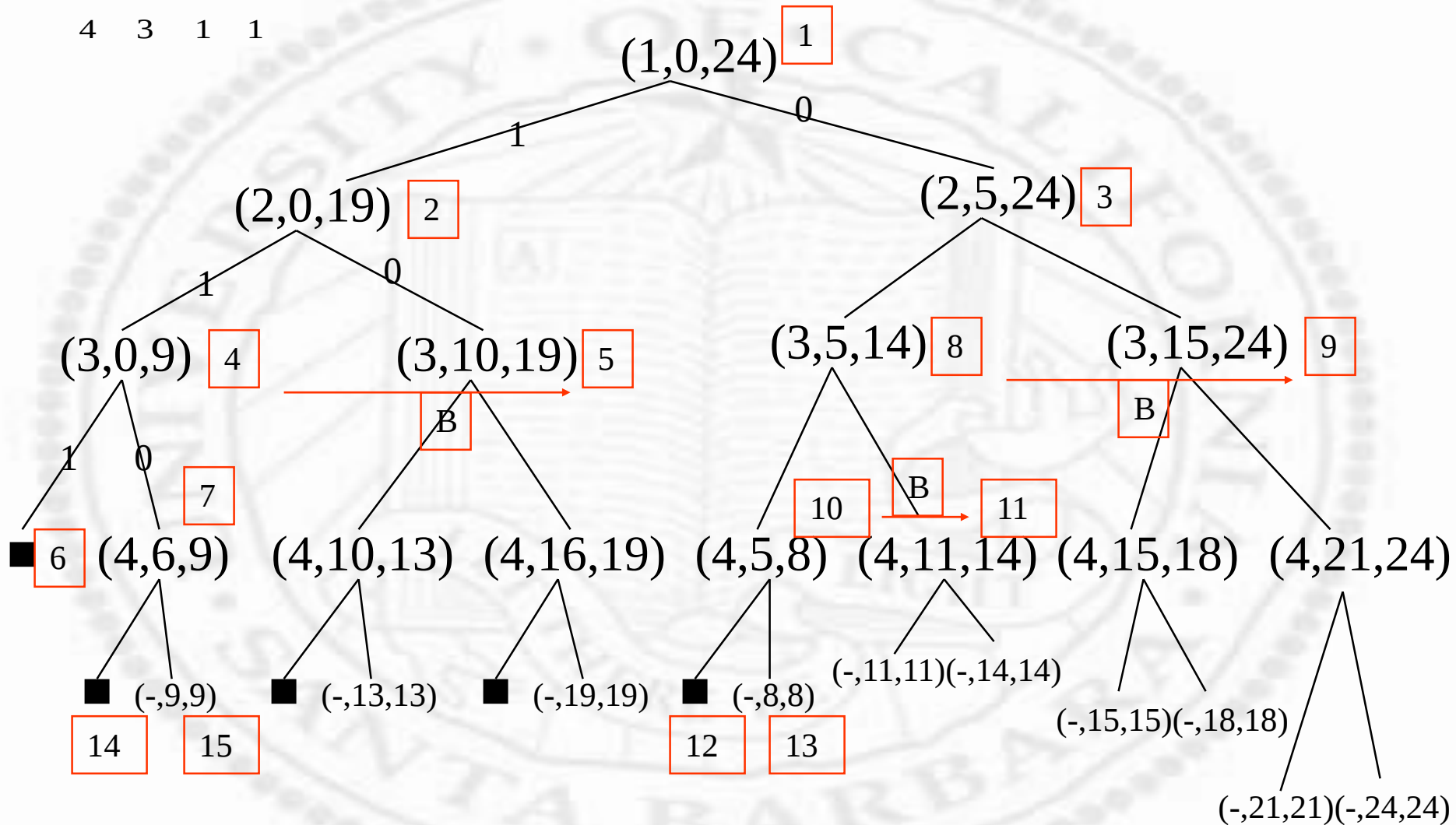
$$k + 1, \hat{C}' = \hat{C} + P_k, \hat{U}' = \hat{U}$$

$$k, \quad \sum_{\substack{i < k \\ i \notin J}} \hat{C} P_i, \quad \sum_{i \notin J} \hat{U} P_i$$


	p	d	t
1	5	1	1
2	10	3	2
3	6	2	1
4	3	1	1

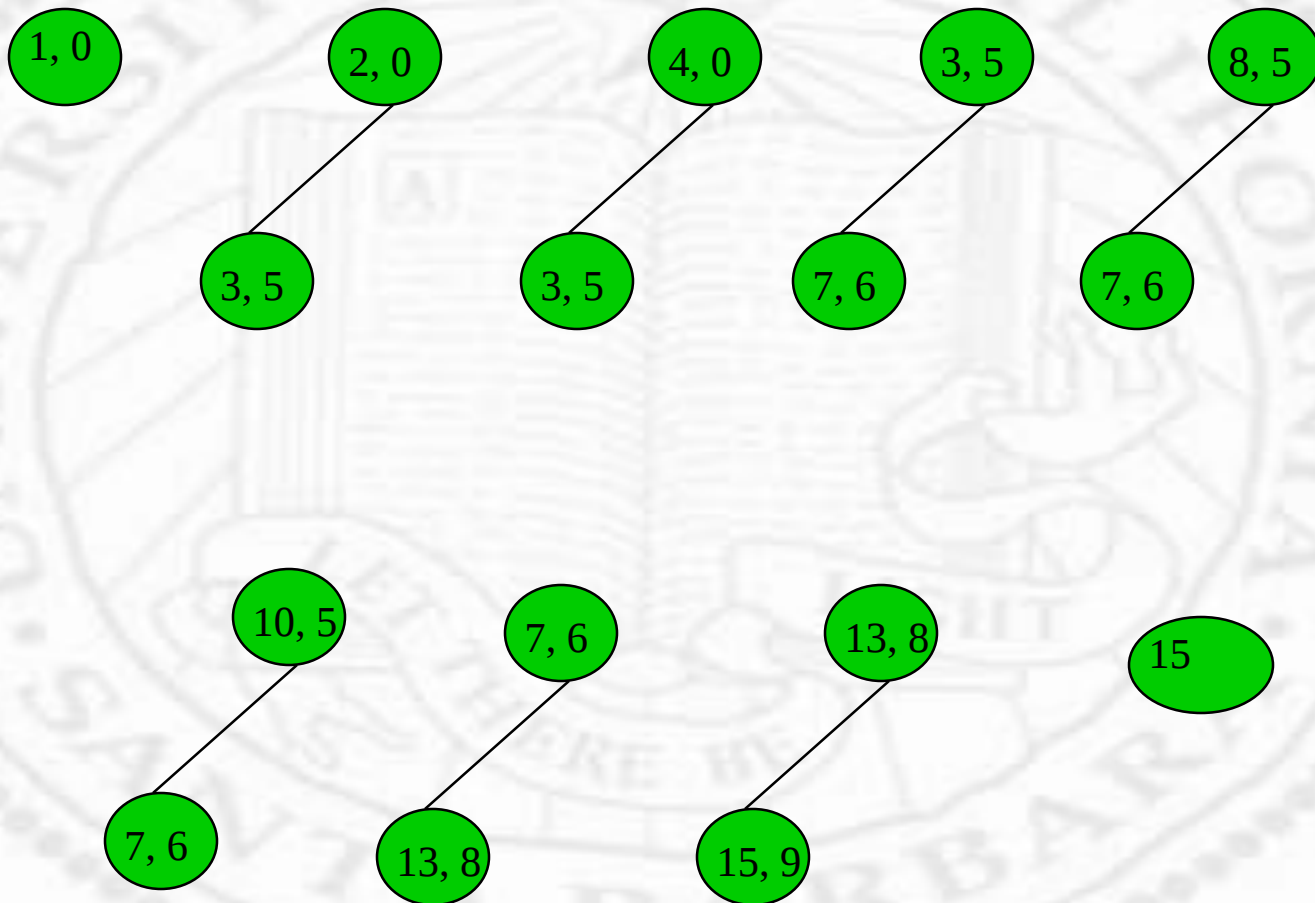
$$k, \quad \hat{C} \quad \hat{U}$$

$$\sum_{\substack{i < k \\ i \notin J}} P_i, \quad \sum_{i \notin J} P_i$$



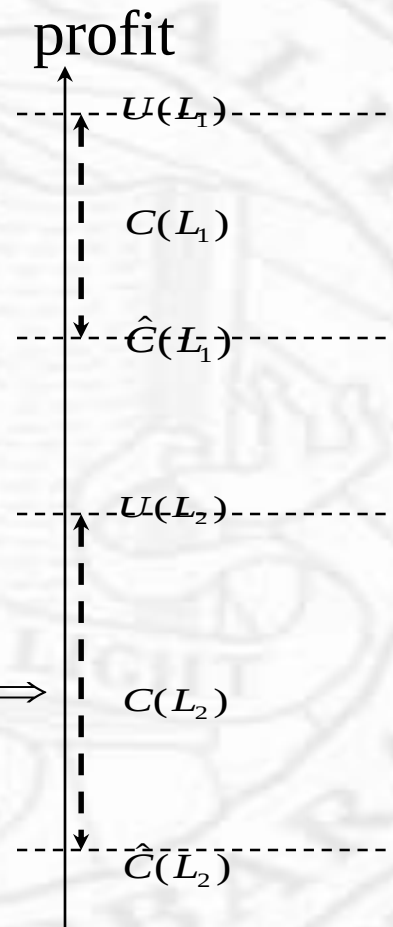
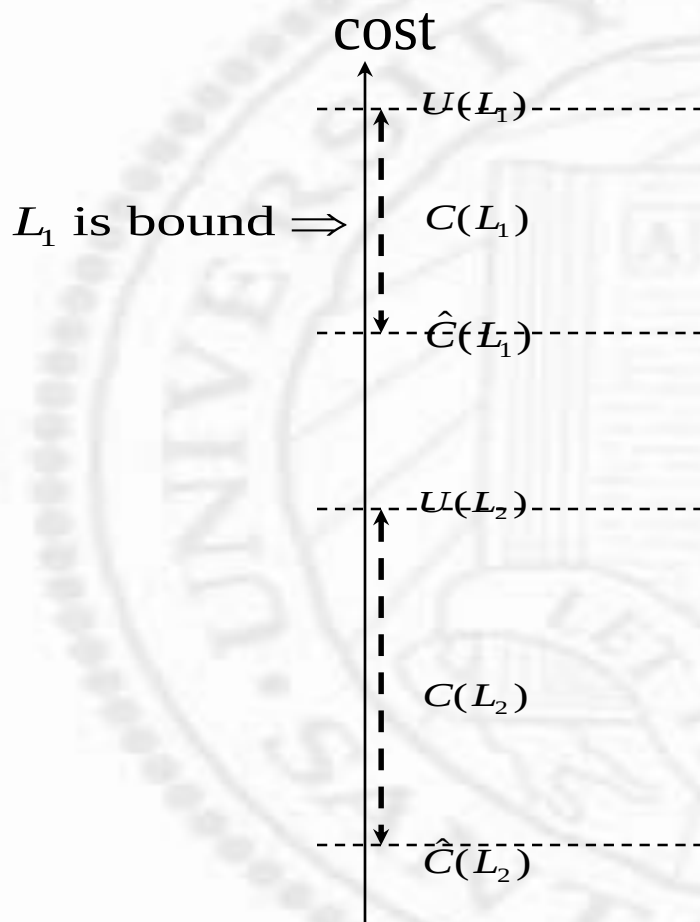
- Store candidates in a partially-ordered tree (a heap)

(node number, c)



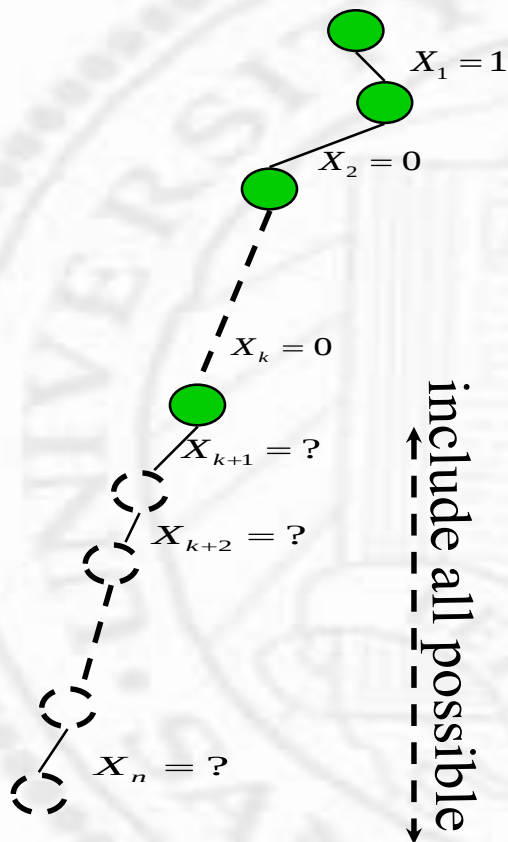
□ Minimization problems

□ Maximization problems

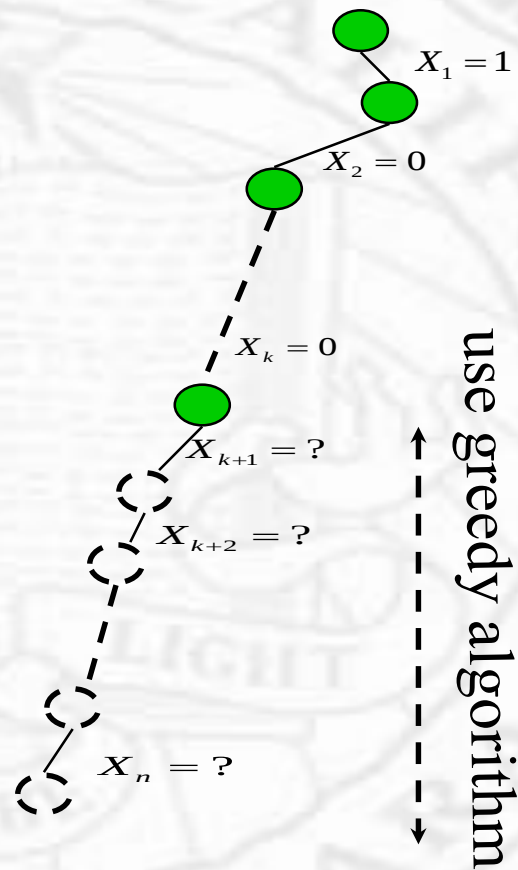


0/1-Knapsack

□ Lower bound



□ Upper bound



$$k, \quad \hat{C} \quad \hat{U}$$

$$\sum_{\substack{i < k \\ i \in \text{sack}}} P_i + \text{integer}, \quad \sum_{\substack{i < k \\ i \in \text{sack}}} P_i + \text{greedy}$$

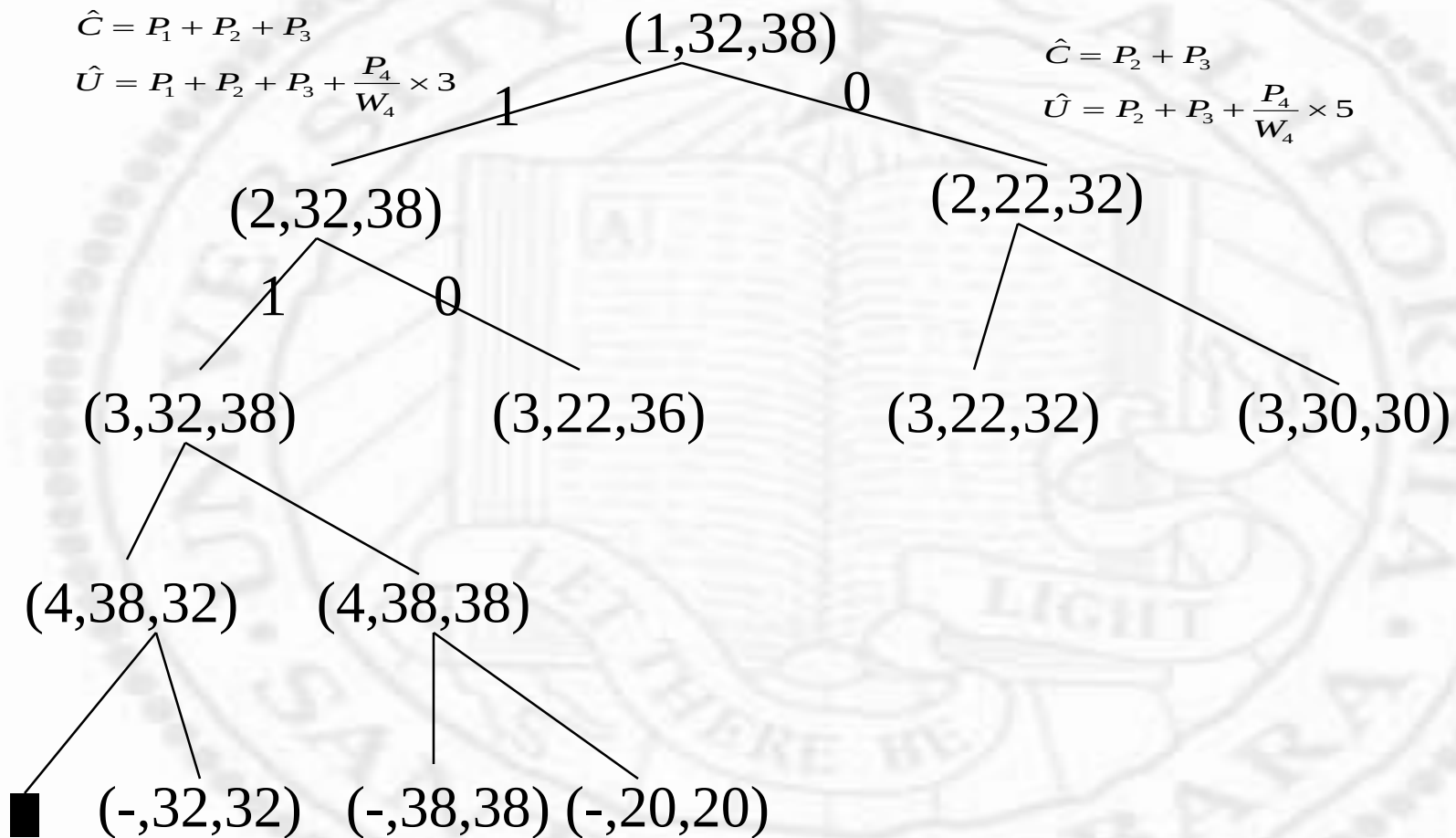
$$X_k = 1$$

$$X_k = 0$$

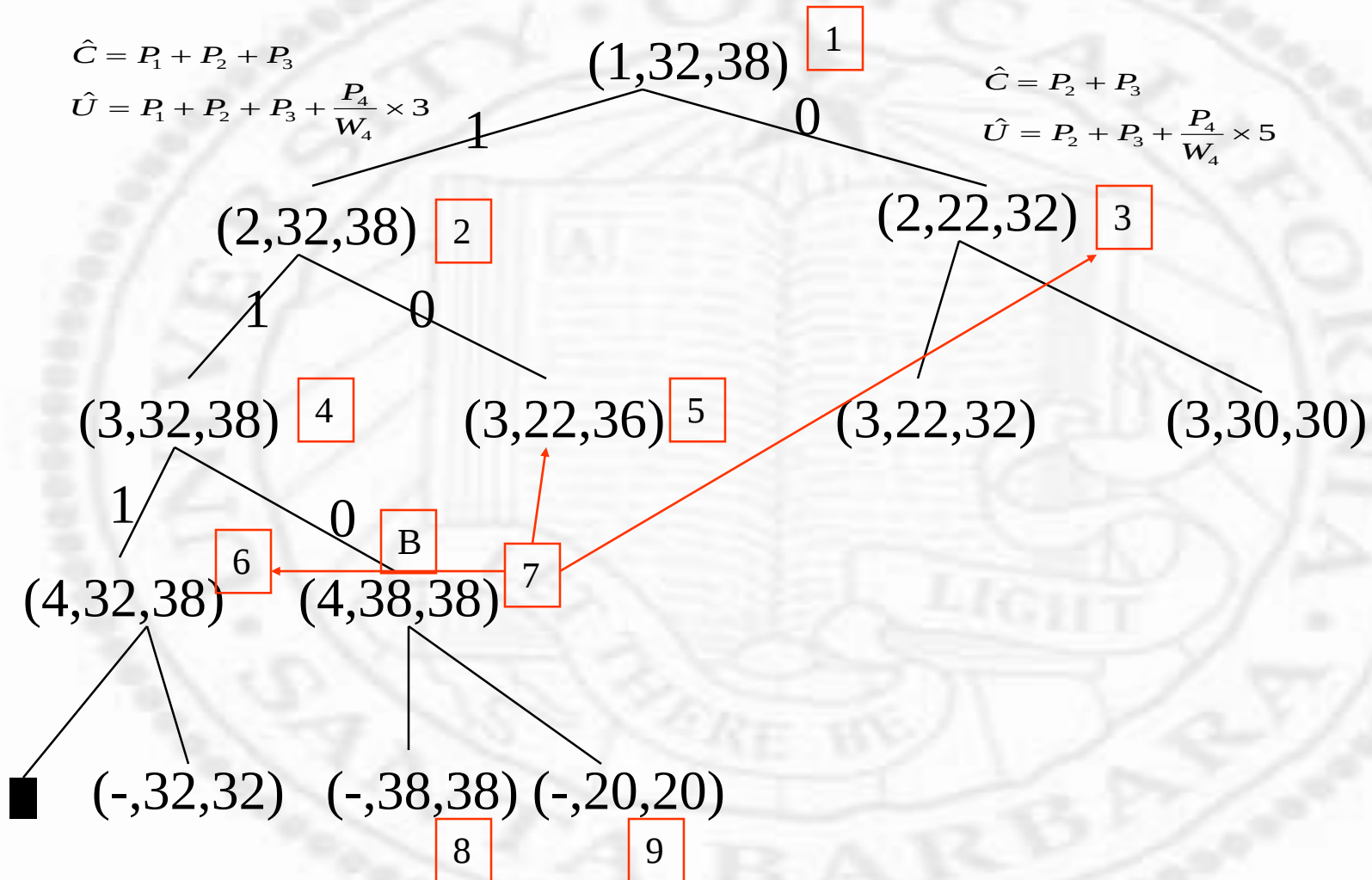
$$k + 1, \hat{C}' = \hat{C}, \hat{U}' = \hat{U}$$

$$k + 1, \hat{C}' \text{ from integer}, \hat{U}' \text{ from greedy}$$

n=4 W=(2, 4, 6, 9)
M=15 P=(10,10,12,18)



n=4 W=(2, 4, 6, 9)
M=15 P=(10,10,12,18)

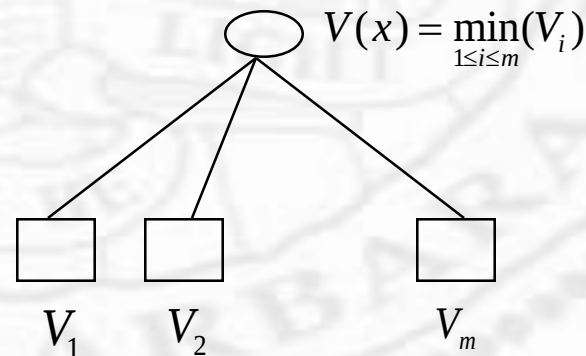
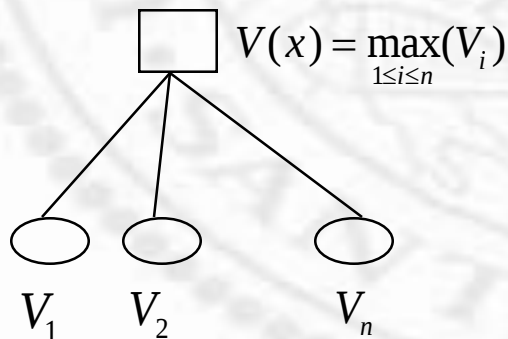


Branch-and-Bound in Game Trees

- Explore many possibilities
- Evaluate their relative merits
- Look ahead finite steps
- *Opposite goals at alternate steps*

- Game tree: all possible instances of a finite games
- Game instance: a particular branch from root to a terminal board configuration
- Terminal configuration:

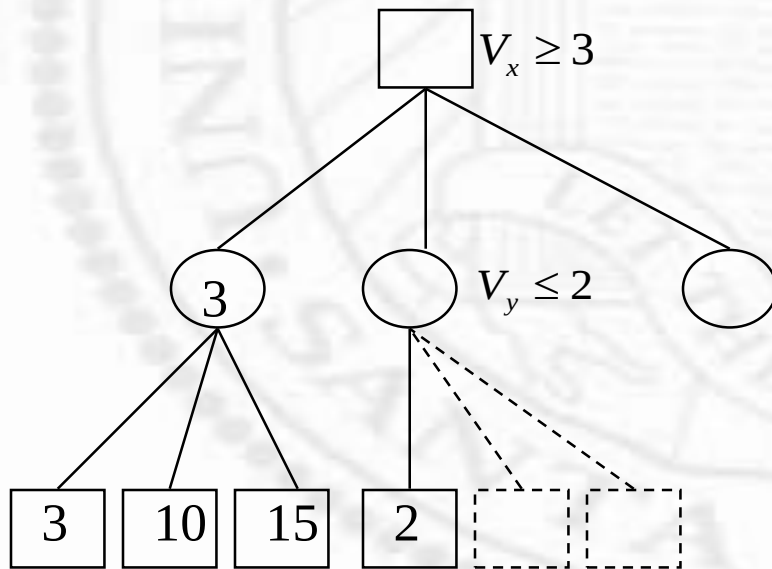
$$V(x) = \begin{cases} 1 & \text{if } x \text{ is a winning configuration for A} \\ 0 & \text{if } x \text{ is a draw configuration for A} \\ -1 & \text{if } x \text{ is a losing configuration for A} \end{cases}$$



- For chess
 - not possible to generate the whole game tree
 - only a few levels can be generated and evaluated
 - an intelligent evaluation strategy is needed
 - the move strategy is still the same
 - ♦ A to maximize the value
 - ♦ B to minimize the value

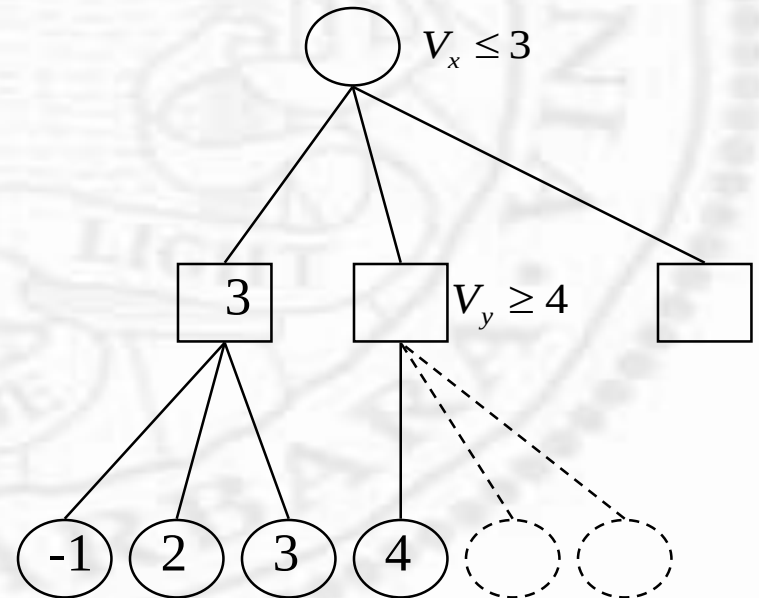
□ Alpha cutoff

- min V at max position
- if the value of a min position is less than the parent's alpha, the min position need not be explored further

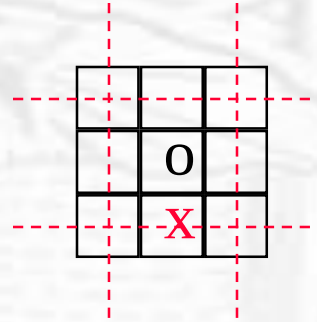
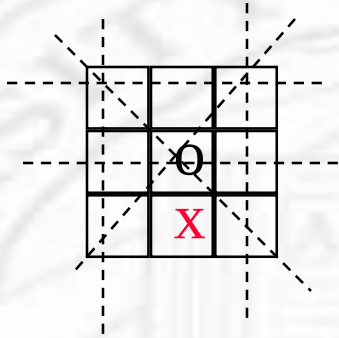


□ Beta cutoff

- max V at min position
- if the value of a max position is greater than the parent's beta, the max position need not be explored further

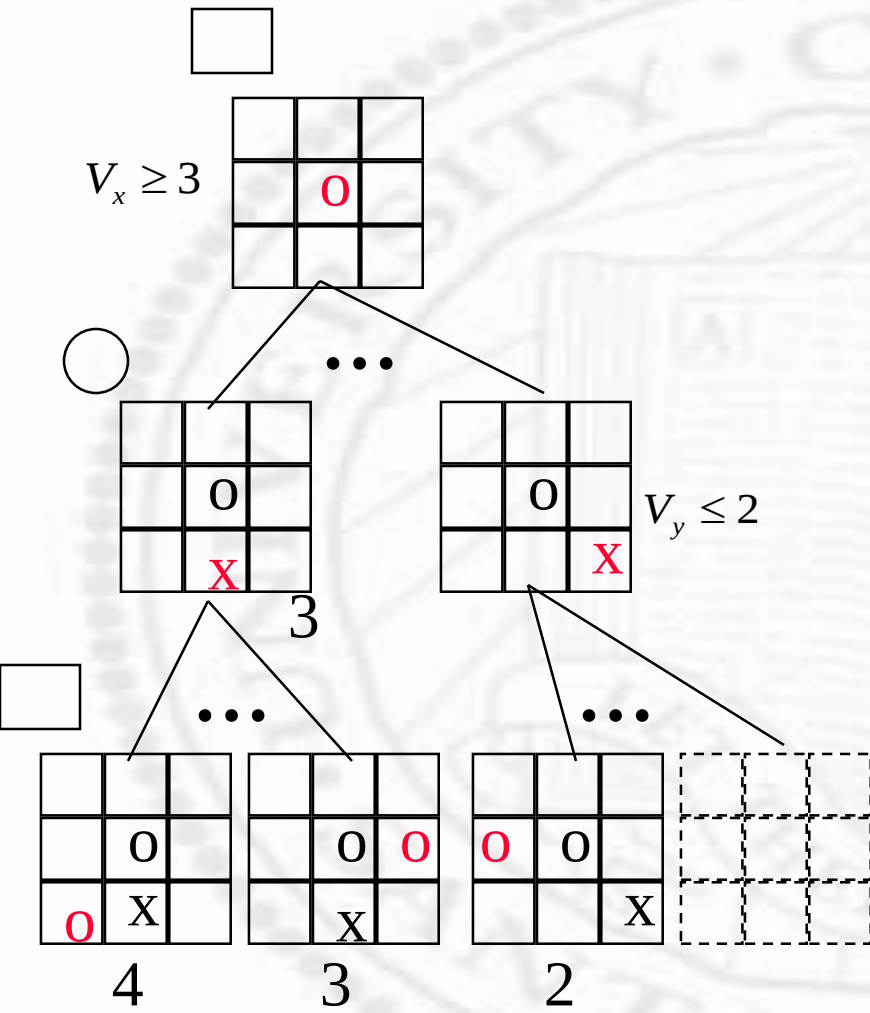


- Example tic-tac-toe
 - evaluation function

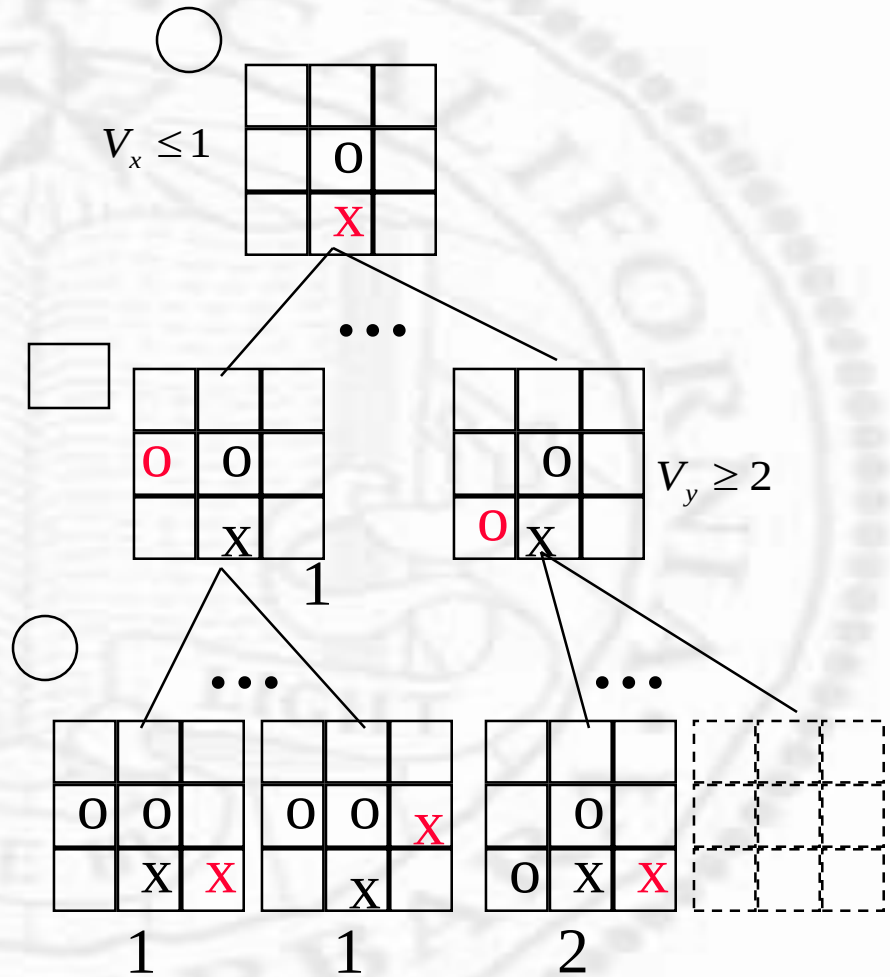


- 6 ways to win for (O) - 4 ways to win for (X)=2 in (O)'s favor

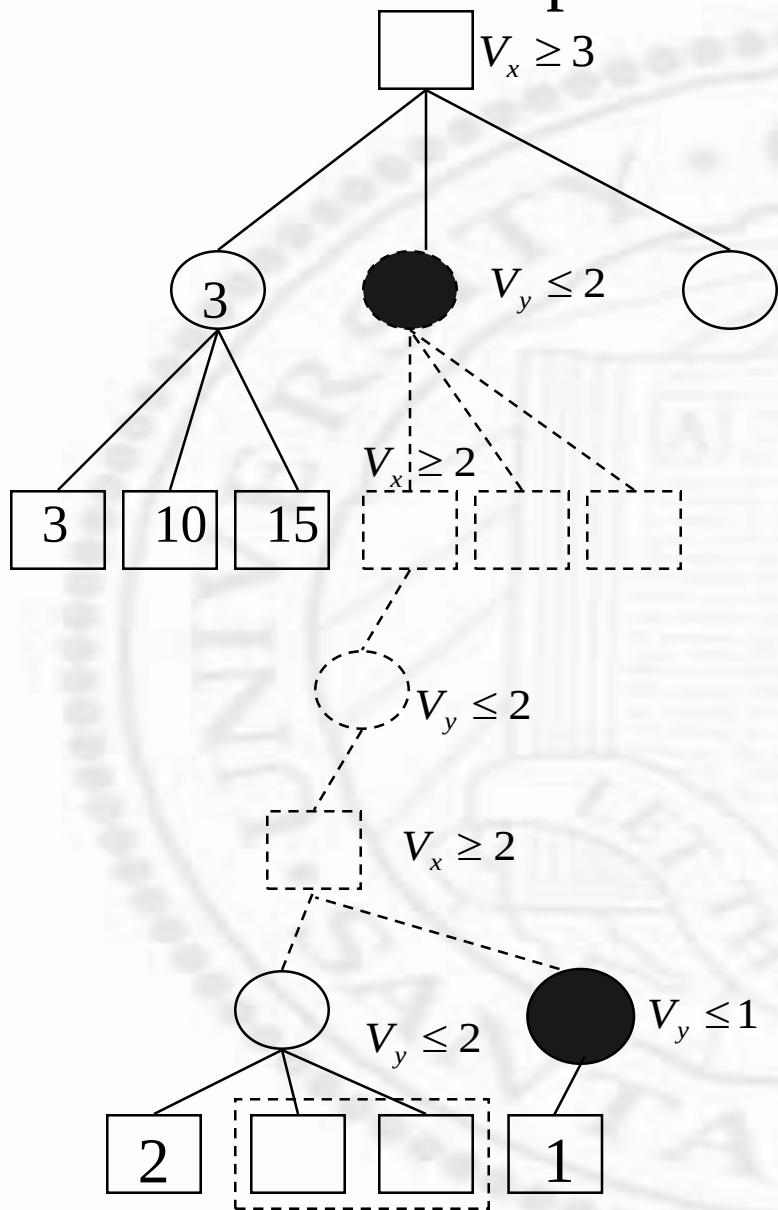
□ Alpha cutoff



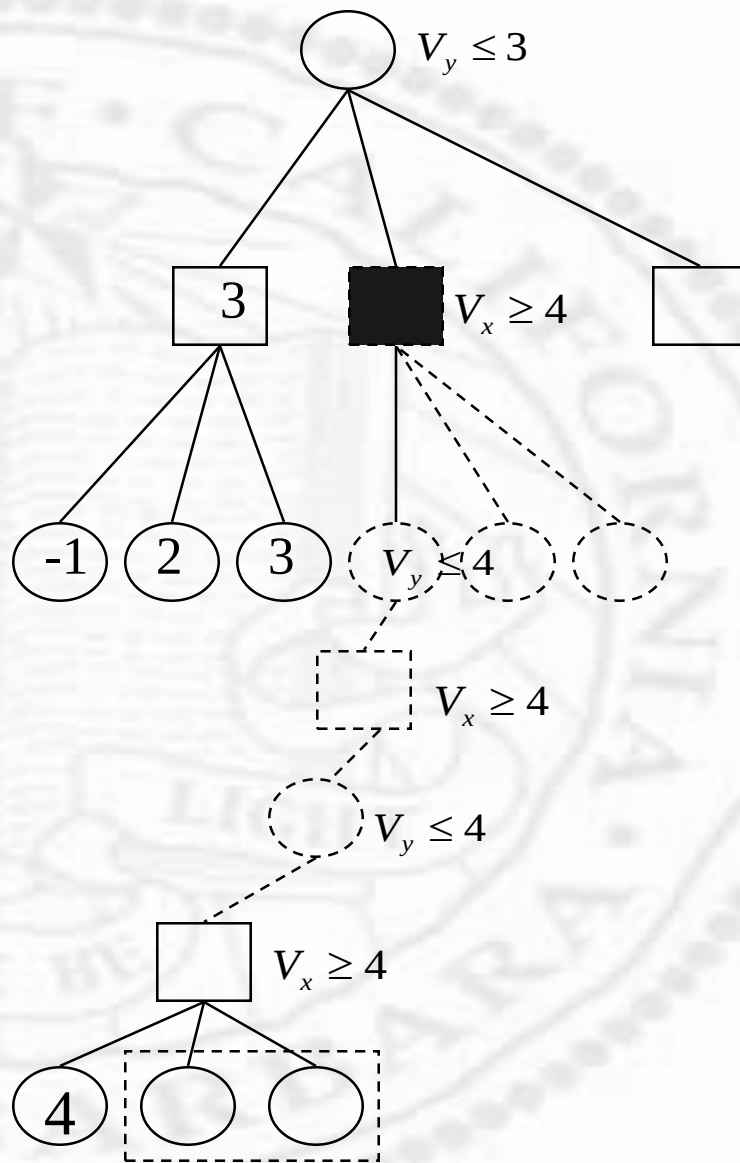
○ Beta cutoff



□ Multi-level Alpha cutoff



□ Multi-level Beta cutoff



Black: bounded