

# *2D Image Analysis*

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- ❖ Segmentation
- ❖ Localization
- ❖ Shape Analysis
- ❖ Classification & Categorization

# Segmentation

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- ❖ Partition images into *meaningful* entities
- ❖ The “*Holy-Grail*” problem in low-level computer vision
- ❖ A panacea to many high-level vision problems

# *Segmentation (cont.)*

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❖ Even though appeared simple, the problem is extremely hard

Noise

Sensing and lighting conditions

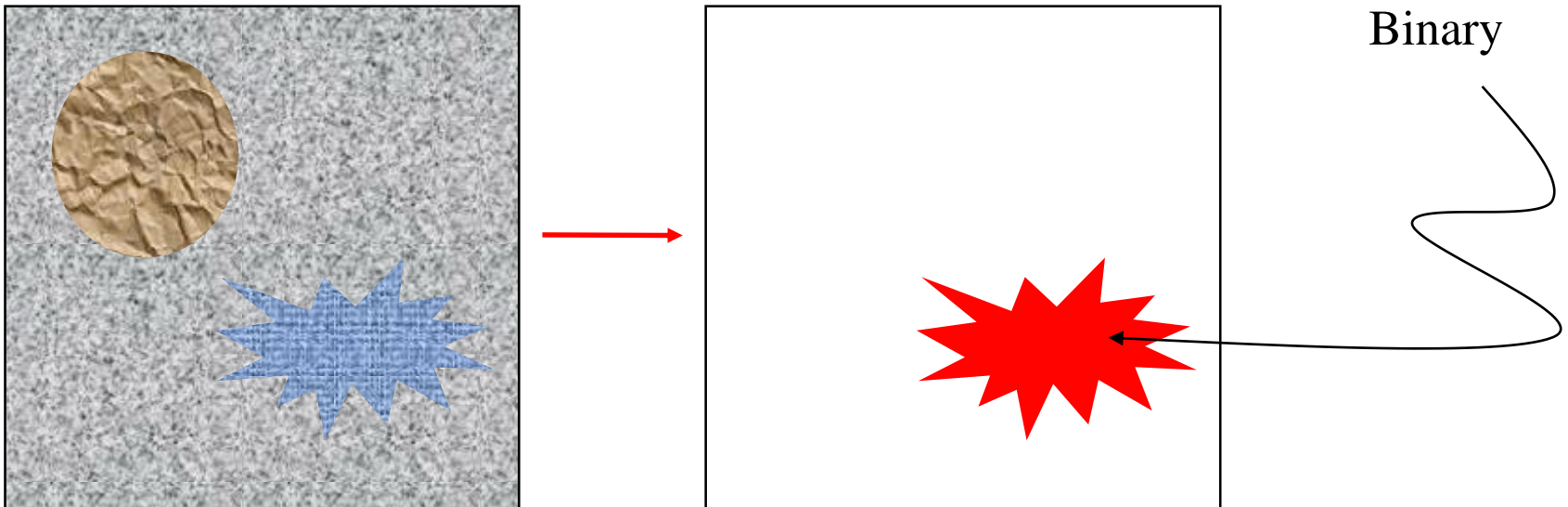
Repetitive patterns

Syntactic vs. semantic grouping

Top down vs. bottom up approaches

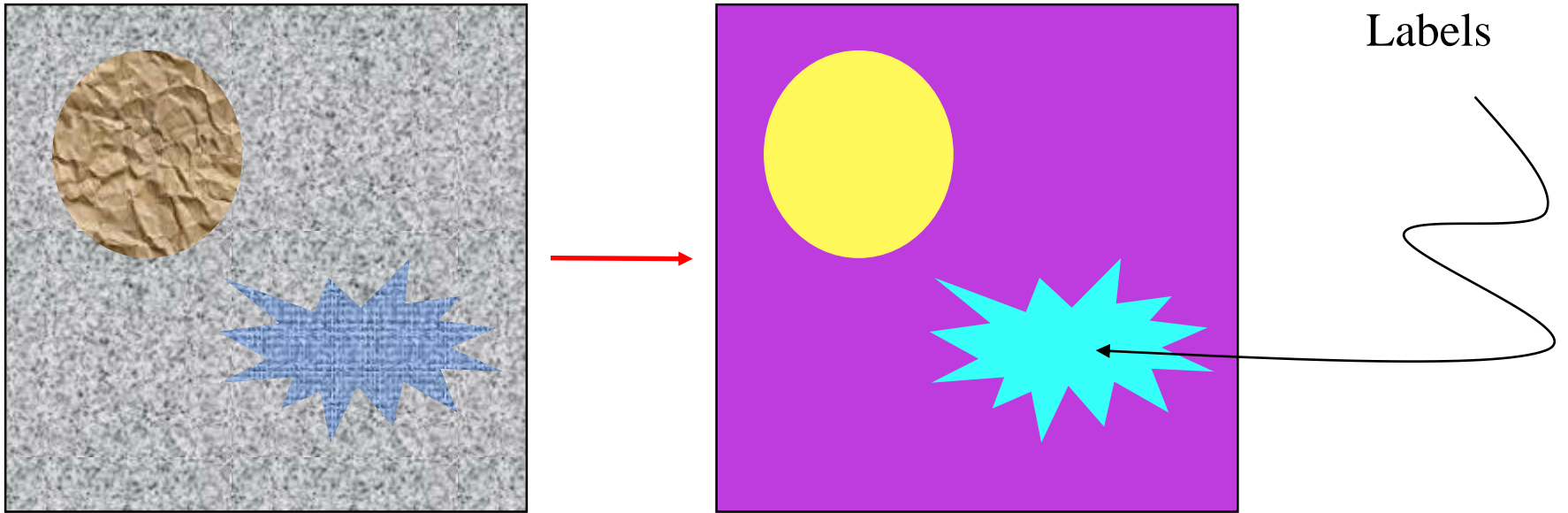
# What is segmentation?

- ❖ Isolating a specific region of interest (“find the star” or “bluish thing”)



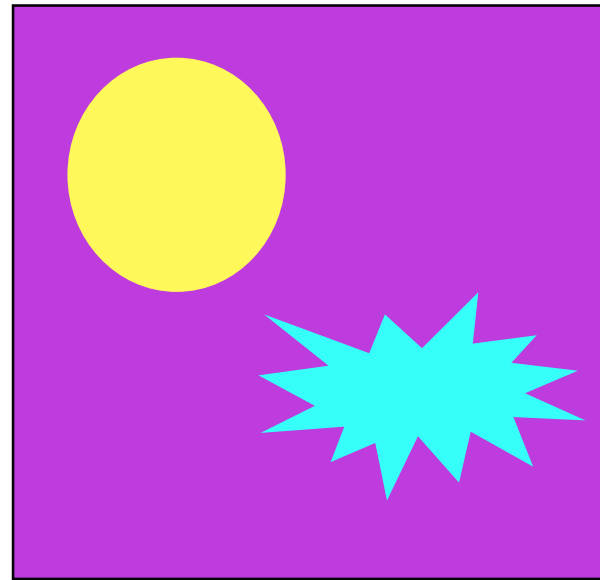
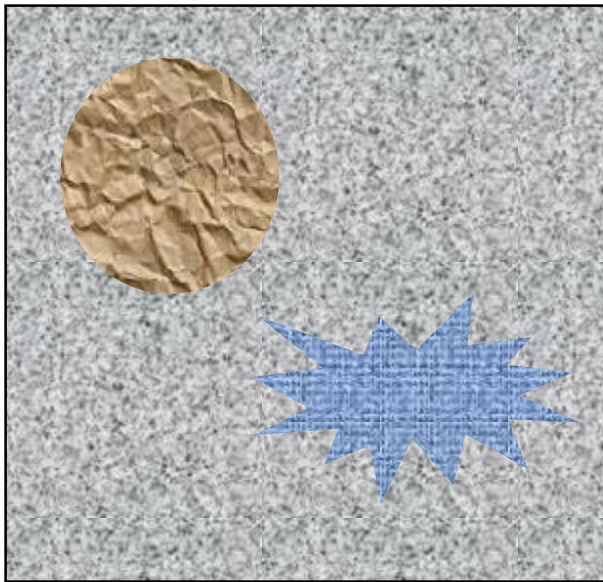
# What is segmentation?

- ❖ Partitioning images/volumes into meaningful pieces



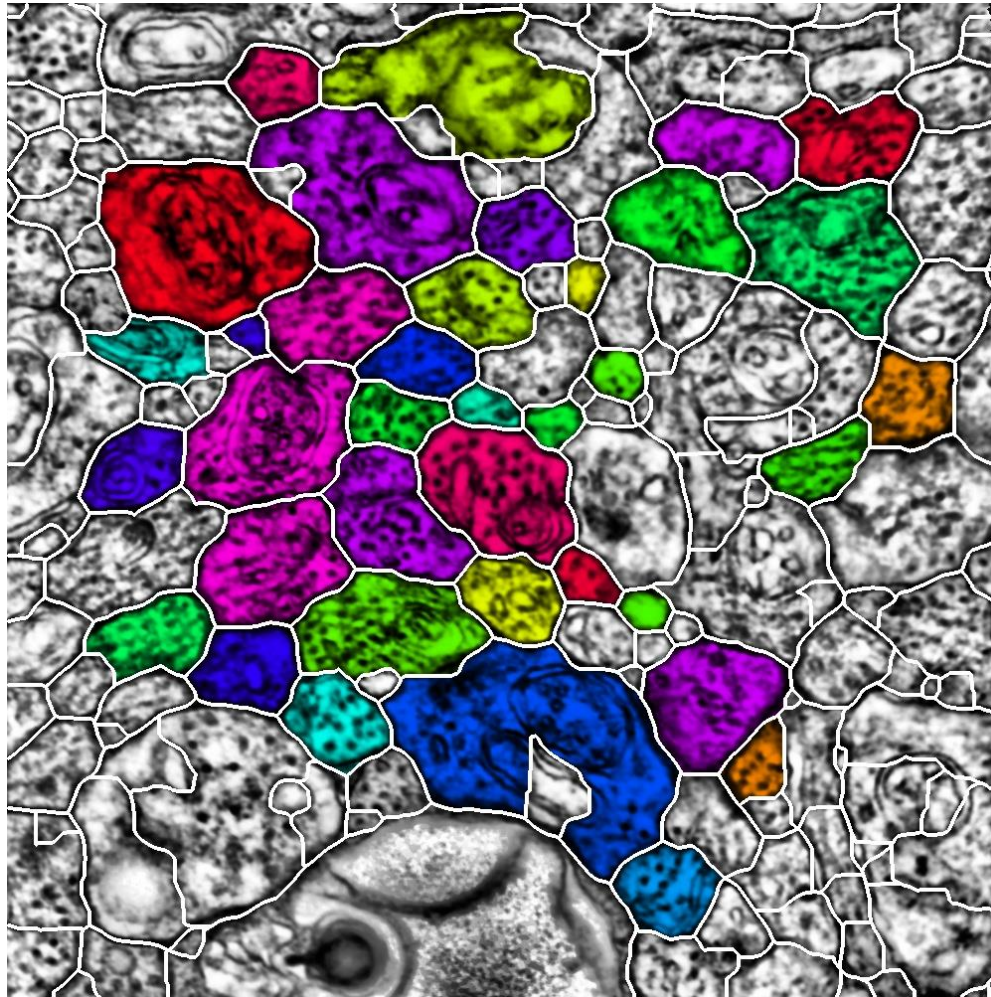
# What is segmentation?

- ❖ Assigning each pixel a type (tissue or material)



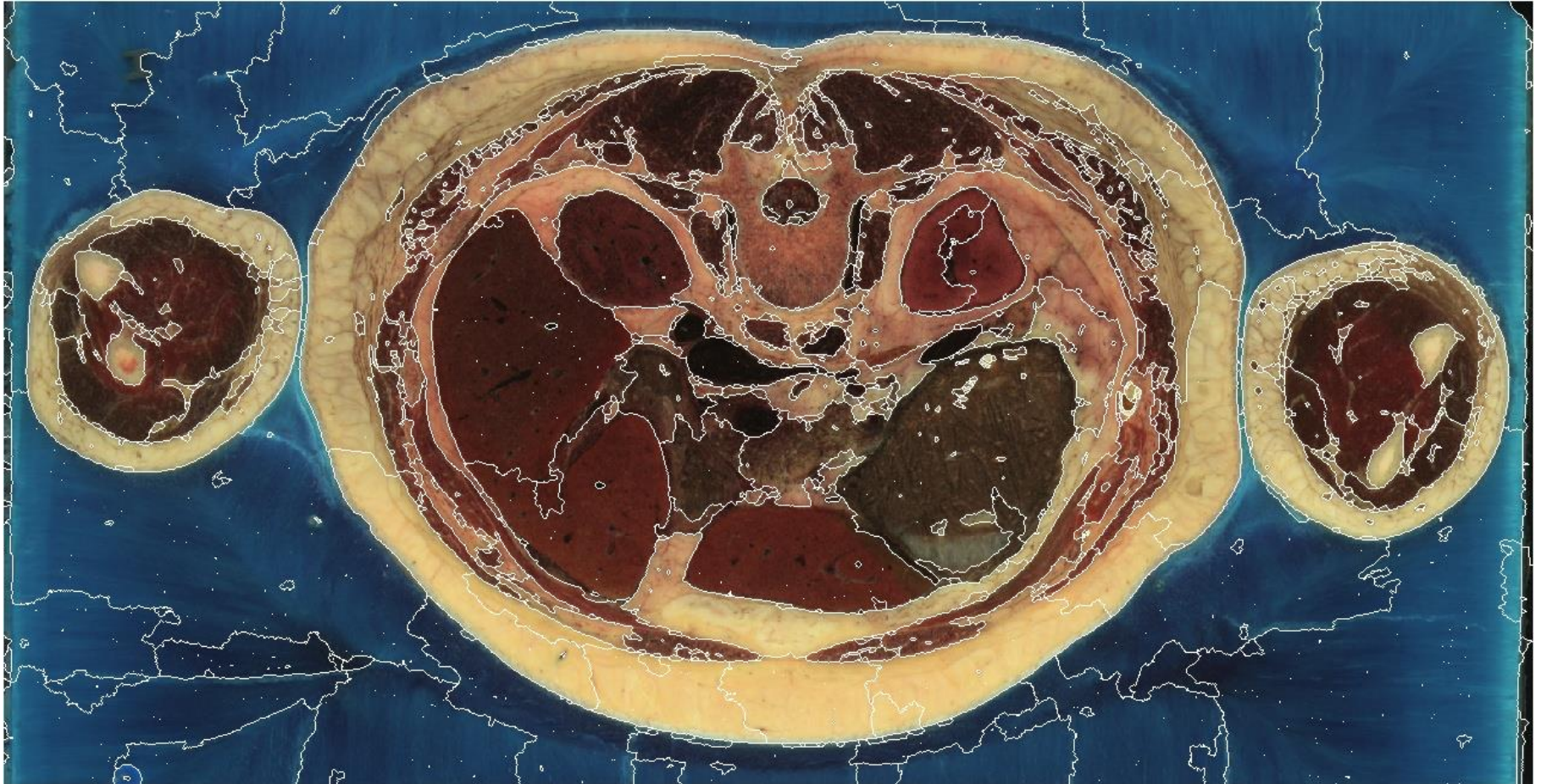
Fabric ●  
Paper ●  
Grass ●

# Examples

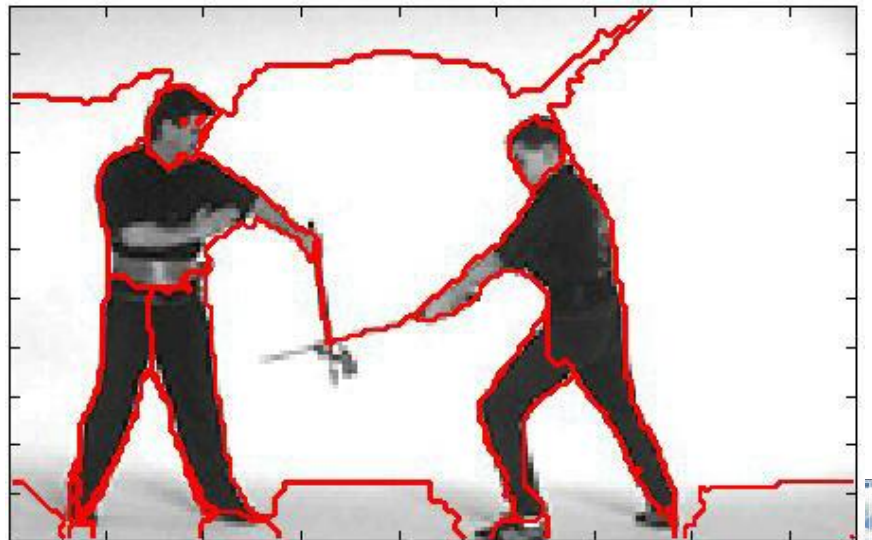
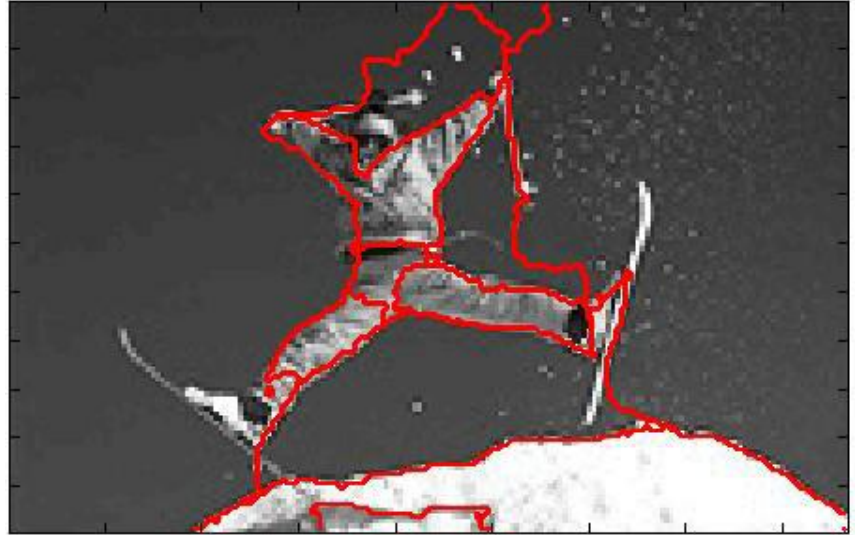
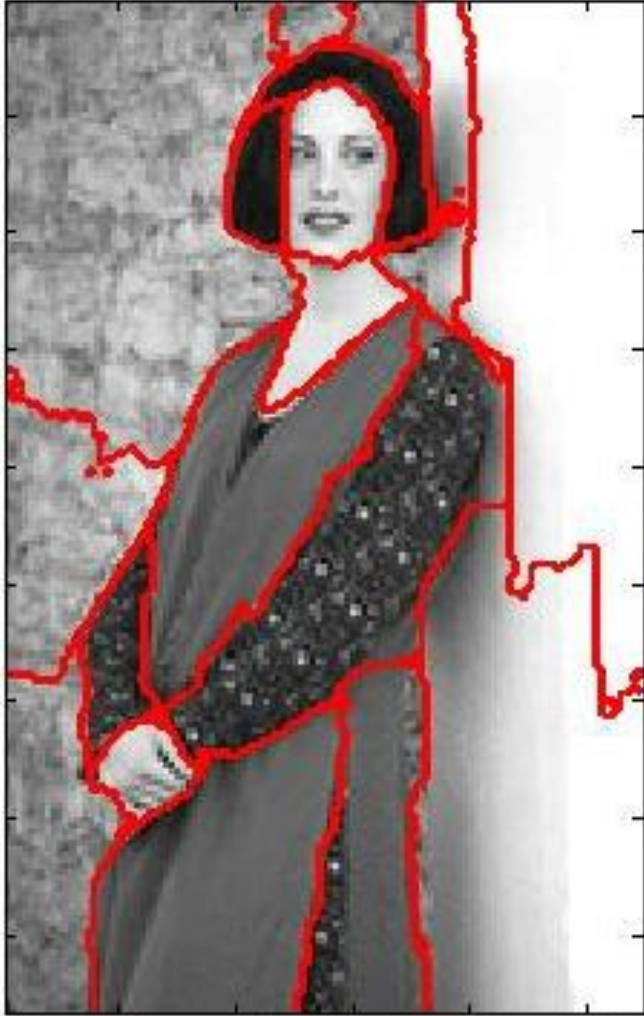




# Example



# Examples



# Examples





Query image: 108019



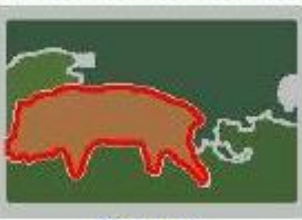
Query blobs

feature importance:					
	overall	color	texture	location	shape
blob	very	very	somewhat	not	not
background	somewhat	very	not	not	not

Querying from 35000 images (2000 returned by the filter).



1: 108044 (score = 0.99)



New query



2: 108023 (score = 0.98)



New query



3: 108006 (score = 0.98)



New query



4: 108029 (score = 0.98)



New query



5: 108051 (score = 0.98)



New query



6: 108084 (score = 0.97)



New query



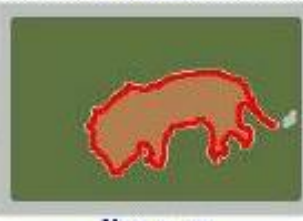
7: 108037 (score = 0.97)



New query



8: 108004 (score = 0.97)



New query

# Examples

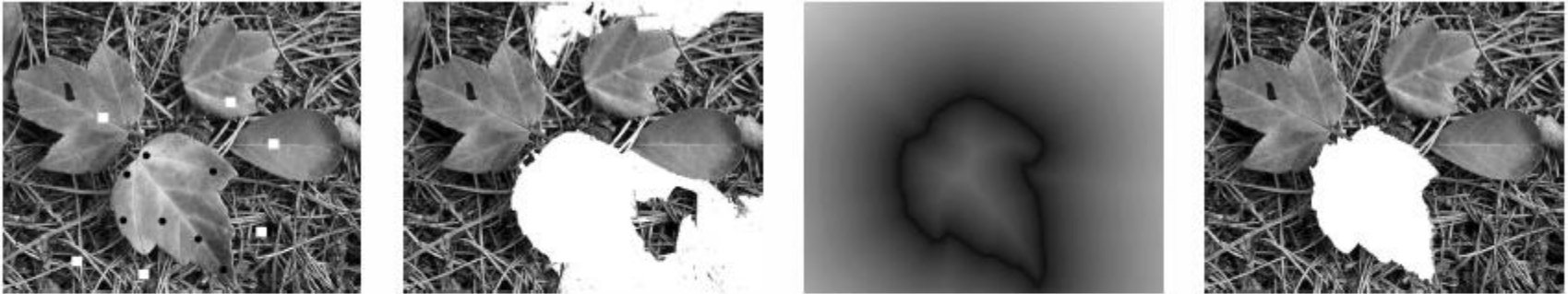


Figure 6. Segmenting a maple leaf. (a) The user input: circles indicate the object, squares indicate the background (colour is for visualization purposes only). (b) The result without shape priors – segmentation is shown in white. (c) The level-set of the shape template after transformation,  $\bar{\phi}_{trans}$ . (d) The result with shape priors.

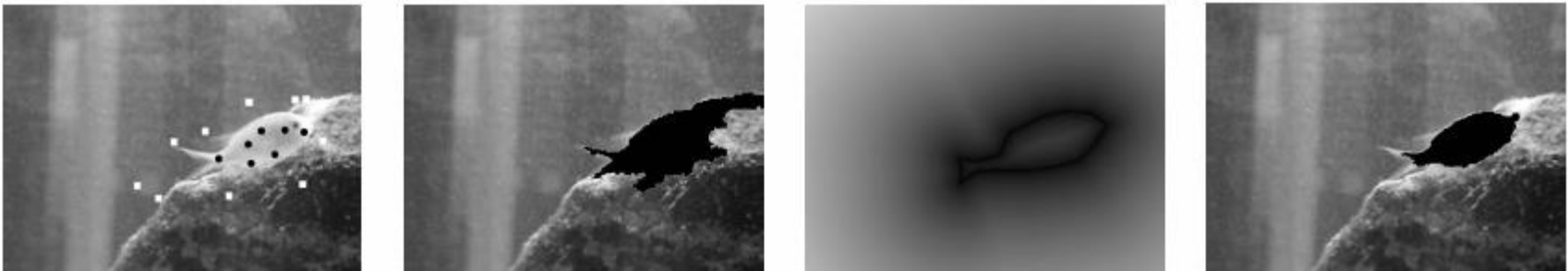


Figure 7. Segmenting a fish. (a) The user input: circles indicate the object, squares indicate the background (colour is for visualization purposes only). (b) The result without shape priors – segmentation is shown in black. (c) The level-set of the shape template after transformation,  $\bar{\phi}_{trans}$ . (d) The result with shape priors.

# Examples

## ❖ Sony EyeToy

□ Background, motion, and color segmentation



# Segmentation

- ❖ Spatial and temporal segmentation
  - ❑ And spatial-temporal (“spatiotemporal”) segmentation
- ❖ Segment images/video based on:
  - ❑ Grayscales
  - ❑ Color
  - ❑ Textures
  - ❑ Depth
  - ❑ Motion
  - ❑ Low-level features
  - ❑ Etc.

# Gelstalt Examples



Not grouped



Proximity



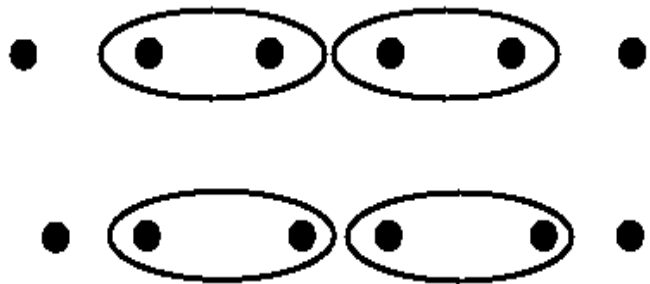
Similarity



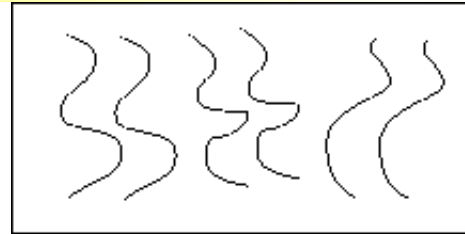
Similarity



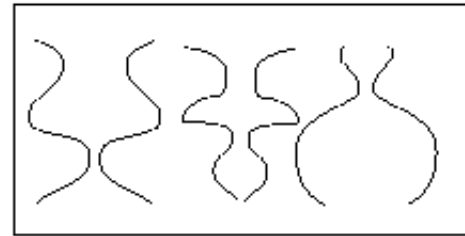
Common Fate



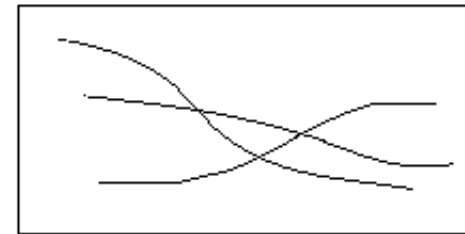
Common Region



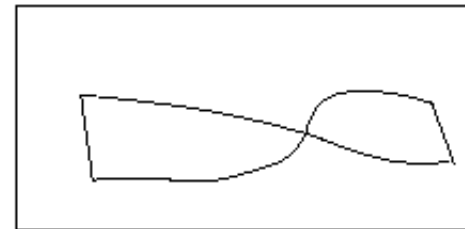
Parallelism



Symmetry



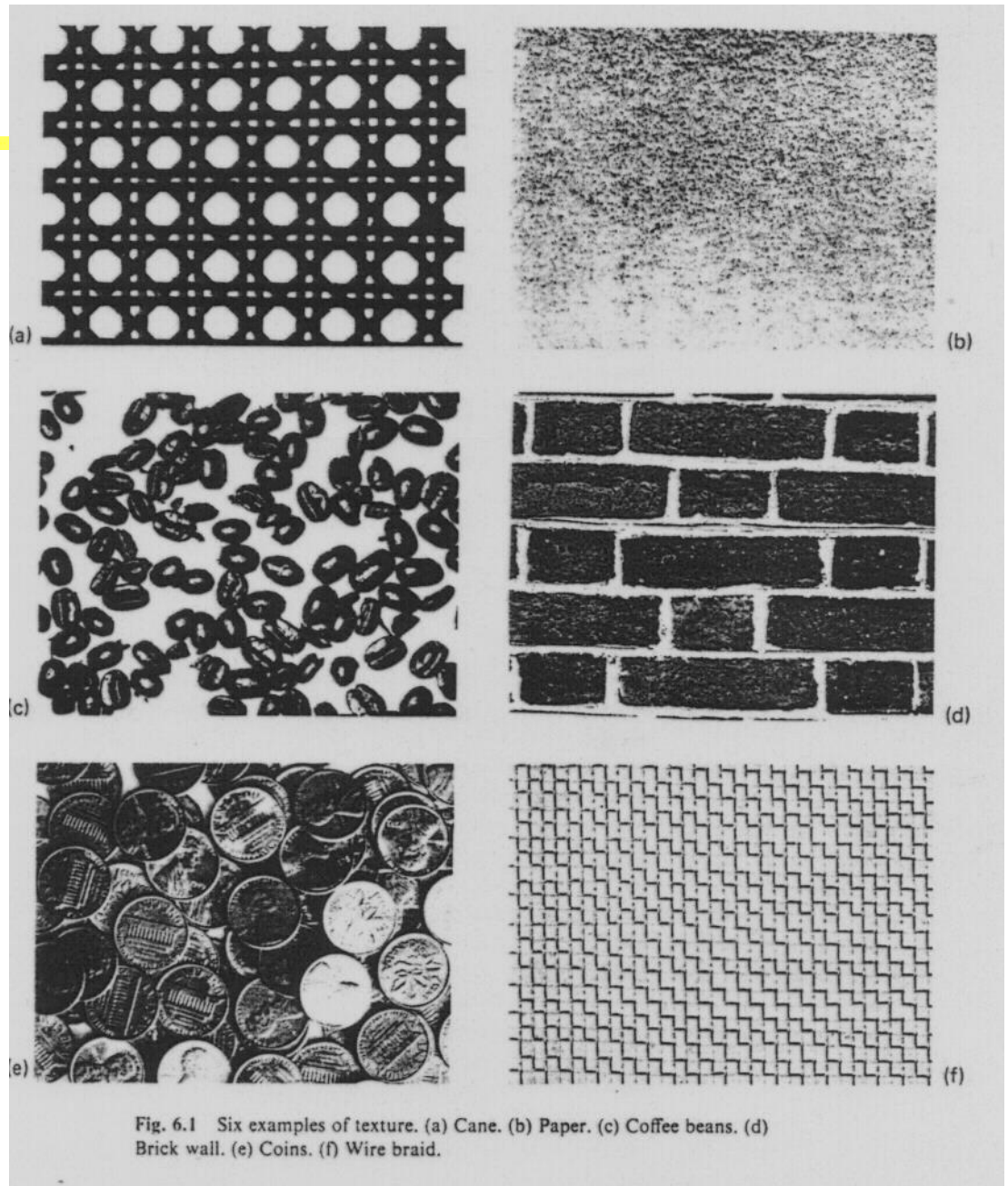
Continuity



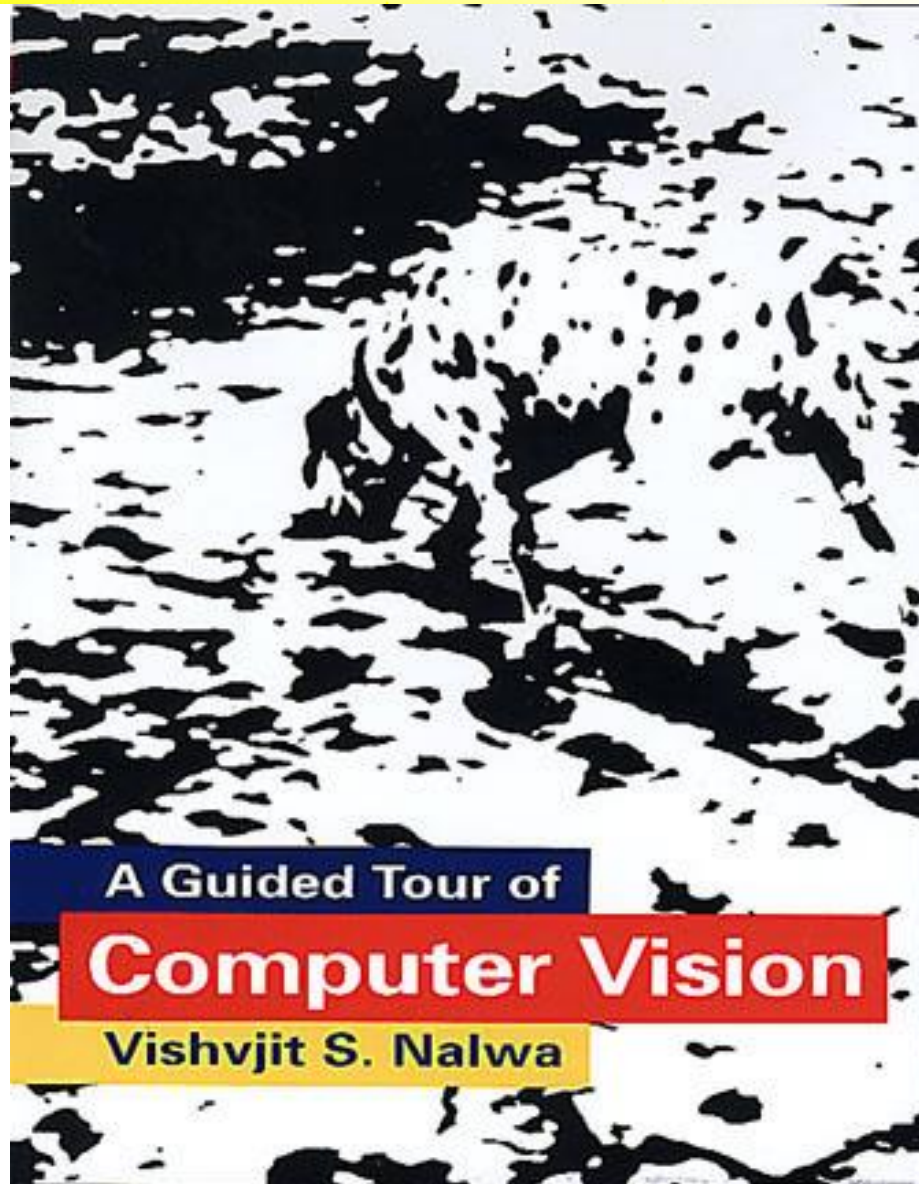
Closure



- ❖ How edges should be grouped?
- ❖ How regions should be defined?
- ❖ Semantic vs. syntactic



# *Syntactic vs. Semantic*



# 2D Image Analysis (cont.)

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## ❖ Representation (*syntactic* level)

□ Describe the *shape (appearance)* of edges and regions

- regions: size, location, orientation, etc.
- edges: curvature, orientation, length, etc.
- info can be extracted from images alone

# 2D Image Analysis (cont.)

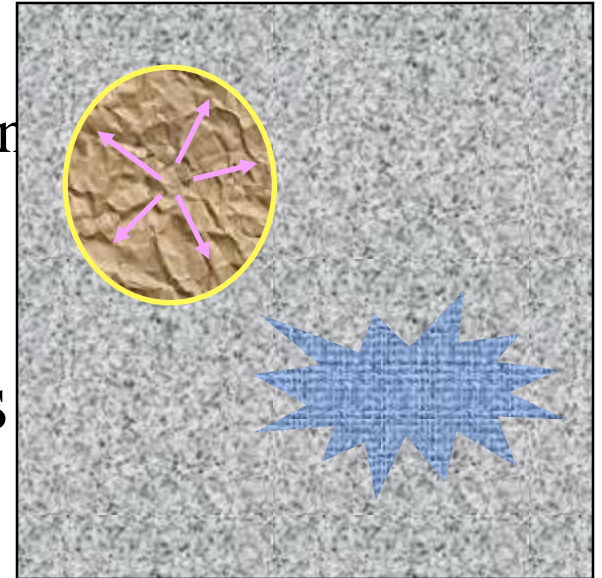
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- ❖ Interpretation (*semantic analysis*)
  - ❑ Describe the *identity* of image features
  - ❑ Regions: sky, water body, etc.
  - ❑ Edges: 3D orientation, occluding contours, road boundaries, etc.
  - ❑ Often need domain specific knowledge and contextual information

# General purpose segmentation strategies

## ❖ Region-based methods

- ❑ Regions are locally homogeneous (in some property)
- ❑ Regions satisfy some property (to within an tolerance)
- ❑ E.g., Flood fill



## ❖ Edge- or contour-based methods

- ❑ Regions are bounded by features
- ❑ Features → sharp contrast
- ❑ E.g., Canny Edges

## ❖ Bottom up (from images to features and objects)

## ❖ Syntactic information



# Segmentation via deformable models

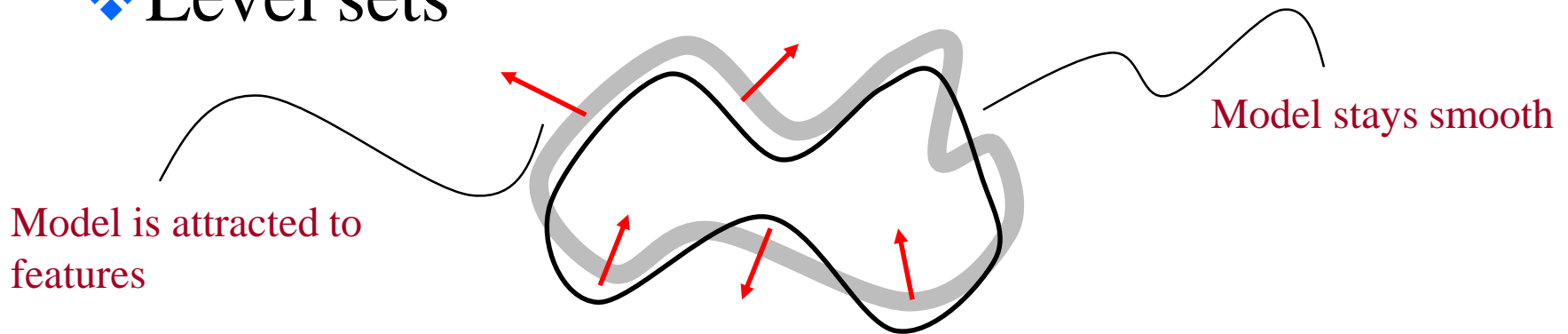
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- ❖ Active contours

  - Train models to learn certain shapes

- ❖ Snakes (polyline)

- ❖ Level sets



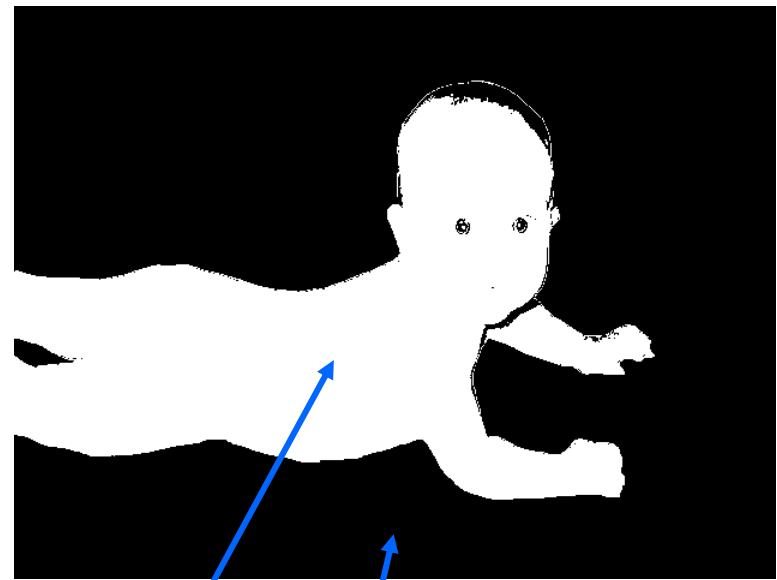
# Grayscale-based segmentation (Thresholding)

❖ “Together” = similar grayscale values

Input image



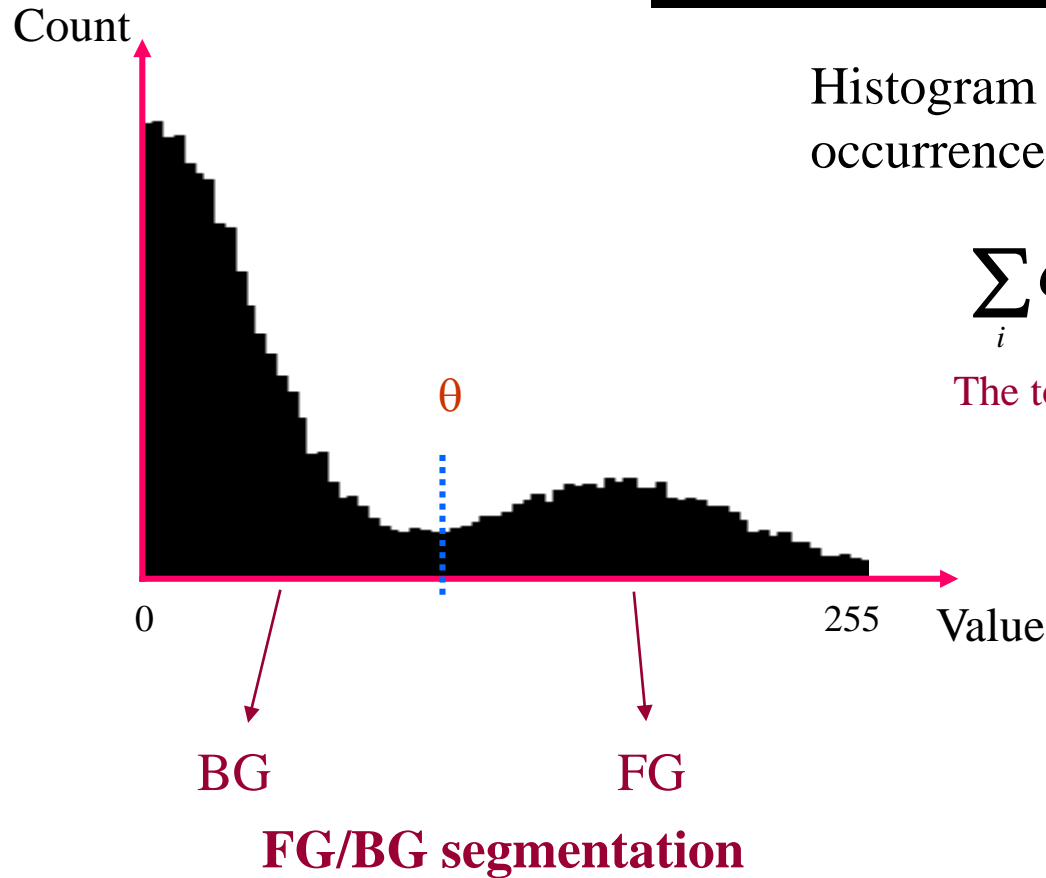
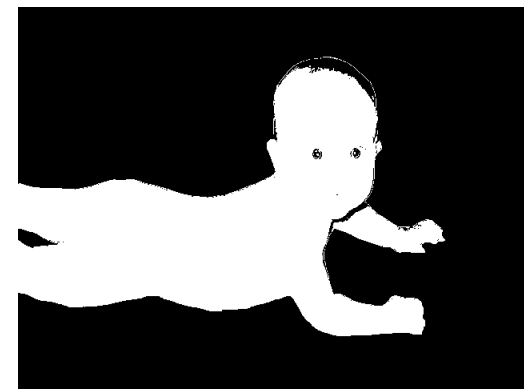
Foreground segmentation



1

2

H

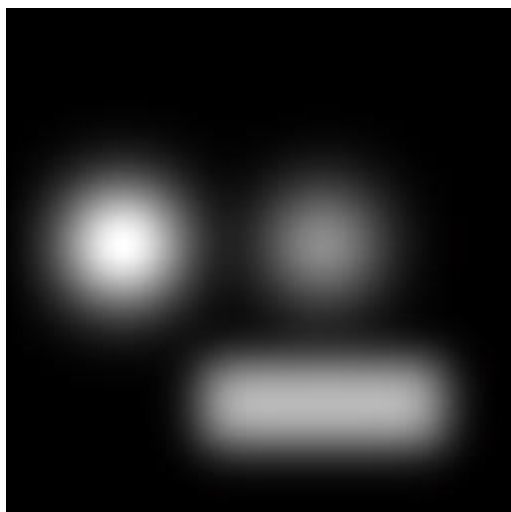


Histogram – a plot of frequency of occurrence (count) of pixel values

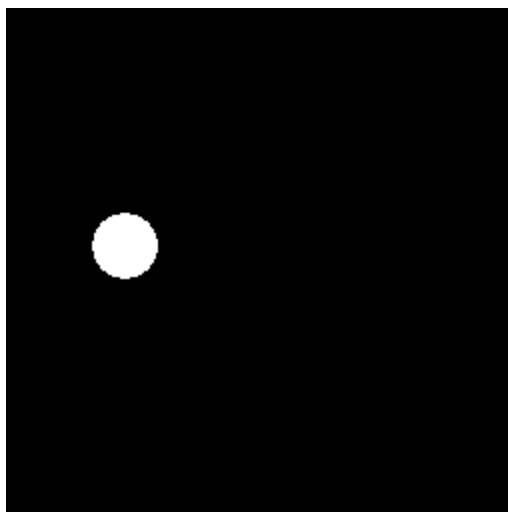
$$\sum_i Count(i) = ?$$

The total number of pixels in the image





Original



$\theta = 100$   
1 FG region



$\theta = 75$   
2 FG regions



$\theta = 50$   
3 FG regions



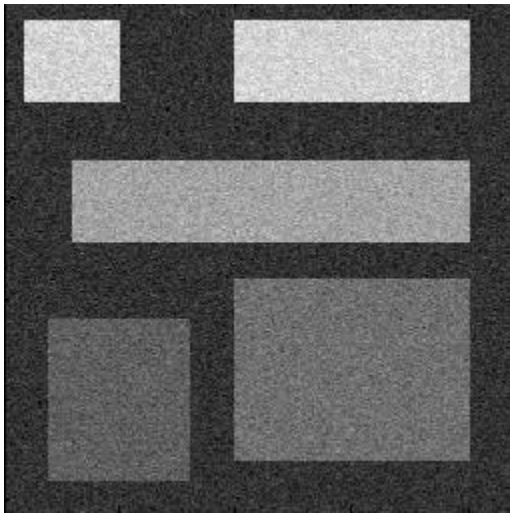
$\theta = 25$   
3 (large) FG regions



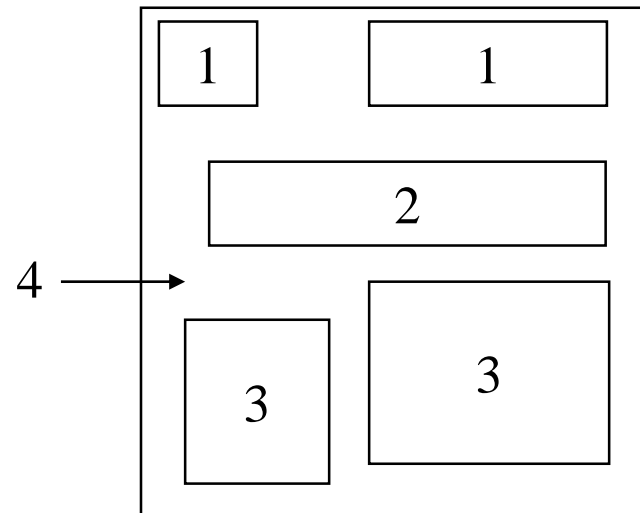
$\theta = 5$   
1 FG region

# Example with noise

Noisy input image

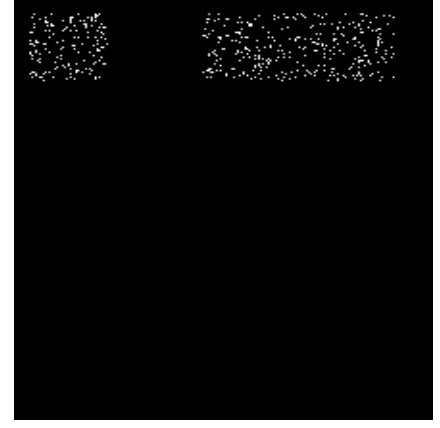
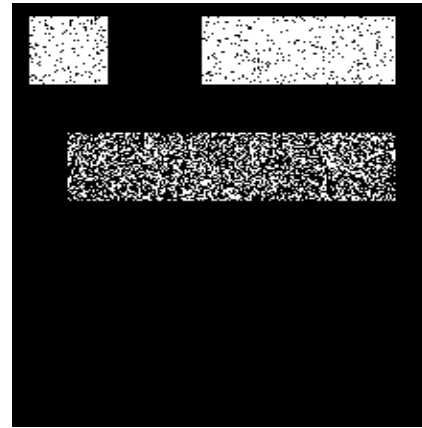
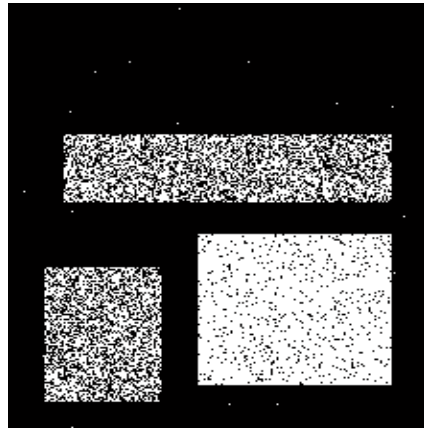
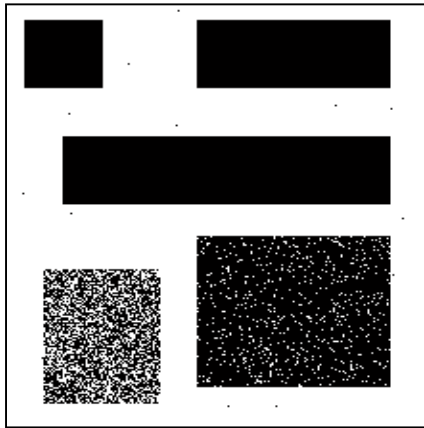
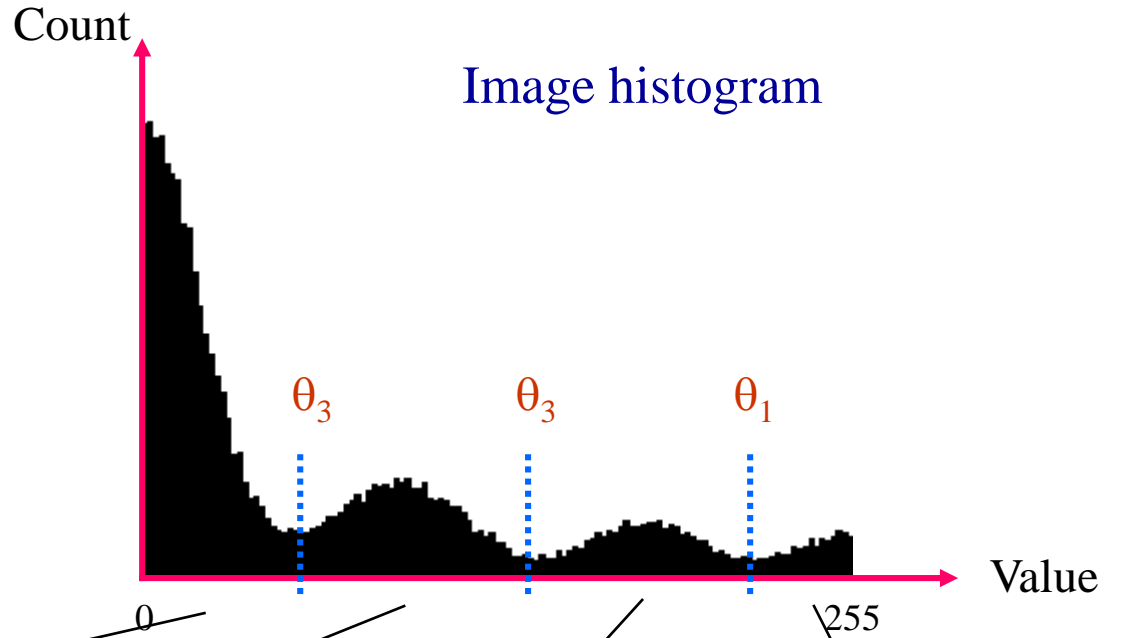
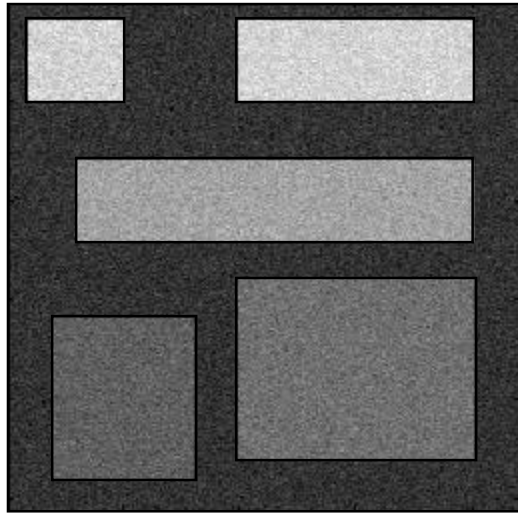


Desired segmentation



Where to threshold to get this segmentation?

Let's look at the histogram of the input image...



# *Color-based segmentation*

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- ❖ “Together” = similar color values
  - Color and intensity, or just color???
  - E.g., are “dark green” and “bright green” similar?
- ❖ Segment based on partitioning of color space
  - RGB, YUV, HSV, ...?
- ❖ Several ways to model the color range of a region, including...

# Color-based segmentation

## ❖ Color cube:

$$\square r_{min} < R < r_{max} \text{ AND } g_{min} < G < g_{max} \\ \text{AND } b_{min} < B < b_{max}$$

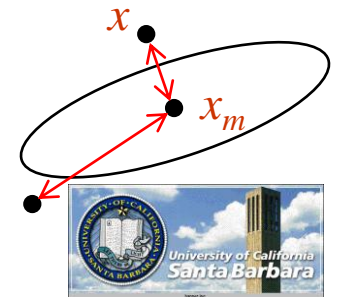
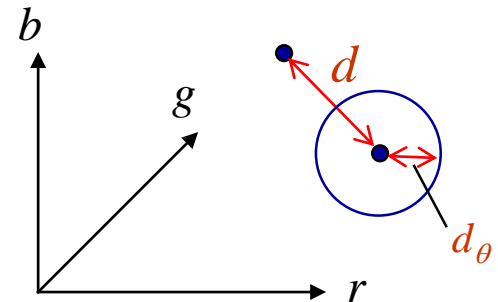
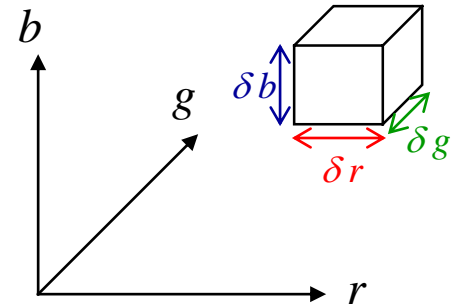
### • Euclidian distance:

- $d = \| (R,G,B) - (r_c, g_c, b_c) \|$
- $d < d\theta$

### • Mahalanobis distance: Takes into account variance in all dimensions:

- $d^2 = (x - x_m)^T C_x^{-1} (x - x_m)$
- $d < d\theta$

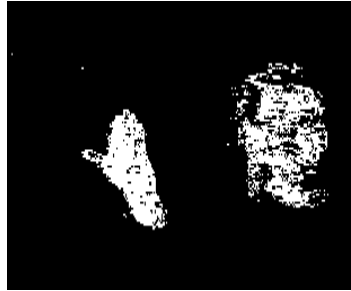
- ◆  $x$  is the (R,G,B) vector
- ◆  $x_m$  is the mean of the class distribution
- ◆  $C_x$  is the covariance matrix of the distribution



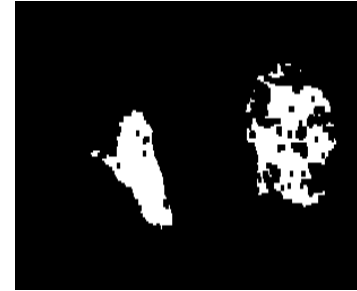
# Color-based skin segmentation



Original



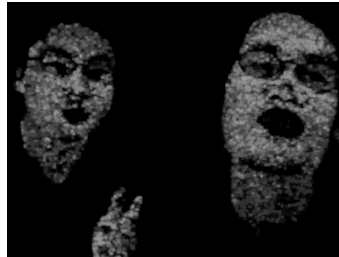
Threshold  
based on color



After  
morphological  
analysis



Original



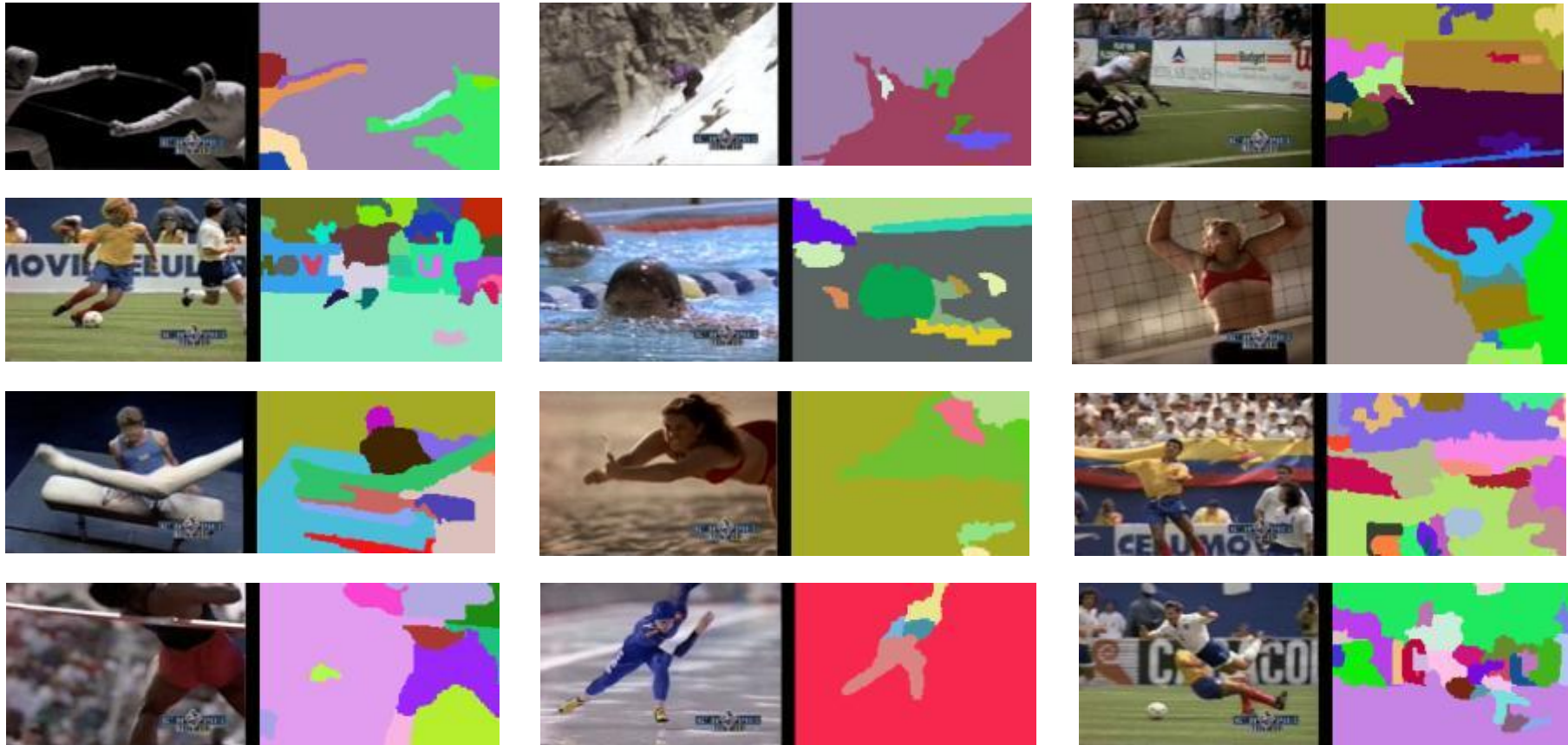
Threshold  
based on color



Texture painted  
back on face  
regions

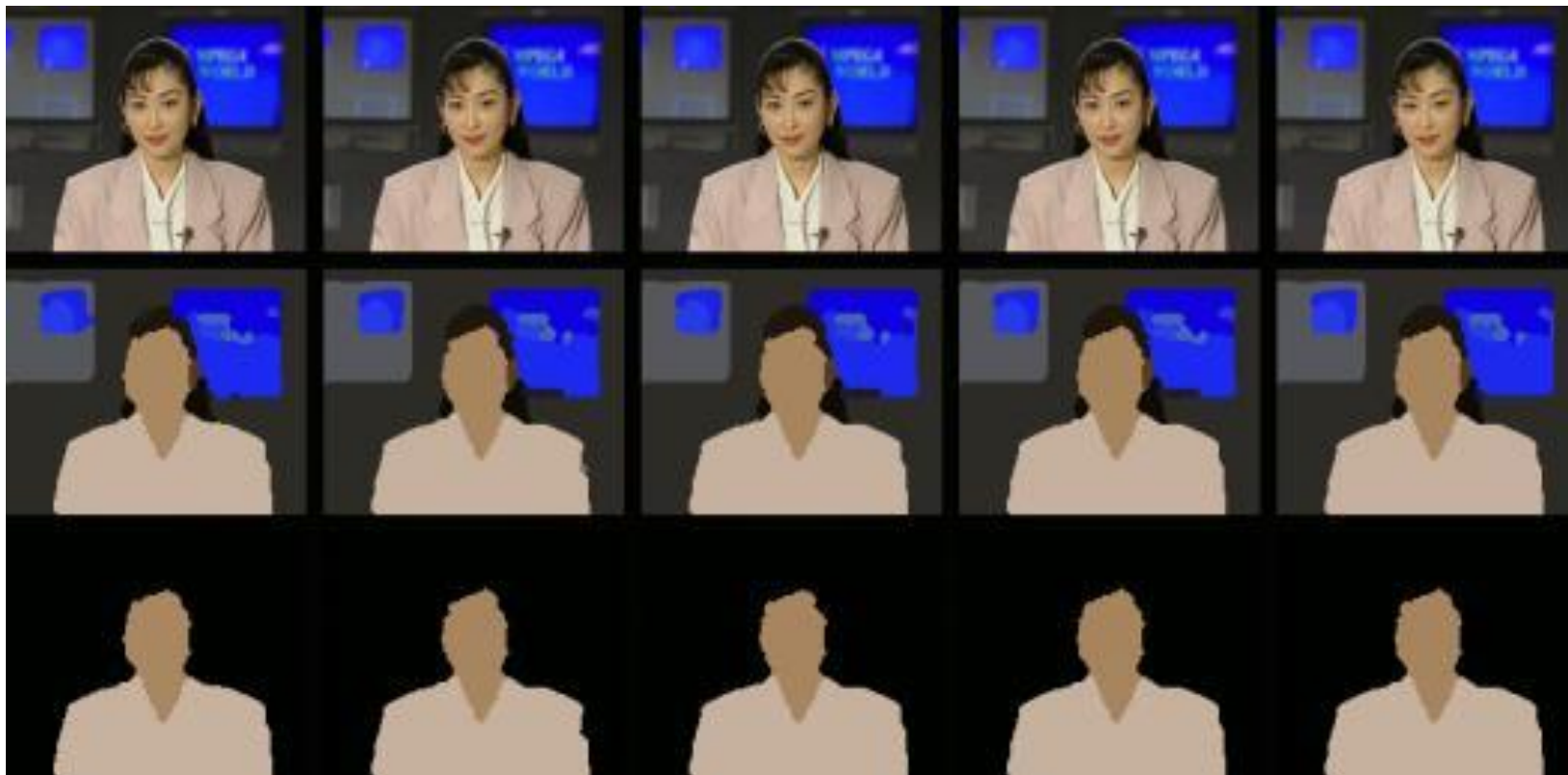
May want to enforce **spatial** proximity as well as **color** proximity

# Color segmentation examples



<http://www.ee.columbia.edu/~dzhong/rtrack/demo.htm>

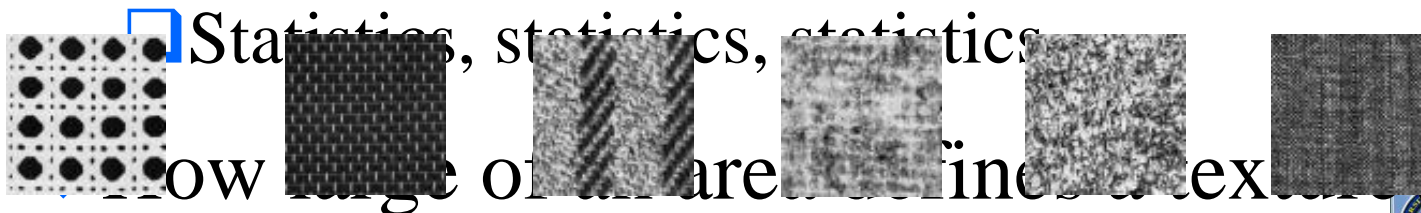
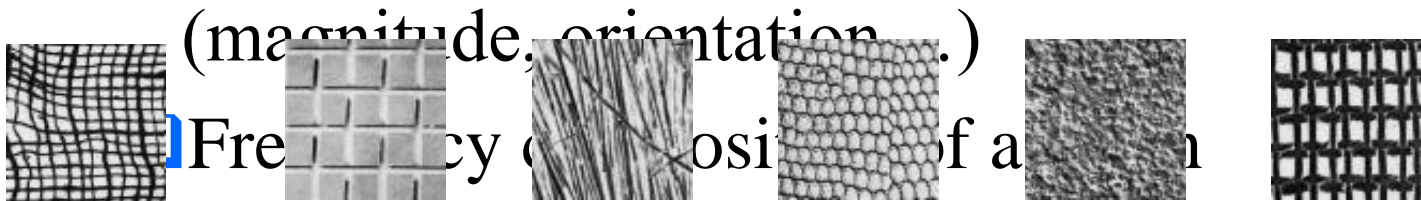
# *Color segmentation examples*





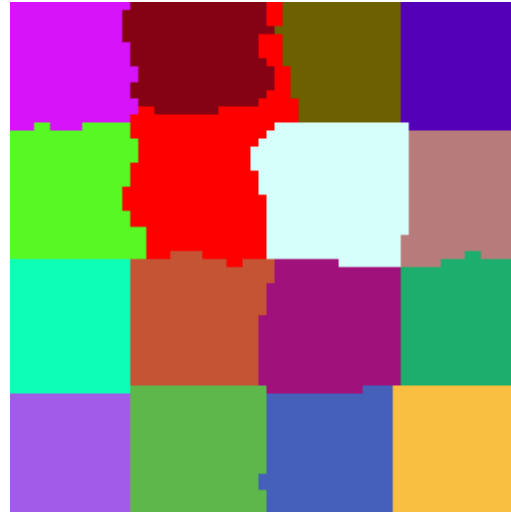
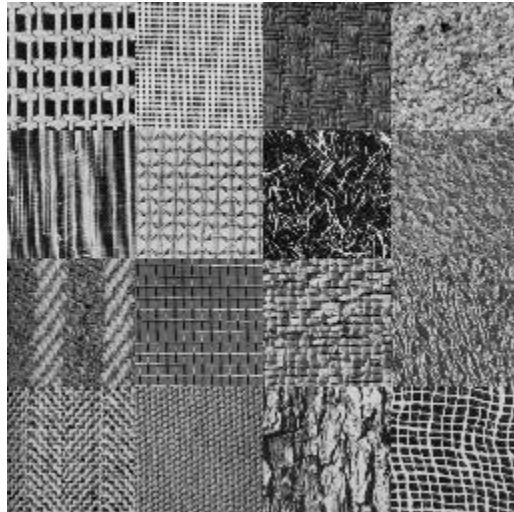
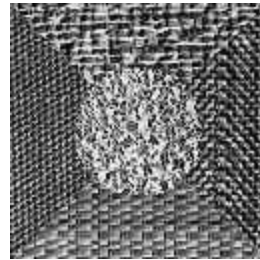
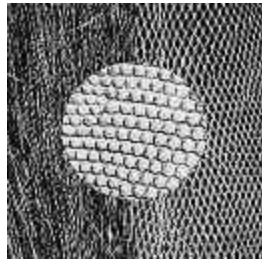
# Texture-based segmentation

- ❖ “Together” = similar texture properties
  - Fundamentally an area-based measure, not a single pixel
- ❖ There is no single definition/measure of texture
  - Number of edge segments per unit area

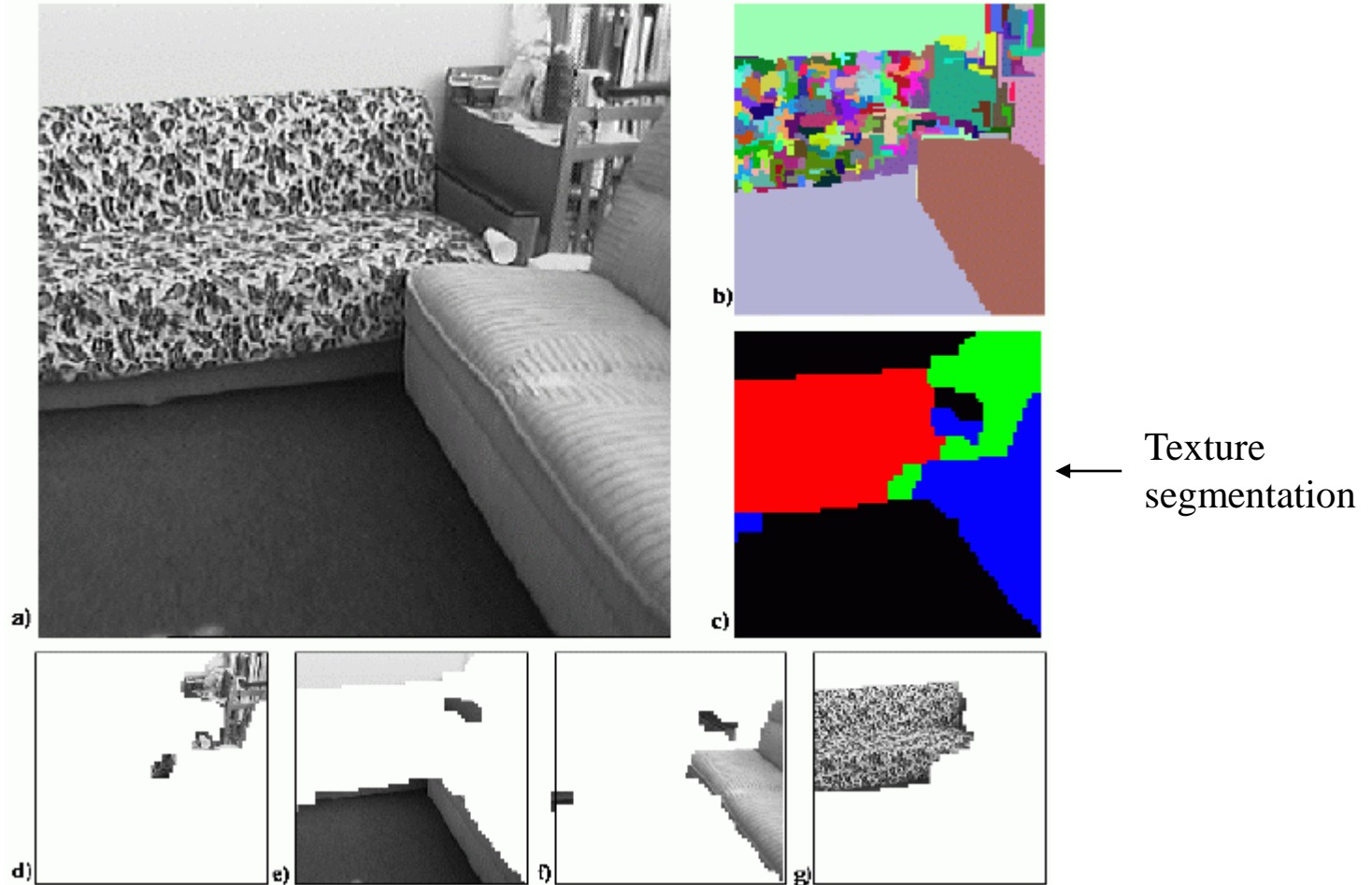


**Brodatz textures**

# *Texture-based segmentation*



# *Texture-based segmentation*



<http://www-dbv.cs.uni-bonn.de/image/example6.html>

# *Motion-based segmentation*

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❖ “Together” = similar motion

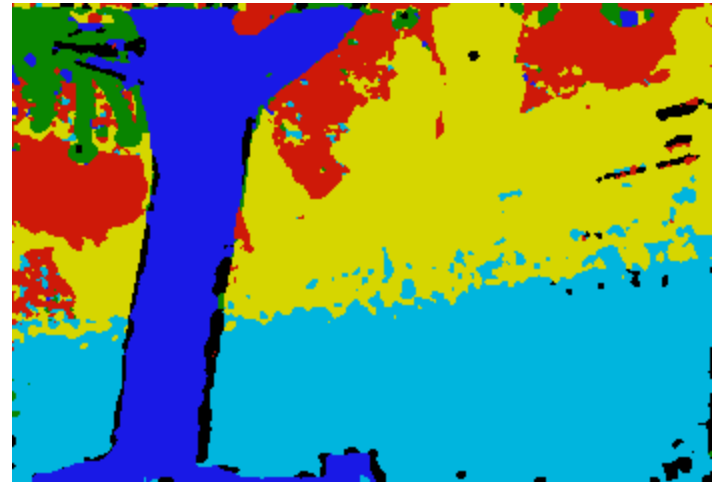
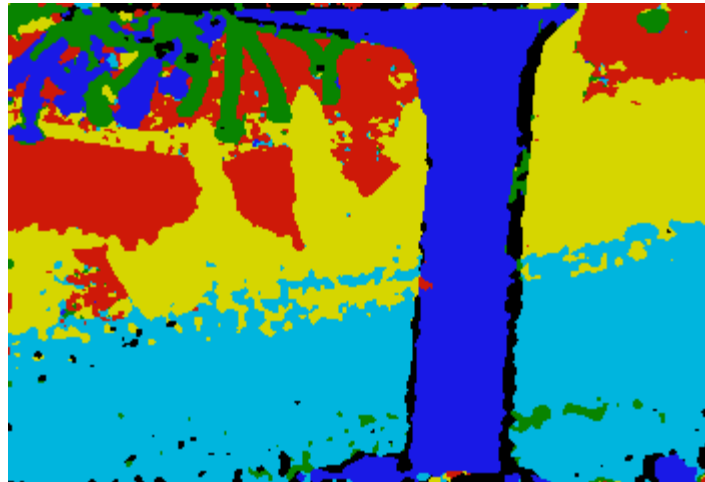
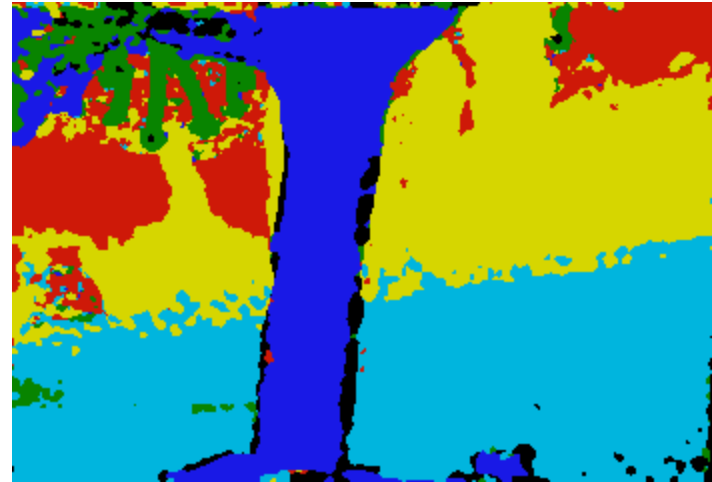
□ Rigid motion: all object points described by the same transformation

- Pencils, coffee mugs, computer monitors, marbles, ...

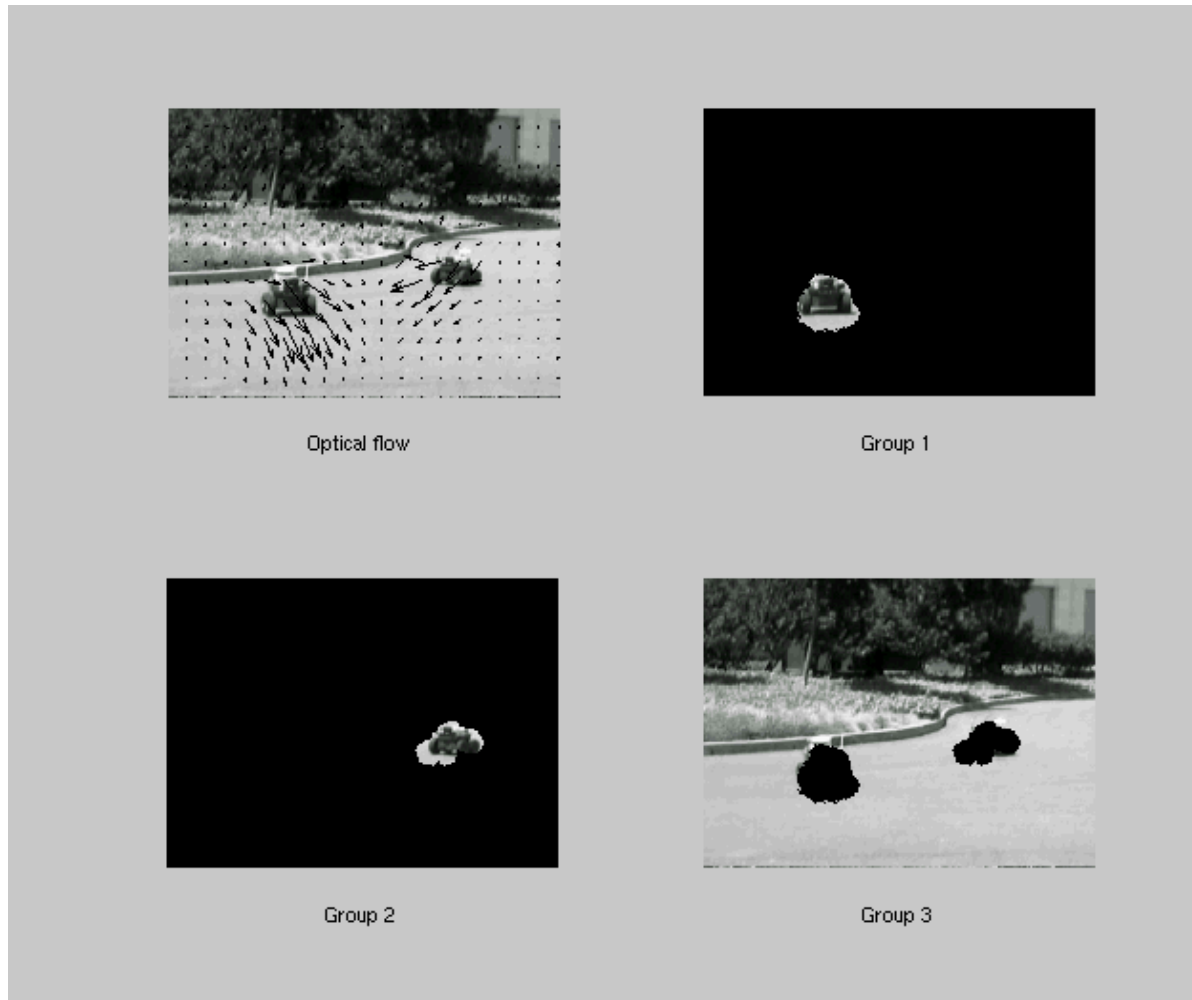
□ Non-rigid motion: articulated objects, bending objects, squishy objects...

- Clouds, fluids, faces, hair, arms, scissors, ...

# *Relative motion (depth)*



# Segmenting two moving objects



<http://robotics.eecs.berkeley.edu/~rvidal/segment.html>

# Surveillance



(a)



(b)

(c)

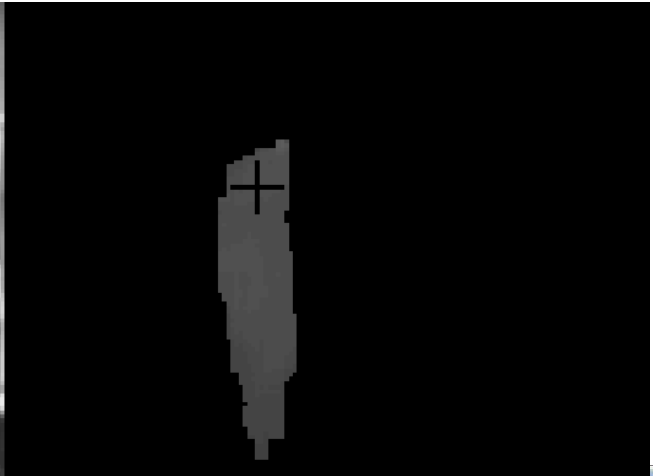
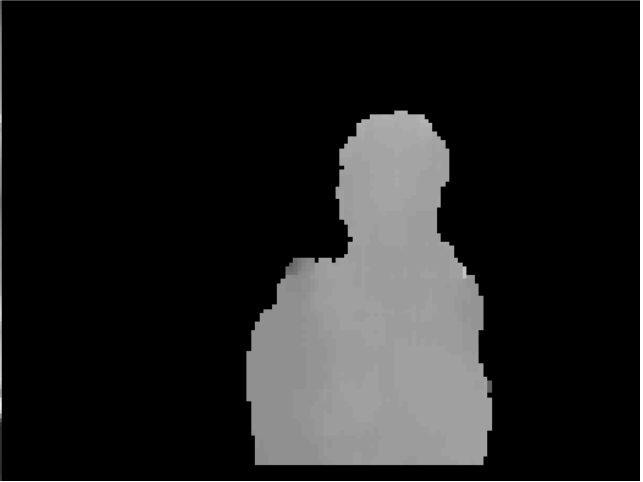
(d)

# *Depth-based segmentation*

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- ❖ “Together” = similar depth (distance from reference)
  - ❑ How similar?
  - ❑ How to segment a large object? A wall?
- ❖ Or surface normal
- ❖ Or contiguous object





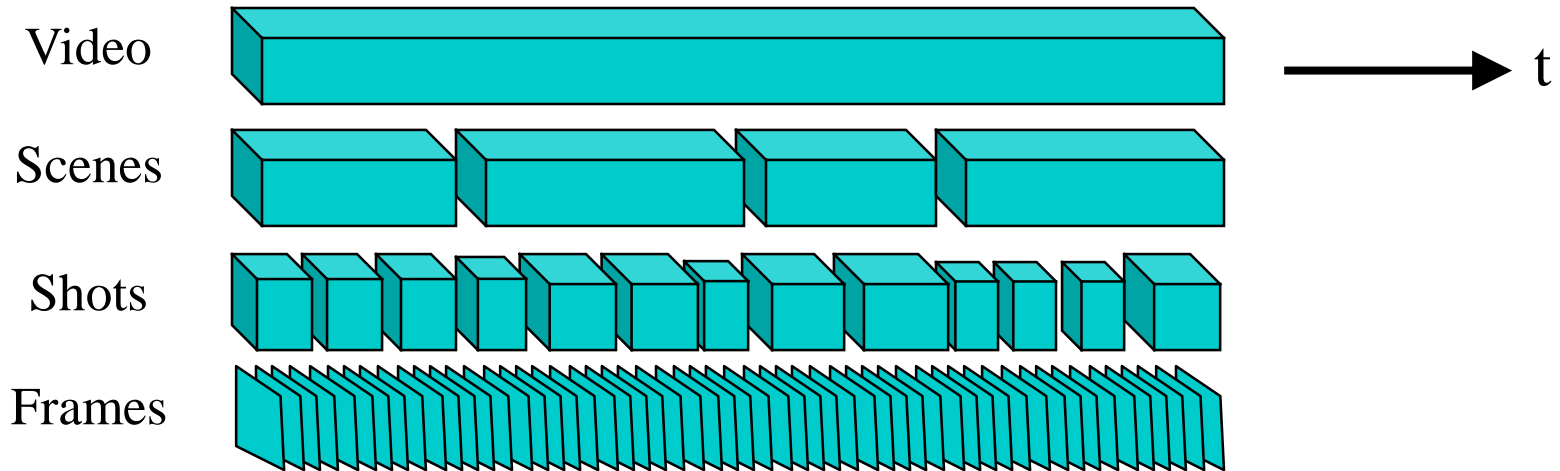
# Segmentation: Background *subtraction*

- ❖ Goal: Separate the “foreground” from the “background” in the scene
  - ❑ Not necessarily related to depth



- Approach: Model the background, then detect significant changes from the model

# Temporal segmentation of video



❖ Segment video into clips (shots) by looking for large changes

❑ Overall frame-to-frame change (frame differencing)

➤ Color, grayscale pixel values

❑ Histogram change

➤ Can be faster to compute