

Artificial Intelligence

CS 165A

Apr 26, 2022

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Today

- Examples of heuristics in A*-search
- Games and Adversarial Search

Project 1 submissions so far

- Most students have submitted
 - A few reports are still missing
- Most submissions got full credits for the coding part
 - We are still grading the reports
- Feel free to talk to us if you find it challenging.
- Notes:
 - You could still submit (late days will be automatically applied)
 - Bonus questions have no deadline.

Recap: Search algorithms

- State-space diagram vs Search Tree
- Uninformed Search algorithms
 - BFS / DFS
 - Depth Limited Search
 - Iterative Deepening Search.
 - Uniform cost search.
- Informed Search (with an heuristic function h):
 - Greedy Best-First-Search. (not complete / optimal)
 - A* Search (complete / optimal if h is admissible)

Recap: Summary table of uninformed search

Criteria	BFS	Uniform-cost	DFS	Depth-limited	IDS	Bidirectional
Complete?	Yes [#]	Yes ^{#&}	No	No	Yes [#]	Yes ^{#+}
Time	$O(b^d)$	$O(b^{1+[C^*/e]})$	$O(b^m)$	$O(b^l)$	$O(b^d)$	$O(b^{d/2})$
Space	$O(b^d)$	$O(b^{1+[C^*/e]})$	$O(bm)$	$O(bl)$	$O(bd)$	$O(b^{d/2})$
Optimal?	Yes ^{\$}	Yes	No	No	Yes ^{\$}	Yes ^{\$+}

b : Branching factor

d : Depth of the shallowest goal

l : Depth limit

m : Maximum depth of search tree

e : The lower bound of the step cost

[#]: Complete if b is finite

[&]: Complete if step cost $\geq e$

^{\$}: Optimal if all step costs are identical

⁺: If both direction use BFS

(Section 3.4.7 in the AIMA book.)

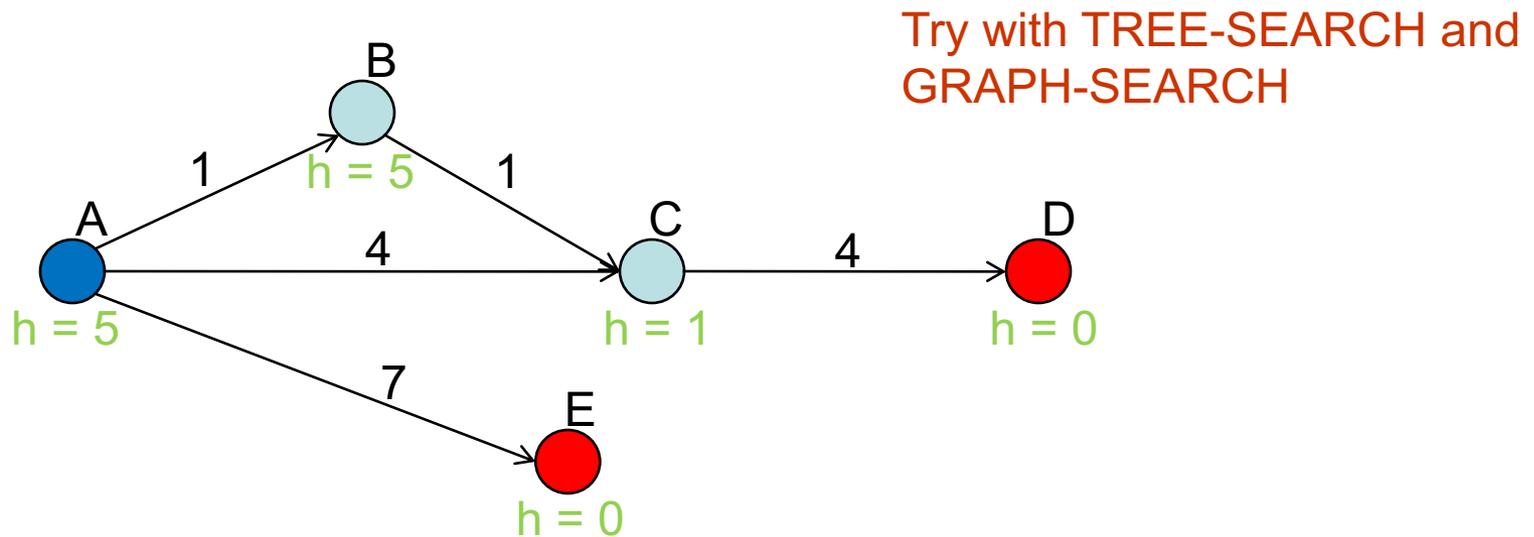
Recap: A* Search (Pronounced “A-Star”)

- Uniform-cost search minimizes $g(n)$ (“past” cost)
- Greedy search minimizes $h(n)$ (“expected” or “future” cost)
- “A* Search” combines the two:
 - Minimize $f(n) = g(n) + h(n)$
 - Accounts for the “past” and the “future”
 - Estimates the cheapest solution (complete path) through node n

```
function A*-SEARCH(problem, h) returns a solution or failure  
return BEST-FIRST-SEARCH(problem, f)
```

Recap: Avoiding Repeated States using A*

- Is GRAPH-SEARCH optimal with A*?



Graph Search

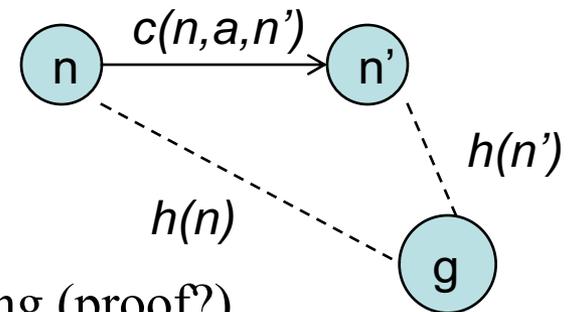
Step 1: Among B, C, E, Choose C

Step 2: Among B, E, D, Choose B

Step 3: Among D, E, Choose E. (you are not going to select C again)

Recap: Consistency (Monotonicity) of heuristic h

- A heuristic is consistent (or monotonic) provided
 - for any node n , for any successor n' generated by action a with cost $c(n,a,n')$
 - $h(n) \leq c(n,a,n') + h(n')$
 - akin to triangle inequality.
 - guarantees admissibility (proof?).
 - values of $f(n)$ along any path are non-decreasing (proof?).



- GRAPH-SEARCH using consistent $f(n)$ is optimal.
- Note that $h(n) = 0$ is consistent and admissible.

This lecture

- Example of heuristics / A* search
 - Effective branching factor
- Games
- Adversarial Search

Heuristics

- What's a heuristic for
 - Driving distance (or time) from city A to city B ?
 - 8-puzzle problem ?
 - M&C ?
 - Robot navigation ?
- **Admissible** heuristic
 - Does not overestimate the cost to reach the goal
 - “Optimistic”
- **Consistent** heuristic:
 - Satisfy a triangular inequality: $h(n) \leq c(n,a,n') + h(n')$
- Are the above heuristics admissible? Consistent?

Example: 8-Puzzle

5	4	
6	1	8
7	3	2

Start State

1	2	3
8		4
7	6	5

Goal State

Comparing and combining heuristics

- Heuristics generated by considering relaxed versions of a problem.
- Heuristic h_1 for 8-puzzle
 - Number of out-of-order tiles
- Heuristic h_2 for 8-puzzle
 - Sum of Manhattan distances of each tile
- h_2 dominates h_1 provided $h_2(n) \geq h_1(n)$.
 - h_2 will likely prune more than h_1 .
- $\max(h_1, h_2, \dots, h_n)$ is
 - admissible if each h_i is
 - consistent if each h_i is
- Cost of sub-problems and pattern databases
 - Cost for 4 specific tiles
 - Can these be added for disjoint sets of tiles?

Effective Branching Factor

- Though informed search methods may have poor *worst-case* performance, they often do quite well if the heuristic is good
 - Even if there is a huge branching factor
- One way to quantify the effectiveness of the heuristic: the **effective branching factor, b^***
 - N: total number of nodes expanded
 - d: solution depth
 - $N = 1 + b^* + (b^*)^2 + \dots + (b^*)^d$
- For a good heuristic, b^* is close to 1

Example: 8-puzzle problem

Averaged over 100 trials each at different solution lengths

d	Search Cost			Effective Branching Factor		
	IDS	$A^*(h_1)$	$A^*(h_2)$	IDS	$A^*(h_1)$	$A^*(h_2)$
2	10	6	6	2.45	1.79	1.79
4	112	13	12	2.87	1.48	1.45
6	680	20	18	2.73	1.34	1.30
8	6384	39	25	2.80	1.33	1.24
10	47127	93	39	2.79	1.38	1.22
12	364404	227	73	2.78	1.42	1.24
14	3473941	539	113	2.83	1.44	1.23
16	–	1301	211	–	1.45	1.25
18	–	3056	363	–	1.46	1.26
20	–	7276	676	–	1.47	1.27
22	–	18094	1219	–	1.48	1.28
24	–	39135	1641	–	1.48	1.26

Ave. # of nodes expanded

Solution length

Memory Bounded Search

- Memory, not computation, is usually the limiting factor in search problems
 - Certainly true for A* search
- Why? What takes up memory in A* search?
- Solution: Memory-bounded A* search
 - Iterative Deepening A* (IDA*)
 - Simplified Memory-bounded A* (SMA*)
 - (Read the textbook for more details.)

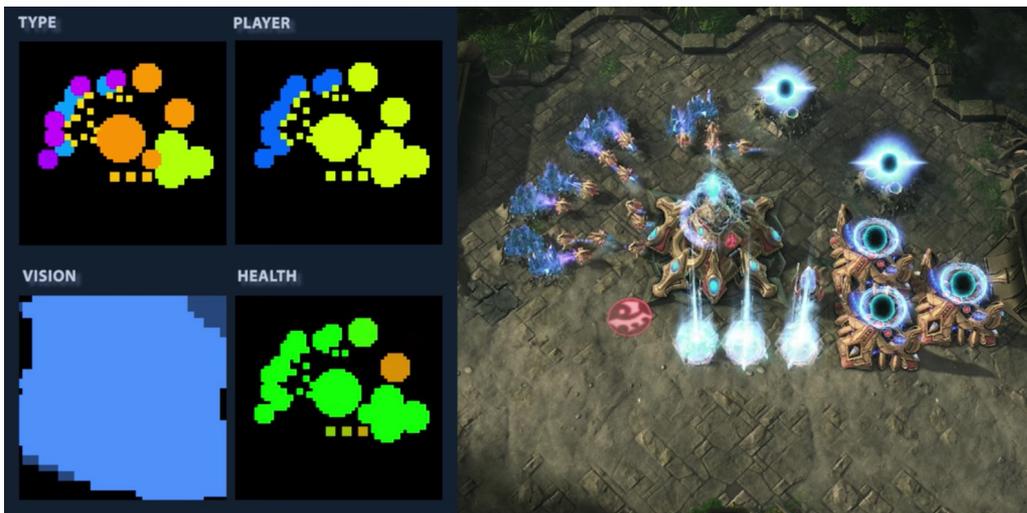
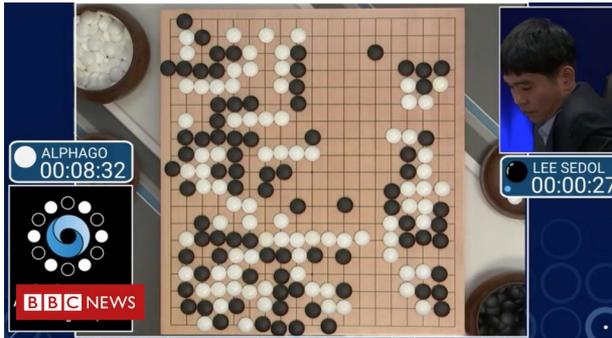
Summary of informed search

- How to use a heuristic function to improve search
 - Greedy Best-first search + Uniform-cost search = A* Search
- When is A* search optimal?
 - h is Admissible (optimistic) for Tree Search
 - h is Consistent for Graph Search
- Choosing heuristic functions
 - A good heuristic function can reduce time/space cost of search by orders of magnitude.
 - Good heuristic function may take longer to evaluate.

Games and Adversarial Search



- Games: problem setup
- Minimax search
- Alpha-beta pruning



Illustrative example of a simple game (1 min discussion)



Example: game 1

You choose one of the three bins.
I choose a number from that bin.
Your goal is to maximize the chosen number.

A

-50 50

B

1 3

C

-5 15

(Example taken from Liang and Sadigh)

Game as a search problem

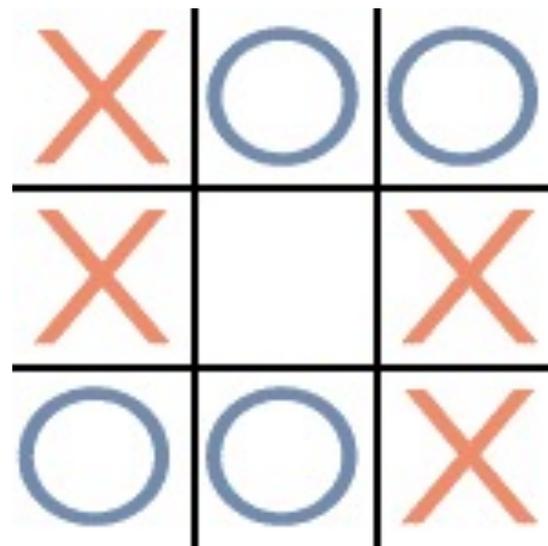
- S_0 The initial state
- $\text{PLAYER}(s)$: Returns which player has the move
- $\text{ACTIONS}(s)$: Returns the legal moves.
- $\text{RESULT}(s, a)$: Output the state we transition to.
- $\text{TERMINAL-TEST}(s)$: Returns True if the game is over.
- $\text{UTILITY}(s,p)$: The payoff of player p at terminal state s .

Two-player, Turn-based, Perfect information, Deterministic, Zero-Sum Game

- Two-player: Tic-Tac-Toe, Chess, Go!
- Turn-based: The players take turns in round-robin fashion.
- Perfect information: The State is known to everyone
- Deterministic: Nothing is random
- Zero-sum: The total payoff for all players is a **constant**.
 - *The 8-puzzle is a one-player, perfect info, deterministic, zero-sum game.*
 - *How about Rock-Paper-Scissors?*
 - *How about Monopoly?*
 - *How about Starcraft?*

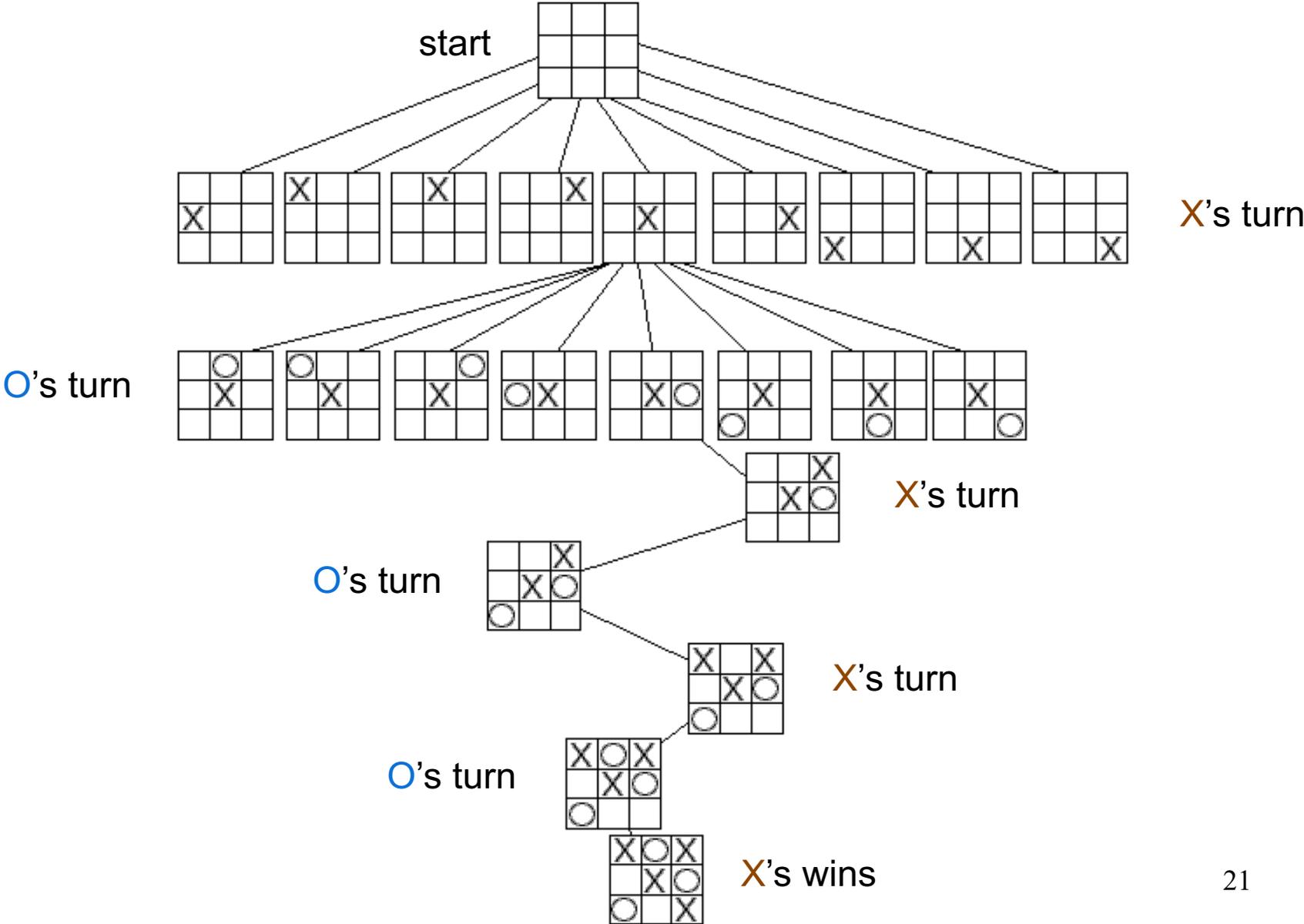
Tic-Tac-Toe

- The first player is **X** and the second is **O**
- Object of game: get three of your symbol in a horizontal, vertical or diagonal row on a 3x3 game board
- **X** always goes first
- Players alternate placing **Xs** and **O**s on the game board
- Game ends when a player has three in a row (a wins) or all nine squares are filled (a draw)



What's the state, action, transition, payoff for Tic-Tac-Toe?

Partial game tree for Tic-Tac-Toe



Game trees

- A game tree is like a search tree in many ways ...
 - nodes are search states, with full details about a position
 - characterize the arrangement of game pieces on the game board
 - edges between nodes correspond to moves
 - leaf nodes correspond to a set of goals
 - { win, lose, draw }
 - usually determined by a score for or against player
 - at each node it is one or other player's turn to move
- A game tree is not like a search tree because you have an opponent!

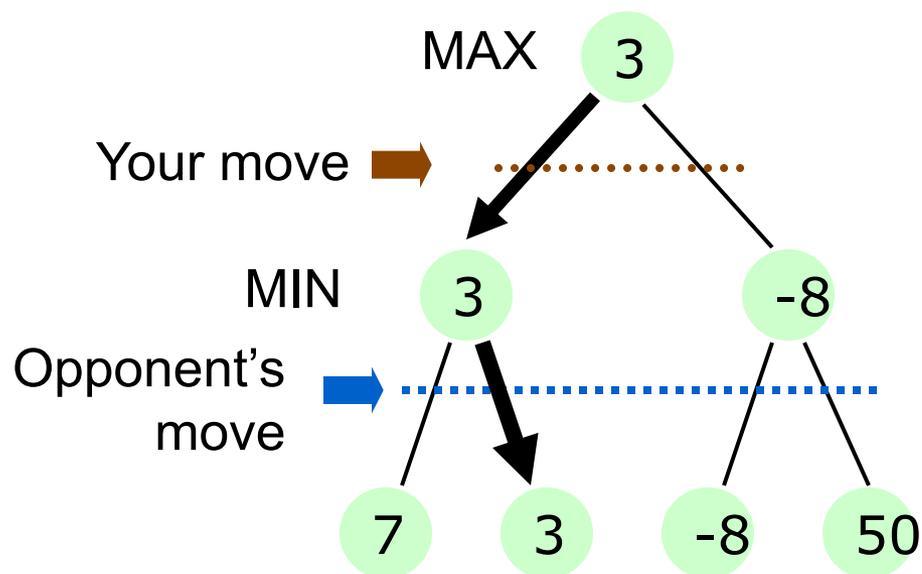
Two players: MIN and MAX

- In a zero-sum game:
 - payoff to Player 1 = - payoff to Player 2
- The goal of Player 1 is to maximizing her payoff.
- The goal of Player 2 is to maximizing her payoff as well
 - Equivalent to minimizing Player 1's payoff.

Minimax search

- Assume that both players play perfectly
 - do not assume player will miss good moves or make mistakes
- Score(s): The score that MAX will get towards the end if both player play perfectly from s onwards.
- Consider MIN's strategy
 - MIN's best strategy:
 - choose the move that **minimizes** the score that will result when MAX chooses the **maximizing** move
 - MAX does the opposite

Minimaxing

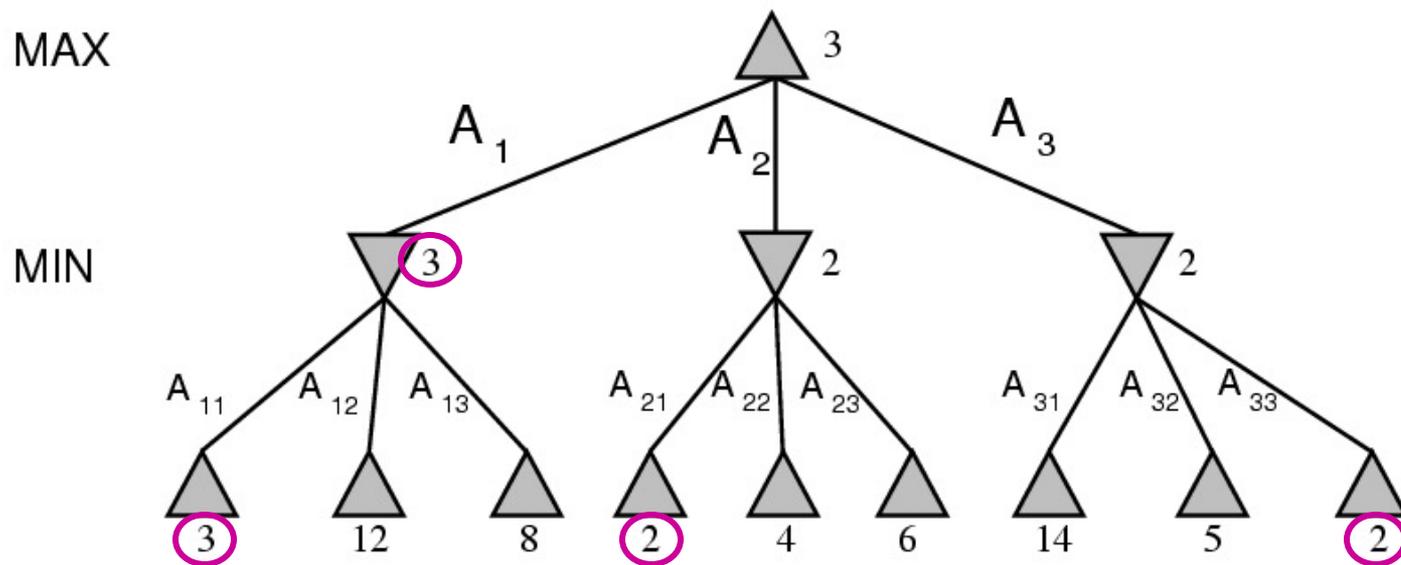


- Your opponent will choose smaller numbers
- If you move left, your opponent will choose 3
- If you move right, your opponent will choose -8
- Thus your choices are only 3 or -8
- You should move left

Each move is called a “ply”. One round is K-pplies for a K-player game.

Minimax example

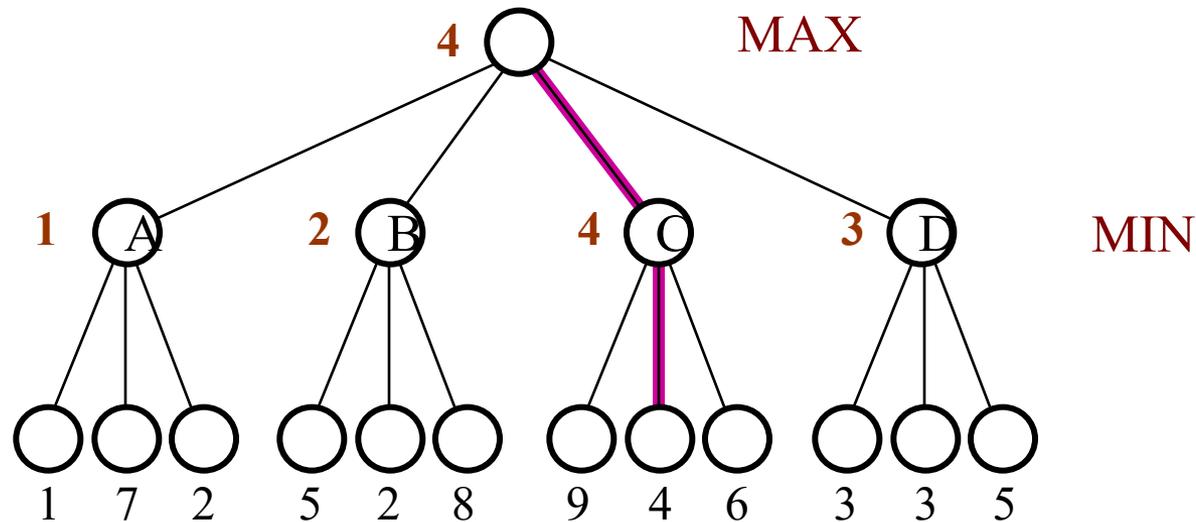
Which move to choose?



The **minimax decision** is move A_1

Another example

- In the game, it's your move. Which move will the minimax algorithm choose – A, B, C, or D? What is the minimax value of the root node and nodes A, B, C, and D?



Minimax search

- The *minimax decision* maximizes the utility under the assumption that the opponent seeks to minimize it (if it uses the same evaluation function)
- Generate the tree of minimax values
 - Then choose best (maximum) move
 - Don't need to keep all values around
 - Good memory property
- Depth-first search is used to implement minimax
 - Expand all the way down to leaf nodes
 - Recursive implementation

Minimax properties

- Optimal? Yes, against an optimal opponent, **if** the tree is finite
- Complete? Yes, **if** the tree is finite
- Time complexity? Exponential: **$O(b^m)$**
- Space complexity? Polynomial: **$O(bm)$**

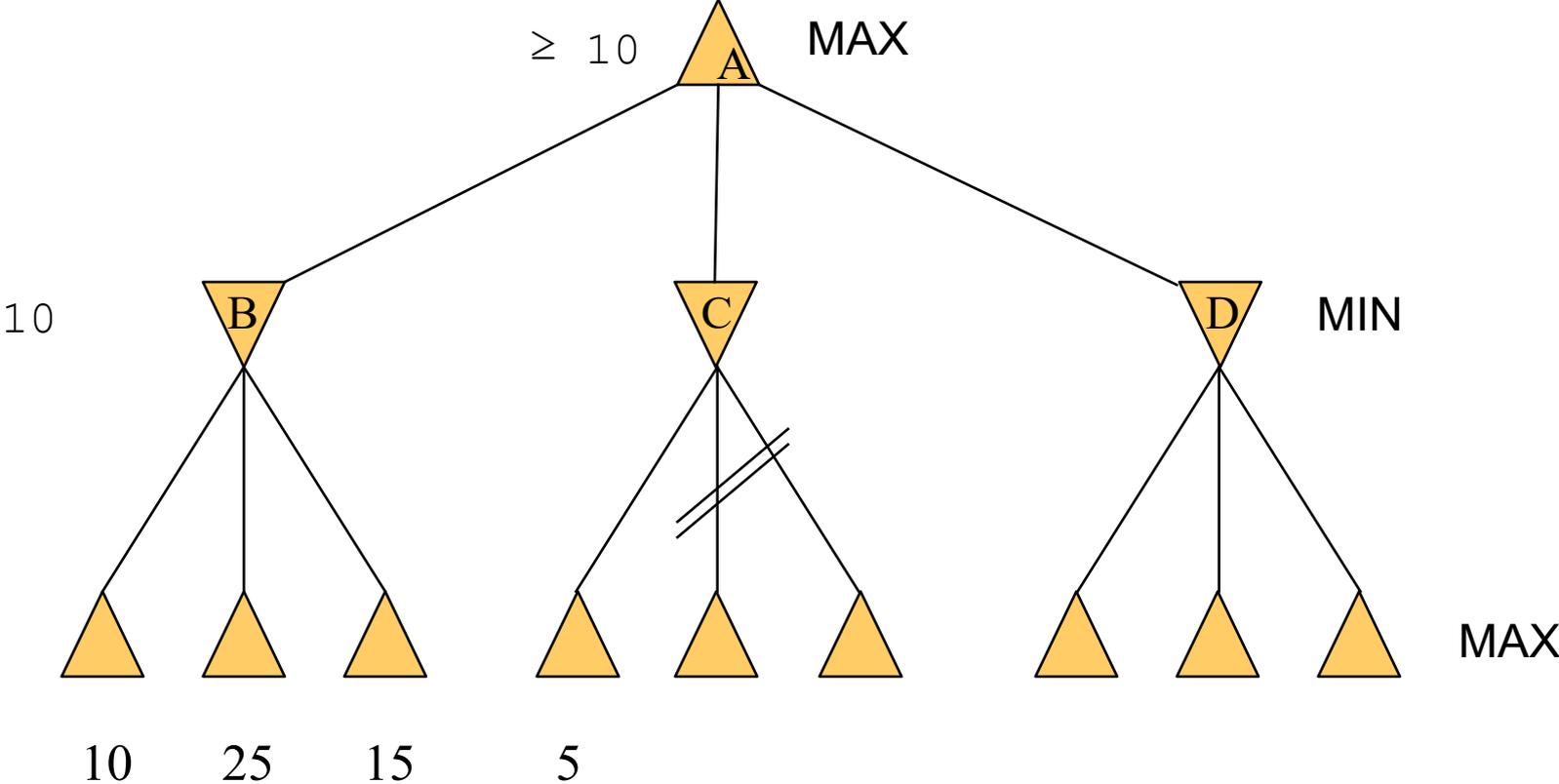
But this could take forever...

- Exact search is intractable
 - Tic-Tac-Toe is $9! = 362,880$
 - For chess, $b \approx 35$ and $m \approx 100$ for “reasonable” games
 - Go is $361! \approx 10^{750}$
- Idea 1: Pruning
- Idea 2: Cut off early and use a heuristic function

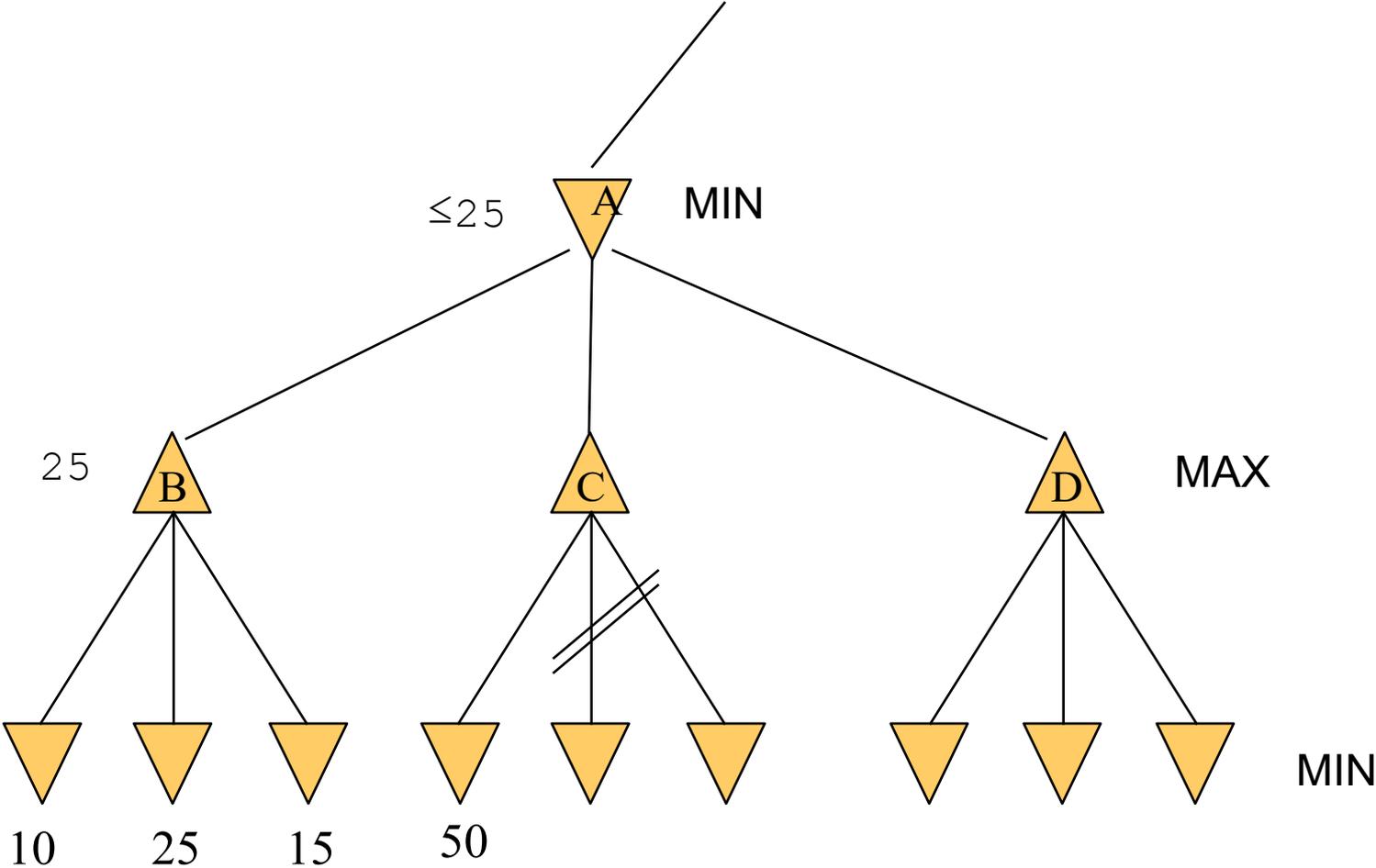
Pruning

- What's really needed is “smarter,” more efficient search
 - Don't expand “dead-end” nodes!
- **Pruning** – eliminating a branch of the search tree from consideration
- **Alpha-beta pruning**, applied to a minimax tree, returns the same “best” move, while pruning away unnecessary branches
 - Many fewer nodes might be expanded
 - Hence, smaller effective branching factor
 - ...and deeper search
 - ...and better performance
 - Remember, minimax is *depth-first* search

Alpha pruning



Beta pruning



Improvements via alpha/beta pruning

- Depends on the ordering of expansion
- Perfect ordering $O(b^{m/2})$
- Random ordering $O(b^{3m/4})$
- For specific games like Chess, you can get to almost perfect ordering.

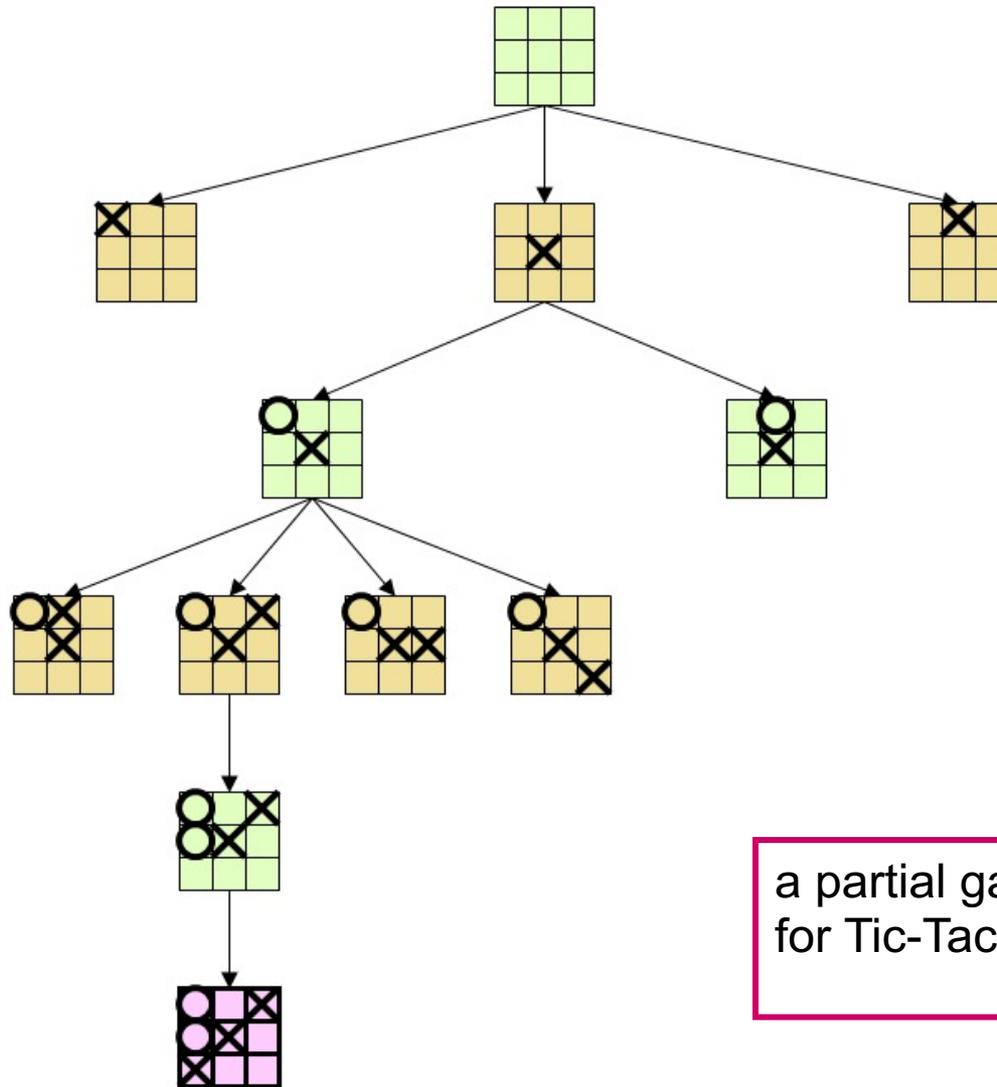
Heuristic (Evaluation function)

- It is usually impossible to solve games completely
- Rather, cut the search off early and apply a heuristic evaluation function to the leaves
 - $h(s)$ estimates the expected utility of the game from a given position (node/state) s
 - like depth bounded depth first, lose completeness
 - Explore game tree using combination of evaluation function and search
- The performance of a game-playing program depends on the quality (and speed!) of its evaluation function

Heuristics (Evaluation function)

- Typical evaluation function for game: weighted linear function
 - $h(s) = w_1f_1(s) + w_2f_2(s) + \dots + w_df_d(s)$
 - *weights* · *features* [dot product]
- For example, in chess
 - $W = \{ 1, 3, 3, 5, 8 \}$
 - $F = \{ \# \text{ pawns advantage, } \# \text{ bishops advantage, } \# \text{ knights advantage, } \# \text{ rooks advantage, } \# \text{ queens advantage} \}$
 - Is this what Deep Blue used?
 - What are some problems with this?
- More complex evaluation functions may involve learning
 - Adjusting weights based on outcomes
 - Perhaps non-linear functions
 - How to choose the *features*?

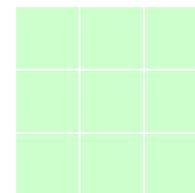
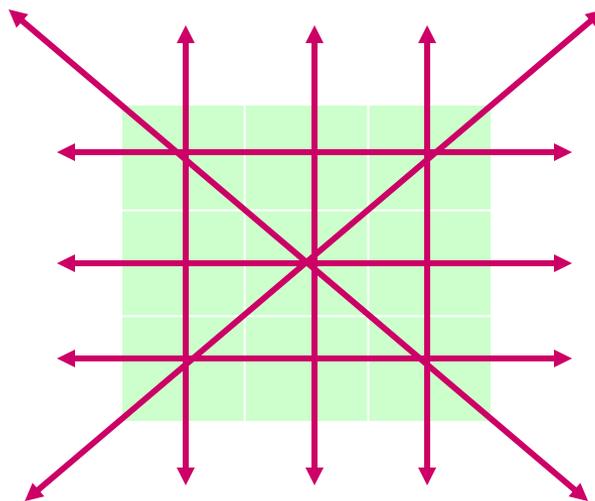
Tic-Tac-Toe revisited



a partial game tree
for Tic-Tac-Toe

Evaluation function for Tic-Tac-Toe

- A simple evaluation function for Tic-Tac-Toe
 - count the number of rows where **X** can win
 - subtract the number of rows where **O** can win
- Value of evaluation function at start of game is zero
 - on an empty game board there are 8 possible winning rows for both **X** and **O**

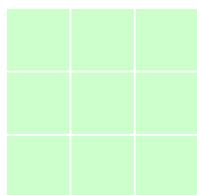


$$8-8 = 0$$

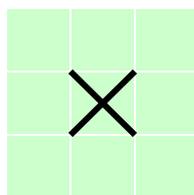
Evaluating Tic-Tac-Toe

$$\text{eval}_X = (\text{number of rows where } X \text{ can win}) - (\text{number of rows where } O \text{ can win})$$

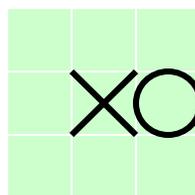
- After **X** moves in center, score for **X** is +4
- After **O** moves, score for **X** is +2
- After **X**'s next move, score for **X** is +4



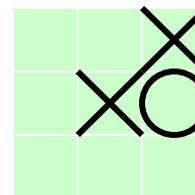
$$8-8 = 0$$



$$8-4 = 4$$



$$6-4 = 2$$

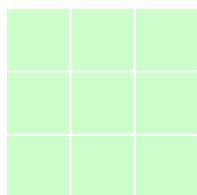


$$6-2 = 4$$

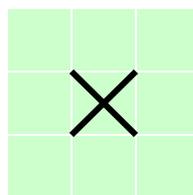
Evaluating Tic-Tac-Toe

$$\text{evalO} = (\text{number of rows where O can win}) - (\text{number of rows where X can win})$$

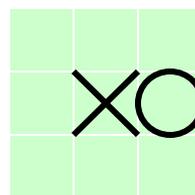
- After **X** moves in center, score for **O** is -4
- After **O** moves, score for **O** is +2
- After **X**'s next move, score for **O** is -4



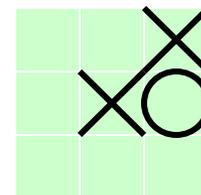
$$8-8 = 0$$



$$4-8 = -4$$



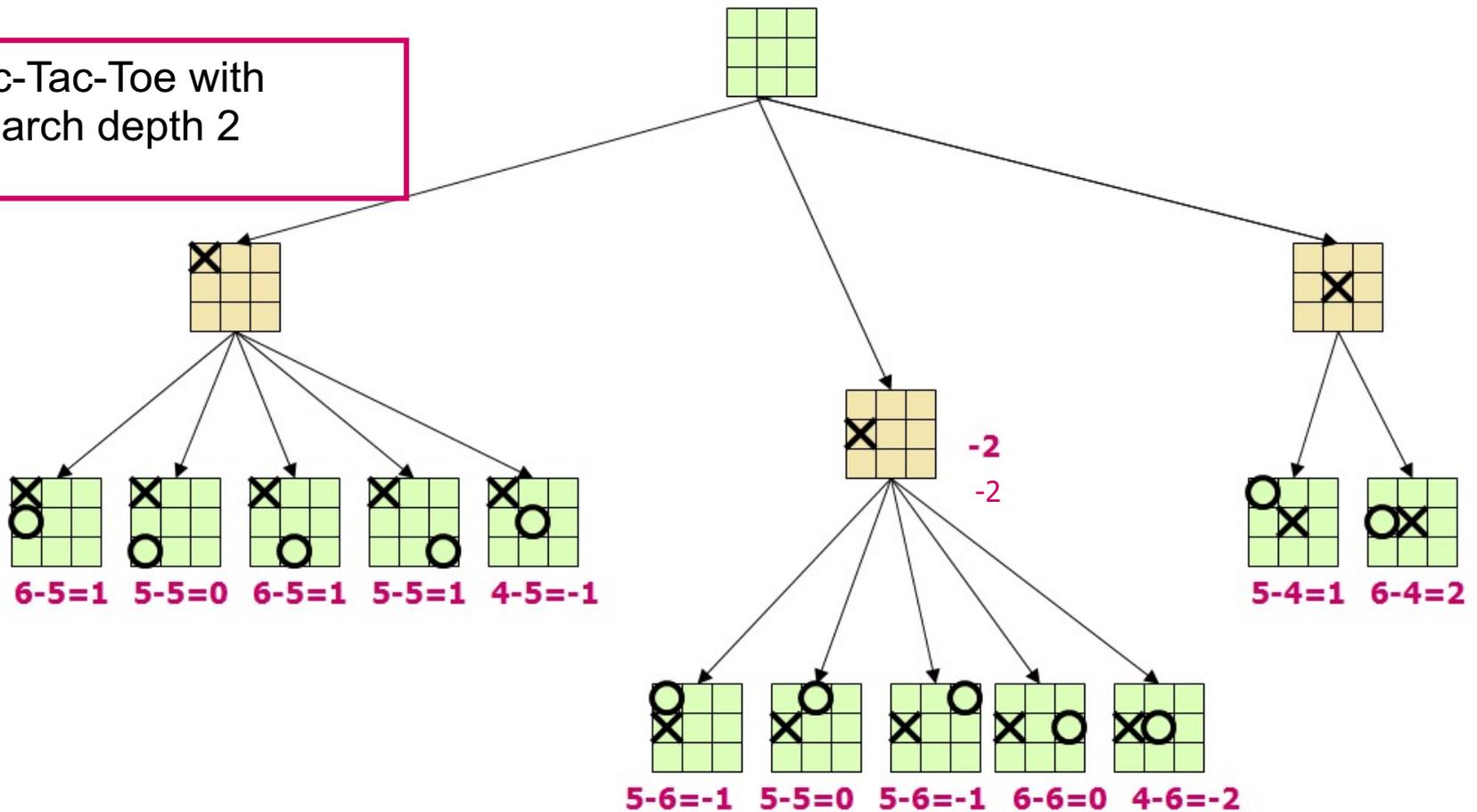
$$4-6 = -2$$



$$2-6 = -4$$

Search depth cutoff

Tic-Tac-Toe with search depth 2

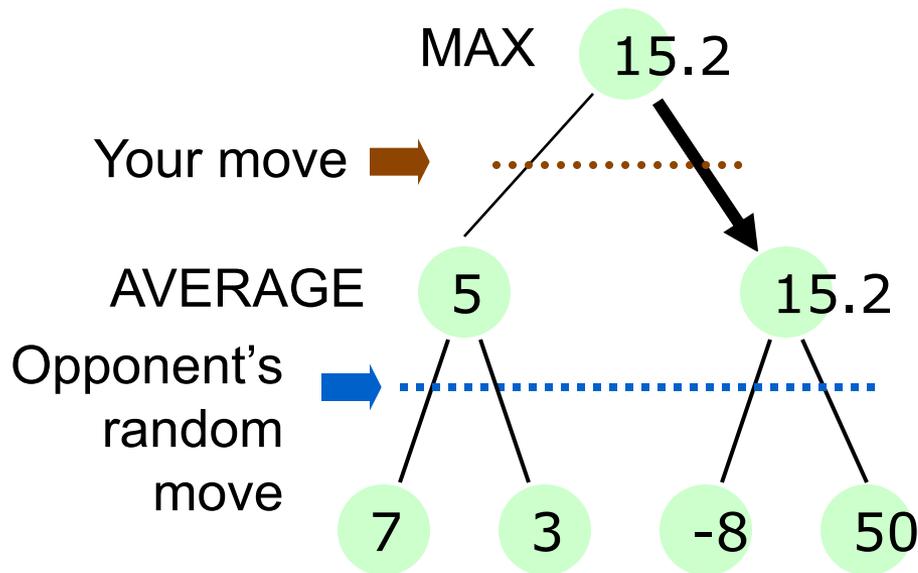


Evaluations shown for X

Expectimax: Playing against a benign opponent

- Sometimes your opponents are not clever.
 - They behave randomly.
 - You can take advantage of that by modeling your opponent.
- Example of game of chance:
 - Slot machines
 - Tetris

Expectimax example



- Your opponent behaves randomly with a given probability distribution,
- If you move left, your opponent will select actions with probability $[0.5, 0.5]$
- If you move right, your opponent will select actions with $[0.6, 0.4]$

Note: pruning becomes tricky in expectimax... think about why.

Summary of game playing

- Minimax search
- Game tree
- Alpha-beta pruning
- Early stop with an evaluation function
- Expectimax

More reading / resources about game playing

- Required reading: AIMA 5.1-5.3
- Stochastic game / Expectiminimax: AIMA 5.5
 - Backgammon. TD-Gammon
 - Blackjack, Poker
- Famous game AI: Read the “Historical notes” of the AIMA Chapter 5
 - Deep blue
 - TD Gammon
- AlphaGo: <https://www.nature.com/articles/nature16961>